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A QUANTUM OBSTRUCTION FOR PURELY COSMETIC SURGERIES

by Renaud DETCHERRY (*)

ABSTRACT. — We present new obstructions for a knot K in S^3 to admit purely cosmetic surgeries, which arise from the study of Witten–Reshetikhin–Turaev invariants at fixed level, and can be framed in terms of the colored Jones polynomials of K.

In particular, we show that if K has purely cosmetic surgeries then the slopes of the surgery are of the form $\pm \frac{1}{5k}$, except if $J_K\left(e^{\frac{2i\pi}{5}}\right) = 1$, where J_K is the Jones polynomial of K. For any odd prime $r \ge 5$, we also give an obstruction for K to have $a \pm \frac{1}{k}$ surgery slope with $r \nmid k$ that involves the values of the first $\frac{r-3}{2}$ colored Jones polynomials of K at an r-th root of unity. We verify the purely cosmetic surgery conjecture for all knots with at most 17 crossings.

RÉSUMÉ. — Nous donnons de nouvelles obstructions pour qu'un nœud K dans S^3 admette des chirurgies purement cosmétiques, qui proviennent de l'étude des invariants de Witten-Reshetikhin-Turaev à niveau fixé.

En particulier, nous montrons que si K a des chirurgies purement cosmétiques alors les pentes sont de la forme $\pm \frac{1}{5k}$, sauf si $J_K\left(e^{\frac{2i\pi}{5}}\right) = 1$, où J_K est le polynôme de Jones de K. Pour tout nombre premier $r \ge 5$, nous donnons aussi une obstruction pour ce que K ait une chirurgie purement cosmétique de pentes $\pm \frac{1}{k}$ avec $r \nmid k$ qui fait intervenir les premiers $\frac{r-3}{2}$ polynômes de Jones coloriés de Ken une racine r-ème de l'unité. Nous vérifions la conjecture pour tous les nœuds à moins de 17 croisements.

1. Introduction

Given an oriented 3-manifold M with $\partial M = \mathbb{T}^2$, a pair of slopes $s \neq s'$ on the boundary is said to form a cosmetic surgery pair if the Dehn fillings M(s) and M(s') are homeomorphic, and a purely cosmetic surgery pair if

 $K\!eywords:$ Dehn surgery, cosmetic surgeries, Jones polynomial, Reshetikhin–Turaev TQFTs.

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M(s) and M(s') are homeomorphic as oriented 3-manifolds. We will write $M(s) \simeq M(s')$ when the two manifolds M(s) and M(s') are homeomorphic as oriented 3-manifolds.

In the case where M is the complement E_K of a non-trivial knot K in S^3 , the cosmetic surgery conjecture, first formulated by Gordon in [8], asserts that:

CONJECTURE 1.1 (Cosmetic Surgery Conjecture). — If K is a nontrivial knot in S^3 and $s \neq s'$ are two slopes, then $E_K(s) \not\simeq E_K(s')$.

In other words, no non-trivial knot in S^3 has a purely cosmetic surgery pair. In the more general setting of a 3-manifold with torus boundary M, the cosmetic surgery conjecture says that $M(s) \simeq M(s')$ if and only if there is a positive self-homeomorphism of M which sends the slope s to s'.

Cosmetic surgery pairs which are not purely cosmetic are called *chirally* cosmetic. Chirally cosmetic pairs do exist: indeed, for any amphichiral knot, any pair of opposite slopes will form a chirally cosmetic pair. Moreover, some chirally cosmetic pairs on the right-hand trefoil knot, and more generally, (2, n)-torus knots, were found by Mathieu [14].

The first result on Conjecture 1.1 was given by Boyer and Lines [3]. Using surgery formulas for the Casson–Walker and Casson–Gordon invariants, they proved the conjecture for any knot K such that $\Delta''_K(1) \neq 0$, where Δ_K is the Alexander polynomial of K. The next finite type invariant of knots also gives an obstruction: Ichihara and Wu showed [10] that if Kadmits purely cosmetic surgeries then $J''_K(1) = 0$ where J_K is the Jones polynomial.

Later on, much of the progress on Conjecture 1.1 has been brought by studying Heegaard Floer homology of knots. First, it was proved than genus one knots do not have purely cosmetic surgeries [22]. Some conditions on the set of possible slopes in a purely cosmetic pair were established: it was first shown that the slopes in a purely cosmetic pair for a knot $K \subset S^3$ have opposite signs [16, 24], then Ni and Wu showed that the slopes must actually be opposite and furthermore that the Ozváth–Szabó–Rasmussen τ invariant of K must vanish [15]. Also, the Heegaard Floer homology $\widehat{HFK}(K)$ must satisfy some other constraints [6, 15].

Then, the work of Futer, Purcell and Schleimer [5] showed for any hyperbolic 3-manifold with torus boundary, it can be algorithmically checked whether it admits a purely cosmetic pair. Their result came out of a different direction, using hyperbolic geometry to bound the length of slopes in a purely cosmetic pair. With their method they proved the conjecture for knots with less than 15 crossings.

Using a new method to express the Heegaard Floer homology of surgeries, Hanselman put further restrictions on the surgery slopes [9]. Similarly to Futer, Purcell and Schleimer's result, those conditions restrict the set of possible slopes to a finite set. Hanselman's bounds seem to be more powerful in practice, with the downside that so far they apply only to the case of knots in S^3 .

Indeed, Hanselman was able to use his results to show that no knot with prime summands with less than 16 crossings has a purely cosmetic surgery pair.

Finally, let us mention that, analyzing JSJ decompositions, Tao has proved that composite knots and cable knots [18] do not have purely cosmetic surgeries. It reduces the conjecture to the case of prime knots.

We will now describe some of Hanselman's main theorems from [9] in more detail below, as our results will build upon his work.

For K a knot in S^3 , let g(K) be its Seifert genus. Let $\widehat{HFK}(K)$ be its Heegaard Floer knot homology, which is bigraded with Alexander grading A and Maslov grading μ . We define the δ -grading by $\delta = A - \mu$, and let the Heegaard Floer thickness of K be

$$\operatorname{th}(K) = \max\left\{\delta(x) \mid x \neq 0 \in \widehat{\operatorname{HFK}}(K)\right\} - \min\left\{\delta(x) \mid x \neq 0 \in \widehat{\operatorname{HFK}}(K)\right\}.$$

Said differently, th(K)+1 is the number of diagonals on which the Heegaard Floer homology of K is supported.

THEOREM 1.2 ([9]). — Let K be a non-trivial knot in S^3 and $s \neq s'$ be slopes such that $E_K(s) \simeq E_K(s')$. Then:

- The pair of slopes $\{s, s'\}$ is either $\{\pm 2\}$ or of the form $\{\pm \frac{1}{k}\}$ for some non-negative integer k.
- If $\{s, s'\} = \{\pm 2\}$, then g(K) = 2.
- If $\{s, s'\} = \{\pm \frac{1}{k}\}$, then

$$k \leqslant \frac{\operatorname{th}(K) + 2g(K)}{2g(K)(g(K) - 1)}.$$

Remark 1.3. — Actually, Hanselman's proof also shows that there is a sequence of integers $(n_t)_{t\in\mathbb{N}}$ which are invariants of the knot that can be extracted from $\widehat{\mathrm{HFK}}(K)$ and which determine an integer k' such that if $E_K(\frac{1}{k}) \simeq E_K(-\frac{1}{k})$ then k = k'. So from Heegaard-Floer data, for any knot there is a unique candidate slope of the form $\frac{1}{k}$ for being a cosmetic surgery slope.

Despite the success of Heegaard Floer homology, it is generally believed that other methods will be needed to study the cosmetic surgery conjecture. Indeed, Hanselman found 337 knots $K \subset S^3$ for which Heegaard Floer homology does not distinguish between $E_K(s)$ and $E_K(-s)$ for s = 1 or 2.

Invariants that have nice surgery expressions are natural candidates for applications to the cosmetic surgery conjecture. Therefore, the author tried to investigate what information the Witten–Reshetikhin–Turaev invariants have to offer about cosmetic surgeries. As WRT invariants are part of TQFTs, they admit some natural surgery expressions. The case of the so-called SO₃ WRT invariants at level 5 seems to give the most straightforward condition. We find:

THEOREM 1.4. — Let $K \subset S^3$ be a knot, let J_K be its Jones polynomial, and assume that K has a purely cosmetic surgery pair $\{\pm s\}$. Then s is of the form $\pm \frac{1}{5k}$ for some $k \in \mathbb{Z}$, unless $J_K(e^{\frac{2i\pi}{5}}) = 1$.

At this point, the role of the 5-th root of unity, and multiples of 5 in the denominator of cosmetic surgery slopes may seem mysterious. This is mostly a matter of exposition: we will also get similar conditions out of SO₃ WRT TQFTs at different levels than 5; with the drawback that they involve several colored Jones polynomials of K. Here, let us write $J_{K,n}$ for the *n*-th normalized colored Jones polynomial of K, with the convention that $J_{K,1} = 1$ and $J_{K,2}$ is the Jones polynomial.

THEOREM 1.5. — Let $r \ge 5$ be an odd prime, ζ_r be a primitive *r*-th root of unity and *K* be a non-trivial knot. Let also $[n] = \frac{\zeta_r^n - \zeta_r^{-n}}{\zeta_r - \zeta_r^{-1}}$. There exists a finite set F_r of nonzero vectors in $\mathbb{C}^{\frac{r-1}{2}}$, with cardinality $|F_r| \le \frac{r+1}{2}$ such that if *K* has a purely cosmetic surgery pair, then either the slopes are of the form $\{\pm \frac{1}{rk}\}$ with $k \in \mathbb{Z}$, or the vector

$$v_{K} = \begin{pmatrix} 1 \\ -[2]J_{K,1}(\zeta_{r}^{2}) \\ [3]J_{K,2}(\zeta_{r}^{2}) \\ \vdots \\ (-1)^{\frac{r-3}{2}}[\frac{r-1}{2}]J_{K,\frac{r-3}{2}}(\zeta_{r}^{2}) \end{pmatrix}$$

is orthogonal to an element of F_r .

Remark 1.6. — The vectors in F_r can actually be naturally associated with pairs $\{\pm 2\}$ or $\{\pm \frac{1}{k}\}$ where \underline{k} is a non-zero element of $\mathbb{Z}/r\mathbb{Z}$. As the proof of Theorem 1.4 will show, if $E_K(2) \simeq E_K(-2)$, then v_K is orthogonal to $v_{\{\pm 2\}} \in F_r$ and if $E_K(\frac{1}{k}) \simeq E_K(-\frac{1}{k})$ then v_K is orthogonal to $v_{\{\frac{1}{k}\}} \in F_r$ where \underline{k} is the class of $k \mod r$. We note that the set F_r and the correspondence between slopes mod r and vectors is explicit, see Definition 4.1 and Remark 4.4 In particular, if one were able to compute the invariants n_t in Hanselman's theorem for a knot K, then it would suffice to test orthogonality of v_K with $v_{\{\pm 2\}}$ and with $v_{\{\pm \frac{1}{k'}\}}$ to rule out a purely cosmetic surgery pair for K.

Remark 1.7. — While the SO₃ WRT invariant at level r = 3 exists, it is entirely determined by homological data. It turns out that the level r = 5is the first one where the SO₃ WRT invariants give non-trivial information about cosmetic surgeries.

Let us now restrict to the simpler condition we get from the case r = 5and focus on the corollaries of Theorem 1.4.

Theorem 1.4 combined with Hanselman's results implies that if a knot K has a purely cosmetic surgery pair and $J_K(e^{\frac{2i\pi}{r}}) \neq 1$, then K must have a rather large crossing number.

COROLLARY 1.8. — If K is a non-trivial knot with at most 31 crossings and such that $J_K(e^{\frac{2i\pi}{5}}) \neq 1$, then K has no purely cosmetic surgery pair.

Proof. — By Theorem 1.4, if K has a purely cosmetic surgery pair then the slopes must be of the form $\pm \frac{1}{5k}$, so the denominator is at least 5.

By Hanselman's inequality and the fact that $g(K) \ge 2$ by [22], this implies that $th(K) \ge 16$.

However, Lowrance [13] proved that $th(K) \leq g_T(K)$, where $g_T(K)$ is the Turaev genus of K.

But for any knot K, the Turaev genus $g_T(K)$ is bounded above by c(K)/2 where c(K) is the crossing number of K (see for example [1, Proposition 2.4]).

Thus a knot with $c(K) \leq 31$ crossings has thickness at most 15, and can not have a purely cosmetic surgery pair if $J_K(e^{\frac{2i\pi}{5}}) \neq 1$.

Let us note that according to Hanselman's computations [9] a prime knot with at most 16 crossings has thickness at most 2, so the inequality $\operatorname{th}(K) \geq \frac{c(K)}{2}$ we used seems to be far from optimal.

The literature has been particularly interested in the special case of alternating knots. In that case, hypothetical alternating counterexamples of the conjecture have been shown to have a very special form. Indeed, Hanselman showed in [9, Theorem 3] that an alternating knot K (or, more generally, a *thin knot*, which has th(K) = 0) with a purely cosmetic surgery must have signature 0 and Alexander polynomial $\Delta_K(t) =$ $nt^2 - 4nt + (6n + 1) - 4nt^{-1} + nt^{-2}$ for some $n \in \mathbb{Z}$. As a corollary of our main result, we can put an extra condition on the Jones polynomial of K: COROLLARY 1.9. — If K is an alternating (or thin) knot with a purely cosmetic surgery, then $J_K(e^{\frac{2i\pi}{5}}) = 1$.

Proof. — It is also part of [9, Theorem 3] that the only possible purely cosmetic surgery pairs of thin knots are the pairs $\{\pm 1\}$ or $\{\pm 2\}$. By Theorem 1.4, K must satisfy $J_K(e^{\frac{2i\pi}{5}}) = 1$.

Finally, let us discuss some numerical estimates of the strength of this obstruction. Knots with $J_K(e^{\frac{2i\pi}{5}}) = 1$ seem to become increasingly rare when the number of crossings increases. Using a census of all 9,755,328 prime knots with at most 17 crossings and their Jones polynomials generated with the Regina software [4], we found that there are only 97 that have $J_K(e^{\frac{2i\pi}{5}}) = 1$. Following Regina's notation, those are the knots:

 $8nt_1, 9at_1, 11ah_{001}, 11at_1, 12ah_{0001}, 12ah_{0002}, 12nh_{003},$

 $13ah_{0002}, 13ah_{0004}, 13ns_2, 14ah_{00003}, 14ah_{00005},$

 $14ah_{00010}, 14ah_{00012}, 14ah_{00013}, 14ah_{00017}, 14ah_{00025}, 14nh_{00007}, 14nh_{00042}, 14nh_{00042},$

 $15ah_{00005}, 15ah_{00007}, 15ah_{00044}, 15ah_{00049}, 15ah_{00050},$

 $15ah_{00070}, 15ah_{00072}, 15nh_{000019}, 15nt_1,$

 $16ah_{000006}, 16ah_{000009}, 16ah_{000010}, 16ah_{000019}, 16ah_{000060}, 16ah_{000062}, 16ah_{000062}, 16ah_{000062}, 16ah_{000062}, 16ah_{000066}, 16ah_{00066}, 16ah_{0006}, 16ah_{0006}, 16ah_{0006}, 16ah_{00$

 $16ah_{000069}, 16ah_{000100}, 16ah_{000104}, 16ah_{000105}, 16ah_{000116}, 16ah_{000137}, 16ah$

 $16ah_{000139}, 16ah_{000141}, 16ah_{000153}, 16ah_{000209}, 16ah_{000253}, 16ah_{000447}, \\$

 $17ah_{0000008}, 17ah_{0000010}, 17ah_{0000032}, 17ah_{0000081}, 17ah_{0000112}, \\$

 $17ah_{0000137}, 17ah_{0000138}, 17ah_{0000161}, 17ah_{0000170}, 17ah_{0000243}, \\$

 $17ah_{0000374}, 17ah_{0000376}, 17ah_{0000384}, 17ah_{0000495}, 17ah_{0000500},$

 $17ah_{0000544}, 17ah_{0000545}, 17ah_{0000593}, 17ah_{0000634}, 17ah_{0000685}, \\$

 $17ah_{0000687}, 17ah_{0000786}, 17ah_{0000979}, 17ah_{0001175}, 17ah_{0001352},$

 $17ah_{0001734}, 17ah_{0001883}, 17ah_{0002693}, 17ah_{0003282}, 17nh_{0000002},$

 $17nh_{0000327}, 17nh_{0000473}, 17nh_{0000765}, 17nh_{0005618}, 17nh_{0005619}.$

Only two of those knots satisfy $\Delta_K''(1) = 0$ and $J_K'''(1) = 0$, the knots $14nh_{00042}, 16ah_{000209}$. We get the following corollary:

COROLLARY 1.10. — No non-trivial knot with at most 17 crossings admits purely cosmetic surgeries.

Proof. — The two exceptions $14nh_{00042}$ and $16ah_{000209}$ that we found were covered by Hanselman's [9] treatment of knots with at most 16 crossings; for those two knots a purely cosmetic surgery can be excluded from

the computation of HFK. Moreover, by [18], a knot with a purely cosmetic surgery pair must be prime. $\hfill \Box$

Remark 1.11. — Since $J''_K(1) = -3\Delta''(1)$ (see [15, Lemma 2.1]), computing only the Jones polynomial one can exclude all but two knots with at most 17 crossings from having a purely cosmetic surgery. While we simply used Hanselman's previous results to exclude those two knots, we could have tried out the criterion in Theorem 1.4 for r = 7 to exclude those last two slopes instead.

We note that Sikora and Tuzun [20] have done extensive computations of Jones polynomials of knots with at most 22 crossings, in order to verify the Jones unknot detection conjecture up to that crossing number. A numerical strategy to verify the conjecture up to some crossing number would be to test knots for the criterions $\Delta_K''(1) = 0$ and $J_K'''(1) = 0$ which are fast to check, if both compute whether $J_K(\zeta_5) = 1$, then for the remaining exceptions use the criterion for primes $r \ge 7$. In forthcoming work, we plan to implement the criterion in Theorem 1.4 for primes $r \ge 7$ to be able to verify the conjecture for the whole census of knots with at most 19 crossings on Regina.

The paper is organized as follows: in Section 2, we review the basics of the SO(3) WRT TQFTs that we will use. In Section 3, we derive the formula of the SO(3) WRT TQFTs of Dehn surgeries of a knot from TQFT axioms. In Section 4, we prove Theorem 1.5 using the surgery formula and deduce Theorem 1.4.

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2. Preliminaries

2.1. SO_3 WRT TQFTs and extended cobordisms

In this section, we review some well-known properties of WRT TQFTs needed in this paper. Although they were initially defined by Reshetikhin and Turaev in [17] to realize Witten's [23] interpretation of the Jones polynomial as a quantum field theory based on the Chern–Simons invariant, it is really the so-called SO₃ TQFTs in the framework of Blanchet, Habegger, Masbaum and Vogel [2] that we will present here. We note that the 3-manifold invariant associated to the SO₃ TQFT is up to normalization identical to the τ'_r invariants of Kirby and Melvin [12].

The SO₃ TQFTs in [2] have a so-called *anomaly*, meaning that the associated representation of mapping class groups are projective: they take value in the Lie group $\operatorname{GL}_d(\mathbb{C})/u_r^{\mathbb{Z}}$ where d is an integer and u_r is a 2r-th root of unity. Lifting this anomaly requires one to work with a category of 2+1 cobordisms with an additional structure, either a p_1 -structure as in [2], or a so-called extended structure by an approach initiated by Walker [21] and further developped by Turaev [19]. We will use the latter approach here.

Let us define extended 3-manifolds as pairs (M, n) where M is a compact oriented 3-manifold and $n \in \mathbb{Z}$. The integer n is called the weight of the extended 3-manifold, and intuitively encodes a choice of signature of a 4manifold bounding M. A connected extended surface (Σ, L) will consist of a compact oriented surface Σ with a choice of Lagrangian $L \subset H_1(\Sigma, \mathbb{Q})$. Manifolds with boundary will be equipped with a weight and a Lagrangian in each boundary component. For any two extended 3-manifolds (M_1, n) and (M_2, m) such that (Σ, L) is the common boundary of (M_1, n) and (M_2, m) , the gluing is the extended closed 3-manifold

$$\left(M_1 \prod_{\Sigma} \overline{M_2}, n+m-\mu \left(\lambda_{M_1}(\Sigma), L, \lambda_{M_2}(\Sigma)\right)\right),$$

where $\lambda_{M_i}(\Sigma) = \ker H_1(\Sigma, \mathbb{Q}) \to H_1(M_i, \mathbb{Q})$ and μ is the Maslov index, which can be computed from the following definition.

DEFINITION 2.1. — Let (V, ω) be a finite dimensional symplectic \mathbb{Q} -vector space, let L_1, L_2, L_3 be Lagrangians in V, and let $W = \{(x_1, x_2) \in L_1 \times L_2 \mid x_1 + x_2 \in L_3\}$. Then the Maslov index $\mu(L_1, L_2, L_3)$ is the signature of the symmetric bilinear form B on W defined by $B((x_1, x_2), (y_1, y_2)) = \omega(x_1, y_2)$.

We recall that the Maslov index changes sign under any odd permutation of L_1, L_2, L_3 . In particular, it vanishes whenever two Lagrangians are equal.

Similar rules apply for the gluing of cobordisms, where the weight of the gluing has to be computed using some Maslov indices. That construction applied to mapping cylinders gives rise to the so-called *extended mapping class group* of surfaces, which we define below:

DEFINITION 2.2. — For Σ a compact oriented surface, and $L \subset H_1(\Sigma, \mathbb{Q})$ a Lagrangian, the extended mapping class group $\widetilde{Mod}(\Sigma)$ is the \mathbb{Z} -central



Figure 2.1. The second Kauffman relation.

extension of $Mod(\Sigma)$ defined by the rule

 $(f, n) \circ (g, m) = (f \circ g, n + m + \mu(L, f(L), (f \circ g)(L)))$

for any $f, g \in Mod(\Sigma)$ and any $n, m \in \mathbb{Z}$.

2.2. The SO_3 invariants from skein theory

Here we review the TQFT constructions defined in [2]. We will first give the definition of the SO₃ invariants of an extended closed 3-manifold (M, n), which are computed from the evaluation at roots of unity of the Kauffman bracket of some cablings of a surgery presentation of M.

Let us fix an odd integer $r \ge 3$, and let A_r be a primitive 2*r*-th root of unity. For any integer $n \in \mathbb{Z}$ the quantum integer [n] is given by

$$[n] = \frac{A_r^{2n} - A_r^{-2n}}{A_r^2 - A_r^{-2}}$$

Let us now recall the definition of the Kauffman bracket $\langle L \rangle$ of a framed link in S^3 . It is an invariant of framed links completely determined by the normalization $\langle \emptyset \rangle = 1$, and the two Kauffman relations: $\langle L \cup U \rangle =$ $(-A^2 - A^{-2})\langle L \rangle$, where $L \cup U$ denotes the disjoint union of a framed link and a 0-framed unknot, and the second Kauffman relation relating 3 links that differ only in a ball is shown in Figure 2.1.

Furthermore, the colored Kauffman bracket $\langle L, c \rangle$ of a link L whose components are colored by elements of $\mathbb{C}[z]$ is defined in the following way: if all components L_i 's are colored by monomials z^{d_i} , then just replace the component L_i by d_i parallel copies and compute the Kauffman bracket. Otherwise, expand by multilinearity.

Now, suppose that M has a surgery presentation $M = S^3(L)$, when L is a framed link in S^3 . Let us write r = 2m+1, and let $\omega = \sum_{i=1}^m (-1)^{i-1} [i] e_i$, when $e_i(z)$ is the *i*-th Chebyshev polynomial, defined by $e_1(z) = 1$, $e_2(z) = z$ and $e_{i+1}(z) = ze_i(z) - e_{i+1}(z)$. We recall that $[i] = \frac{A_r^{2i} - A_r^{-2i}}{A_r^2 - A_r^{-2}}$ is the *i*-th quantum integer.

Finally, we introduce some important constants:

DEFINITION 2.3. — For $r \ge 3$ an odd integer, we set

$$\eta_r = \frac{(A_r^2 - A_r^{-2})}{\sqrt{-r}}$$
 and $\kappa_r = \eta_r \langle U_-, \omega \rangle = \eta_r \sum_{i=1}^{\frac{r-1}{2}} (-A_r)^{-(i^2-1)} [i]^2$,

where U_{-} is the unknot with framing -1. Moreover, when $A_r = e^{\frac{i\pi}{r}}$, a closed formula for κ_r is

$$\kappa_r = i^{\frac{r+1}{2}} e^{\frac{3i\pi}{r}}.$$

THEOREM 2.4 ([19, Theorem 2.2.2]). — If M is obtained by surgery on a framed link $L \subset S^3$, with n(L) components and signature $\sigma(L)$, then

$$Z_r(M,\sigma(L)) = \eta_r^{1+n(L)} \langle L, \omega, \omega, \dots, \omega \rangle$$

is a topological invariant of the extended 3-manifold $(M, \sigma(L))$. Furthermore, if M contains a colored link (K, c), then

$$Z_r(M, \sigma(L), K, c) = \eta_r^{1+n(L)} \langle L \cup K, \omega, \dots, \omega, c \rangle$$

is a topological invariant of the extended 3-manifold $(M, \sigma(L), K, c)$. In both cases, the invariant satisfies $Z_r(M, n) = \kappa_r^{-n} Z_r(M, 0)$.

Although we defined the invariant for extended 3-manifolds, for any 3manifold the quantity $Z_r(M) = Z_r(M, 0)$ is a topological invariant of M. The last property allows one to compute $Z_r(M)$ from any surgery presentation of M, no matter the signature, by renormalizing by the appropriate power of κ_r . We also note that the definition of the invariants $Z_r(M, n)$ from the Kauffman bracket comes from [2, Section 2].

2.3. The SO_3 WRT TQFTs

The SO₃ WRT invariants Z_r are part of a TQFT defined on the category of extended cobordisms in dimension 2 + 1. Objects of this category are extended surfaces and morphisms are (homeomorphism classes fixing the boundary of) extended cobordism of dimension 3, as introduced in Section 2.1. The disjoint union gives the category a monoidal structure, and the invariant Z_r can be extended to a monoidal functor from the category of extended 2 + 1-cobordisms to the category of complex vector spaces. Concretely speaking, we have the following:

THEOREM 2.5 ([2, Theorem 1.4]). — For any odd integer $r \ge 3$, we have:

• For any closed compact oriented 3-manifold M, $Z_r(M) = Z_r(M, 0)$ is a \mathbb{C} -valued topological invariant.

- For every closed compact oriented extended surface (Σ, L), Z_r(Σ, L) is a finite dimensional vector space with a natural Hermitian form ⟨⟨·,·⟩⟩.
- For any compact oriented extended 3-manifold M = (M, 0), containing a link $K \subset M$, and with a fixed homeomorphism $\partial M \simeq \Sigma$, and a choice of Lagrangian $L \subset H_1(\Sigma, \mathbb{Q}), Z_r(M, K)$ is a vector in $Z_r(\Sigma, L)$, and $Z_r(\Sigma, L)$ is spanned by such vectors.
- The extended mapping class group $Mod(\Sigma)$, acting on extended 3-manifolds with boundary (Σ, L) , gives rise to a representation

$$\rho_r : \operatorname{Mod}(\Sigma) \longrightarrow \operatorname{Aut}(Z_r(\Sigma, L))$$

called the SO_3 quantum representation.

• For any two extended 3-manifolds (possibly with links) $(M_1, 0)$ and $(M_2, 0)$ with $\partial M_1 \simeq \partial M_2 \simeq (\Sigma, L)$, the underlying closed 3manifold $M = M_1 \coprod_{\Sigma} \overline{M_2}$ has invariant

$$Z_r(M) = \kappa_r^{\mu(\lambda_{M_1}(\Sigma), L, \lambda_{M_2}(\Sigma))} \langle\!\langle Z_r(M_1), Z_r(M_2) \rangle\!\rangle$$

We also refer to [19, Chapter IV] for a comprehensive treatment of TQFT axioms, in particular the gluing rules involving Maslov indices.

In this paper, we will only compute WRT invariants of manifolds that are Dehn surgeries of knots rather than links, and will use the TQFT properties of Z_r to compute them. That is, we will use the last point of Theorem 2.5 in the special case where Σ is a torus, M_1 is a knot complement in S^3 and M_2 is a solid torus. Therefore we will now focus on the TQFT space and quantum representation of the torus.

2.4. Quantum representations of the torus

We first describe a basis of the Z_r TQFT-space of the torus \mathbb{T}^2 . We will fix the choice of Lagrangian in $H_1(\mathbb{T}^2, \mathbb{Q})$ to be the subspace generated by the class of the meridian $S^1 \times \{0\}$, and therefore no longer make reference to the choice of Lagrangian in this section.

If $1 \leq i \leq \frac{r-1}{2}$, let f_i be the vector in $Z_r(\mathbb{T}^2)$ corresponding to the solid torus $D^2 \times S^1$ with boundary T^2 and meridian $S^1 \times \{0\}$, containing the framed knot $\{[0,\varepsilon]\} \times S^1$ colored by $e_i(z)$. In particular, f_1 corresponds to the solid torus with the empty link inside, since $e_1(z) = z^0 = 1$.

PROPOSITION 2.6 ([2, Corollary 4.10]). — Let $r = 2m + 1 \ge 3$ be an odd integer. The vector space $Z_r(\mathbb{T}^2)$ admits f_1, \ldots, f_m as an orthonormal basis.

With this in mind, we will now describe the quantum representations of the torus, in the above basis.

Let us recall that the mapping class group of the torus is isomorphic to $\operatorname{SL}_2(\mathbb{Z})$, and generated by the two matrices $T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ and $T = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. As mapping classes, T corresponds to the Dehn-twist along the meridian $S^1 \times \{0\}$ of $\mathbb{T}^2 = S^1 \times S^1$, and S to the map S(u, v) = (-v, u) of order 4. A presentation of $\operatorname{SL}_2(\mathbb{Z})$ is then given by

$$\mathrm{SL}_2(\mathbb{Z}) = \langle S, T | S^4 = 1, S^2 = (ST)^3 \rangle.$$

In the extended mapping class group, the relations turn into

$$(S,0)^4 = (\mathrm{Id},0), \ (S,0)^2 = (S^2,0) \text{ and } ((S,0)(T,0))^3 = (S^2,1).$$

Indeed, let a, b be the basis of $H_1(\mathbb{T}^2, \mathbb{Q})$ given by the class of the meridian $S^1 \times \{0\}$ and longitude $\{0\} \times S^1$.

For $x \in \mathbb{R}$, let $\operatorname{sign}(x)$ be 0 if x = 0, and $\frac{x}{|x|}$ otherwise. We have the following quick rule to compute Maslov indices in the case of the torus:

LEMMA 2.7. — Let $L_1 = \text{Span}(x)$, $L_2 = \text{Span}(y)$ and $L_3 = \text{Span}(z)$ be Lagrangians of $H_1(\mathbb{T}^2, \mathbb{Q})$. Then, if any two of x, y, z are linearly dependent, then $\mu(L_1, L_2, L_3) = 0$, and otherwise if $z = \alpha x + \beta y$, then

$$\mu(L_1, L_2, L_3) = \operatorname{sign}(\alpha \beta \omega(x, y)).$$

Proof. — Follows from Definition 2.1.

To simplify notation, we will write $\mu(x, y, z)$ for

$$\mu(\operatorname{Span}(x), \operatorname{Span}(y), \operatorname{Span}(z)).$$

We can compute that $(S, 0)^2 = (S^2, \mu(a, b, a)) = (S^2, 0)$ and

$$(S,0)^4 = (S^4, \mu(a, a, a)) = (\mathrm{Id}, 0).$$

Moreover,

$$\begin{split} (S,0)(T,0) &= (ST,\mu(a,b,a)) = (ST,0),\\ (ST,0)^2 &= ((ST)^2,\mu(a,b,-a+b)) = ((ST)^2,-1),\\ (ST,0)^3 &= ((ST)^3,-1+\mu(a,-a+b,-a)) = (S^2,-1) \end{split}$$

PROPOSITION 2.8 ([7, Section 2]). — We have, in the basis e_i , that

$$\rho_r((T,0))f_i = (-A_r)^{i^2-1}f_i$$

and

$$\rho_r((S,0))f_i = \eta_r \sum_{1 \le j \le \frac{r-1}{2}} (-1)^{i+j} [ij]f_j.$$

Moreover, $\rho_r((\mathrm{Id}, 1)) = \kappa_r \mathrm{Id}.$

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Remark 2.9. — Note that the matrix $\rho_r(T)$ is diagonal with distinct eigenvalues, since $(-A_r)$ is a primitive *r*-th root of 1, and the $i^2 - 1$ are all distinct modulo *r* for $1 \leq i \leq \frac{r-1}{2}$.

To simplify notation, we will sometimes abusively write $\rho_r(S^{n_1}T^{n_2}...S^{n_k})$ for $\rho_r((S,0)^{n_1}(T,0)^{n_2}...(S,0)^{n_k})$, even though ρ_r is defined on $\widetilde{\mathrm{Mod}}(\mathbb{T}^2)$ instead of $\mathrm{SL}_2(\mathbb{Z})$. If the word in the generators S and T is fixed then there is no ambiguity.

The following lemma shows that the above definition yields a projective representation of $_2(\mathbb{Z})$, or a linear representation of the extended mapping class group $\widetilde{\text{Mod}}(\mathbb{T}^2)$:

LEMMA 2.10. — The matrices $\rho_r(S)$ and $\rho_r(T)$ are unitary for $\langle\!\langle \cdot, \cdot \rangle\!\rangle$, and we have $\rho_r(T^r) = \text{Id}$, $\rho_r(S^2) = \text{Id}$ and $\rho_r((ST)^3) = \kappa_r^{-1} \text{Id}$.

Proof. — We refer to [19, Section II.3.9] for a proof. Note that our constants η_r and κ_r correspond to the constants \mathcal{D}^{-1} and $\Delta \mathcal{D}^{-1}$, and our matrices $\rho_r((S,0))$ and $\rho_r((T,0))$ are the same as the matrices $\mathcal{D}^{-1}S$ and T in [19]. Finally J = Id in our context. Then in [19] the equivalent relation $\rho_r(STS) = \kappa_r^{-1}\rho_r(T^{-1}ST^{-1})$ is proven.

3. Surgery formulas for Z_r

In this section, we will present formulas that express the Z_r invariant of a Dehn surgery on a knot in terms of its colored Jones polynomials. We will first describe the surgery formulas for Z_r for arbitrary slopes, then we will specialize to slopes of the form $\frac{1}{k}, k \in \mathbb{Z}$ or ± 2 . We have the following:

PROPOSITION 3.1. — Let K be a framed knot in S^3 , and let $r = 2m + 1 \ge 3$ be an odd integer. Then, in the basis e_1, \ldots, e_m , we have

$$Z_r(E_K) = Z_r(E_K, 0) = \eta_r \begin{pmatrix} 1 \\ \langle K, e_2 \rangle \\ \langle K, e_3 \rangle \\ \vdots \\ \langle K, e_m \rangle \end{pmatrix}.$$

Moreover, if ϕ is any element of $Mod(\partial E_K)$ which sends the meridian of K to the curve of slope s, then

$$Z_r(E_K(s),0) = \kappa_r^{-\operatorname{sign}(s)} \langle\!\langle Z_r(E_K), \rho_r(\phi,0)e_1 \rangle\!\rangle,$$

where by definition sign(s) = 0 for $s \in \{0, \infty\}$.

Proof. — The first identity expresses the fact that pairing E_K with the basis vectors e_i , we simply get the manifold S^3 with the link K colored by e_i in it. By Theorem 2.4, η_r is the Z_r invariant of S^3 , and adding a knot K colored by e_i multiplies the invariant by $\langle K, e_i \rangle$.

As for the second identity, recall that f_1 is the vector corresponding to the solid torus (with meridian the meridian of K). Thus the second identity follows from the last part of Theorem 2.5 and the definition of the quantum representation, once we show that the Maslov index is $-\operatorname{sign}(s)$.

Since we equip the torus with the span Span(a) of the meridian as Lagrangian, and the longitude b bounds a surface in E_K while the curve of slope s = p/q bounds a disk in the solid torus, by Lemma 2.7, this Maslov index is

$$\mu(b, a, pa + qb) = -\operatorname{sign}(p/q) = -\operatorname{sign}(s)$$

In the cases s = 0 or $s = \infty$ the Maslov index vanishes.

Remark 3.2. — One may want to compare the vector $Z_r(E_K)$ with the vector v_K in Theorem 1.5. To do this, we should say that while the colored Jones polynomials are invariants of knots, the colored Kauffman brackets are invariants of framed knots only. However, when talking about the cosmetic surgery problem for a knot K, a framing on K is somewhat implicit, if we want to be able to talk about slopes on the knot.

Taking the convention that we chose as framing for K the longitude with zero winding number, we have

$$\langle K, e_i \rangle (A_r) = (-1)^{i-1} [i] J_{K,i}(A_r^4) = (-1)^{i-1} [i] J_{K,i}(\zeta_r^2),$$
where $[i] = \frac{A_r^{2i} - A_r^{-2i}}{A_r^2 - A_r^{-2}} = \frac{\zeta_r^i - \zeta_r^{-i}}{\zeta_r - \zeta_r^{-1}}.$

Remark 3.3. — The map $\phi \in \text{Mod}(\mathbb{T}^2)$ which sends the meridian to the curve of slope s is not unique. However, any two such maps differ by multiplication on the right by T^k , with $k \in \mathbb{Z}$. As $\rho_r(T)f_1 = f_1$, the pairing $\langle \langle Z_r(E_K), \rho_r(\phi)f_1 \rangle \rangle$ does not depend on the choice of ϕ .

PROPOSITION 3.4. — Let K be a knot in S^3 . Then, we have

$$Z_r(E_K(\frac{1}{k}), 0) = \langle\!\langle Z_r(E_K), \rho_r(ST^{-k}S)f_1 \rangle\!\rangle$$

and

$$Z_r(E_K(2),0) = \kappa_r^{-1} \langle\!\langle Z_r(E_K), \rho_r(T^2S)f_1 \rangle\!\rangle,$$

$$Z_r(E_K(-2),0) = \kappa_r \langle\!\langle Z_r(E_K), \rho_r(T^{-2}S)f_1 \rangle\!\rangle.$$

We note that writing the continued fraction expansion of s = p/q, one can find a word in the generators S and T that maps the meridian to the curve

of slope s. Giving similar surgery formula then amounts to computing the contribution $\kappa_r^{m_s}$ coming from Maslov indices, where m_s is an integer that can be computed from the continued fraction expansion of s = p/q. Explicit formulas for m_s involve Dedekind sums and Rademacher ϕ functions, for example closely related computations can be found in [11], where the Z_r invariant of lens spaces is computed.

Moreover, closely related surgery formulas for the τ'_r invariant for the integer and 1/k-surgeries were computed in [12].

Proof. — First, let us show that $(S,0)(T,0)^{-k}(S,0) = (ST^{-k}S, \operatorname{sign}(k))$ and $(T,0)^{\pm 2}(S,0) = (T^{\pm 2}S,0)$. We compute that $(T,0)^k = (T^k,0)$ for any $k \in \mathbb{Z}$ by induction as $\mu(a, a, a) = 0$. Moreover,

$$(S,0)(T^{-k},0) = (ST^{-k},\mu(a,b,b)) = (ST^{-k},0),$$

$$(ST^{-k}, 0)(S, 0) = (ST^{-k}S, \mu(a, b, -a - kb)) = (ST^{-k}S, \operatorname{sign}(k)),$$

and

$$(T^{\pm 2}, 0)(S, 0) = (T^{\pm 2}S, \mu(a, a, \mp 2a - b)) = (T^{\pm 2}S, 0).$$

Now, by Proposition 3.1, we have

$$Z_r(E_K(\frac{1}{k})) = \kappa_r^{-\operatorname{sign}(k)} \langle\!\langle Z_r(E_K), \rho_r(ST^{-k}S, 0)f_1 \rangle\!\rangle$$
$$= \kappa_r^{-\operatorname{sign}(k)} \langle\!\langle Z_r(E_K), \kappa_r^{-\operatorname{sign}(k)} \rho_r(ST^{-k}S)f_1 \rangle\!\rangle$$
$$= \langle\!\langle Z_r(E_K), \rho_r(ST^{-k}S)f_1 \rangle\!\rangle$$

where the last equality uses that $\langle\!\langle \cdot, \cdot \rangle\!\rangle$ is anti-linear on the right. Similarly, we have

$$Z_r(E_K(2)) = \kappa_r^{-1} \langle\!\langle Z_r(E_K), \rho_r(T^2S, 0) f_r \rangle \rangle$$
$$= \kappa_r^{-1} \langle\!\langle Z_r(E_K), \rho_r(T^2S) f_1 \rangle\!\rangle$$

and

$$Z_r(E_K(-2)) = \kappa_r \langle\!\langle Z_r(E_K), \rho_r(T^{-2}S, 0)f_1 \rangle\!\rangle$$
$$= \kappa_r \langle\!\langle Z_r(E_K), \rho_r(T^{-2}S)f_1 \rangle\!\rangle.$$

 $(0) f_1 \rangle\rangle$

4. Proof of the main theorems

Before we move to the proof of Theorem 1.5, we will explicitly describe the finite set F_r of vectors in $Z_r(\mathbb{T}^2)$.

DEFINITION 4.1. — Let $r \ge 5$ be a prime. We define

$$F_r = \{ \rho_r(ST^{-k}S)f_1 - \rho_r(ST^kS)f_1, 1 \le k \le \frac{r-1}{2} \} \\ \cup \{ \rho_r(T^2S)f_1 - \kappa_r^{-2}\rho_r(T^{-2}S)f_1 \},$$

where we write $\rho_r(T)$, $\rho_r(S)$ for the matrices $\rho_r((S,0))$, $\rho_r((T,0))$ defined in Proposition 2.8 and κ_r is the constant defined in Definition 2.3 for $A_r = e^{\frac{i\pi}{r}}$.

It is clear from the definition that $|F_r| \leq \frac{r+1}{2}$. The following lemma shows that F_r contains only non-zero vectors:

LEMMA 4.2. — Let $r \ge 5$ be an odd prime. Then,

$$\rho_r(ST^{-k}S)f_1 - \rho_r(ST^kS)f_1 = 0$$
 if and only if $k = 0 \mod r$.

Moreover, $\rho_r(T^2S)f_1 - \kappa_r^{-2}\rho_r(T^{-2}S)f_1 \neq 0.$

 $\begin{aligned} &Proof. & -\text{Note that as } \rho_r(T^r) = \text{Id, if } k = 0 \mod r, \text{ then } \rho_r(ST^{\pm k}S) = \\ &\rho_r(S^2) = \text{Id and thus } \rho_r(ST^{-k}S)f_1 - \rho_r(ST^kS)f_1 = 0. \text{ Now, by contradiction assume } \rho_r(ST^{-k}S)f_1 = \rho_r(ST^kS)f_1 \text{ but } k \neq 0 \mod r. \text{ Then applying } \\ &\rho_r(T^kS) \text{ on the left we get } \rho_r(T^{2k}S)f_1 = \rho_r(S)f_1. \text{ So, } \rho_r(S)f_1 \text{ must be an eigenvector of } \rho_r(T^{2k}) \text{ of eigenvalue 1. As the order of } r \text{ is coprime with } \\ &2k, \text{ we deduce that } \rho_r(S)f_1 \text{ must be an eigenvector of } \rho_r(T) \text{ of eigenvalue } \\ &1, \text{ thus } \rho_r(S)f_1 \text{ must be colinear to } f_1 \text{ by Remark 2.9. This is not the case: } \\ &\text{ as all quantum integers } [i] = \frac{A_r^{2i} - A_r^{-2i}}{A_r^2 - A_r^{-2}} \text{ with } 1 \leqslant i \leqslant \frac{r-1}{2} \text{ are non-zero, } \\ &\rho_r(S)f_1 \text{ has non-zero coefficient along each } f_i. \text{ Note that we use here that } \\ &\dim(Z_r(\mathbb{T}^2)) \geqslant 2 \text{ for } r \geqslant 5. \end{aligned}$

Now, by contradiction assume that $\rho_r(T^2S)f_1 = \kappa_r^{-2}\rho_r(T^{-2}S)f_1$, then similarly $\rho_r(S)f_1$ must be an eigenvector of $\rho_r(T^4)$, and thus an eigenvector of $\rho_r(T)$ as 4 is coprime to r which is the order of T. Note that the diagonal coefficients $(-A_r)^{i^2-1}$ where $i = 1, \ldots, \frac{r-1}{2}$ of $\rho_r(T)$ are all distinct (see Remark 2.9). Thus $\rho_r(S)f_1$ would have to be collinear to one of the f_i 's, which is not the case.

Remark 4.3. — The proof above uses the fact that r > 3. In the case of r = 3, we would find that $\dim(Z_3(\mathbb{T}^2)) = 1$, $\kappa_3 = 1$, $\rho_3(S) = \eta_3 = 1$ and $\rho_3(T) = 1$. This implies that when r = 3, all of the vectors in Definition 4.1 are zero.

We are now ready to prove Theorem 1.5:

Proof of Theorem 1.5. — Fix $r \ge 5$ an odd prime. Let K be a knot in S^3 with a purely cosmetic surgery pair s > s'. By Theorem 1.2, the slopes s, s' must be opposite and $s = \frac{1}{k}$ or s = 2.

Let us consider the first case and assume that r does not divide k. We have $E_K(\frac{1}{k}) \simeq E_K(-\frac{1}{k})$, thus the Z_r invariants coincide: $Z_r(E_K(\frac{1}{k})) = Z_r(E_K(-\frac{1}{k}))$. By Proposition 3.4 we have

$$\langle\!\langle Z_r(E_K), \rho_r(ST^{-k}S)f_1 - \rho_r(ST^kS)f_1 \rangle\!\rangle = Z_r(E_K(\frac{1}{k})) - Z_r(E_K(-\frac{1}{k})) = 0.$$

Note that $\rho_r(ST^{\pm k}S)f_1$ depends only on $k \mod r$ as $\rho_r(T^r) = \text{Id.}$ Let $l \in \{\pm 1, \pm 2, \ldots, \pm \frac{r-1}{2}\}$ be such that $k = l \mod r$. Then $Z_r(E_K)$ must be orthogonal to the vector $\rho_r(ST^{-l}S)f_1 - \rho_r(ST^lS)f_1$. Either this vector or its opposite is in the set F_r , so the claim is proved in that case.

Similarly, in the case where $E_K(2) \simeq E_K(-2)$, applying Proposition 3.4, we get that

$$\langle\!\langle Z_r(E_K), \rho_r(T^2S)f_1 - \kappa_r^{-2}\rho_r(T^{-2}S)f_1\rangle\!\rangle = \kappa_r^{-1}(Z_r(E_K(2)) - Z_r(E_K(-2))) = 0,$$

and thus $Z_r(E_K)$ is orthogonal to $\rho_r(T^2S)f_1 - \kappa_r^{-2}\rho_r(T^{-2}S)f_1$, which is in F_r by definition.

Remark 4.4. — The proof of Theorem 1.4 makes clear that if $k = \pm l$ mod r with $1 \leq l \leq \frac{r-1}{2}$ and $\{\pm \frac{1}{k}\}$ is a purely cosmetic surgery pair for a knot K, then $Z_r(E_K)$ is orthogonal to a specific vector in F_r , namely the vector $\rho_r(ST^{-l}S)f_1 - \rho_r(ST^lS)f_1$. Similarly, if $\{\pm 2\}$ is a purely cosmetic surgery pair, then $Z_r(E_K)$ is orthogonal to $\rho_r(T^2S)f_1 - \kappa_r^{-2}\rho_r(T^{-2}S)f_1$.

Remark 4.5. — Note that the unknot admits $\pm \frac{1}{k}$ cosmetic surgery pair for any $k \in \mathbb{Z}$, and that ± 2 is also a purely cosmetic surgery pair for the unknot. Therefore the vector $Z_r(E_U)$ is orthogonal to all of the vectors in F_r . As $Z_r(E_U) = \rho_r(S)f_1$ is a non-zero vector, all of the vectors in F_r actually lie in a codimension 1 subspace of $Z_r(\mathbb{T}^2)$.

The proof of Theorem 1.4 is a simple corollary of Theorem 1.5, Remark 4.5, and the fact that if r = 5, then the dimension of $Z_r(\mathbb{T}^2)$ is 2.

Proof of Theorem 1.4. — By Theorem 1.5, if K has a purely cosmetic surgery pair $\pm s$ then either the slope s is of the form $\frac{1}{5k}$ or $Z_5(E_K)$ must be orthogonal to one of the (non-zero) vectors in F_5 . Note that the vector of the unknot $Z_5(E_U) = \rho_r(S)f_1 \neq 0$ is orthogonal to all of the vectors in F_5 by Remark 4.5. As dim $(Z_5(\mathbb{T}^2)) = \frac{5-1}{2} = 2$, the vectors in F_5 are all colinear and any vector orthogonal to a vector in F_5 must be colinear to $Z_5(E_U)$.

So if the slope s is not of the form $\frac{1}{5k}$, the vector $Z_r(E_K) = \eta_5 \begin{pmatrix} 1 \\ -[2]J_K(\zeta_5^2) \end{pmatrix}$ must be collinear to $Z_r(E_U) = \eta_5 \begin{pmatrix} 1 \\ -[2] \end{pmatrix}$.

As η_5 and [2] are non-zero, this implies that $J_K(\zeta_5^2) = 1$. By Galois action, we also have $J_K(\zeta_5) = 1$.

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