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EFFECTIVE QUASIMORPHISMS ON RIGHT-ANGLED ARTIN GROUPS

by Talia FERNÓS, Max FORESTER & Jing TAO (*)

Abstract. — We construct families of quasimorphisms on many groups acting on CAT(0) cube complexes. These quasimorphisms have a uniformly bounded defect of 12, and they “see” all elements that act hyperbolically on the cube complex. We deduce that all such elements have stable commutator length at least 1/24.

The group actions for which these results apply include the standard actions of right-angled Artin groups on their associated CAT(0) cube complexes. In particular, every non-trivial element of a right-angled Artin group has stable commutator length at least 1/24.

These results make use of some new tools that we develop for the study of group actions on CAT(0) cube complexes: the essential characteristic set and equivariant Euclidean embeddings.


Les actions pour lesquelles ces résultats sont vérifiés comprennent l’action standard d’un groupe d’Artin à angles droits sur son complexe cubique associé. En particulier, la longueur stable des commutateurs de tout élément non trivial d’un groupe d’Artin à angles droits est minorée par 1/24.

Ces résultats reposent sur de nouveaux outils que nous développons pour étudier les actions de groupes sur des complexes cubiques CAT(0) : l’ensemble caractéristique essentiel et les plongements euclidiens équivalents.

Keywords: quasimorphism, stable commutator length, bounded cohomology, CAT(0) cube complex, right-angled Artin group, median property.

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1. Introduction

In this paper, we construct quasimorphisms on groups that admit actions on CAT(0) cube complexes. Our emphasis is on finding quasimorphisms that are both efficient and effective. By “efficient” we mean that the quasimorphisms have low defect. By “effective” we mean that the quasimorphisms take non-zero values on specified elements of the group. These two qualities, taken together, allow one to establish lower bounds for stable commutator length (scl) in the group.

According to Bavard Duality [1], if \( \varphi \) is a homogeneous quasimorphism of defect at most \( D \) and \( \varphi(g) \geq 1 \), then \( \text{scl}(g) \geq 1/2D \). Thus, for the strongest bound on scl, one needs to find effective quasimorphisms with the smallest possible defect.

The quasimorphisms we define have similarities with the “non-overlapping” counting quasimorphisms of Epstein and Fujiwara [15], which in turn are a variation of the Brooks counting quasimorphisms on free groups [6]. If \( X \) is a CAT(0) cube complex, there is a notion of a tightly nested segment of half-spaces in \( X \). If \( G \) acts on \( X \) non-transversely (see Definition 4.1), then for each tightly nested segment \( \gamma \) there is an associated counting quasimorphism \( \varphi_\gamma \). This function counts non-overlapping copies (or \( G \)-translates) of \( \gamma \) and \( \overline{\gamma} \) inside characteristic subcomplexes of elements of \( G \). Using the median property of CAT(0) cube complexes, we show that \( \varphi_\gamma \) has defect at most 6, and therefore its homogenization \( \hat{\varphi}_\gamma \) has defect at most 12. (Note that this bound is independent of both the length of \( \gamma \) and the dimension of \( X \).)

We now have a large supply of efficient quasimorphisms, but it is by no means clear that any of them are non-trivial. Our main task, given an element \( g \in G \), is to find a tightly nested segment \( \gamma \) such that \( \hat{\varphi}_\gamma(g) \geq 1 \). This will only be possible for suitable elements \( g \); for instance, if \( g \) is conjugate to \( g^{-1} \), then \( \text{scl}(g) = 0 \) and every homogeneous quasimorphism vanishes on \( g \).

For our main result we consider cube complexes with group actions that have properties in common with the standard actions of right-angled Artin groups on their associated CAT(0) cube complexes. These are called RAAG-like actions; see Section 7 and Definition 7.1. Our main theorem is that for such actions, the desired segments \( \gamma \) can be found for every hyperbolic element \( g \). Using Bavard Duality, we obtain:

**Theorem A.** — Let \( X \) be a CAT(0) cube complex with a RAAG-like action by \( G \). Then \( \text{scl}(g) \geq 1/24 \) for every hyperbolic element \( g \in G \).
Since the standard action of a right-angled Artin group on its associated CAT(0) cube complex is RAAG-like, with all non-trivial elements acting hyperbolically, the following corollary is immediate.

**Corollary B.** — Let $G$ be a right-angled Artin group. Then $\text{scl}(g) \geq 1/24$ for every nontrivial $g \in G$.

What is perhaps surprising about this result is that there is a uniform gap for $\text{scl}$, independent of the dimension of $X$. Note that in Theorem A we do not assume that $X$ is either finite-dimensional or locally finite; thus Corollary B applies to right-angled Artin groups defined over arbitrary simplicial graphs.

The defining properties of RAAG-like actions arose naturally while working out the arguments in this paper. It turns out, however, that RAAG-like actions are closely related to the special cube complexes of Haglund and Wise [19]. That is, if $G$ acts freely on $X$, then the action is RAAG-like if and only if the quotient complex $X/G$ is special. See Section 7 and Remark 7.4 for the precise correspondence between these notions.

**Corollary C.** — Let $G$ be the fundamental group of a special cube complex. Then $\text{scl}(g) \geq 1/24$ for every non-trivial $g \in G$.

This follows from Theorem A since the action of $G$ on the universal cover is RAAG-like, with every non-trivial element acting hyperbolically. Alternatively, it follows from Corollary B and monotonicity, since every such group embeds into a right-angled Artin group.

**Related results**

There are other gap theorems for stable commutator length in the literature, though in some cases the emphasis is on the existence of a gap, rather than its size. The first such result was Duncan and Howie's theorem [14] that every non-trivial element of a free group has stable commutator length at least 1/2. In [12] it was shown that in Baumslag–Solitar groups, stable commutator length is either zero or at least 1/12. A different result in [12] states that if $G$ acts on a tree, then $\text{scl}(g) \geq 1/12$ for every “well-aligned” element $g \in G$. There are also gap theorems for stable commutator length in hyperbolic groups [8, 17] and in mapping class groups (and their finite-index subgroups) [3], where existence of a gap is established. In these cases it is also determined which elements of the group have positive $\text{scl}$. In [8],
the size of the gap in the case of a hyperbolic group is estimated, in terms of the number of generators and the hyperbolicity constant.

In [21, Corollary 6.13], it was shown that every finitely generated right-angled Artin group $G$ embeds into the Torelli subgroup of the mapping class group of a surface. Since scl is positive on the Torelli group [3], monotonicity implies that every non-trivial element of $G$ has positive scl. However, the lower bounds obtained in this way are neither explicit nor uniform. For instance, the genus of the surface needed in [21] grows with the number of generators of $G$, and this affects the bounds arising in [3] (which go to zero as the genus grows).

There are numerous results on the existence of homogeneous quasimorphisms on groups, where the purpose is to show that the group has non-zero second bounded cohomology. Let $\tilde{Q}H(G)$ denote the space of homogeneous quasimorphisms on $G$, modulo homomorphisms. Then $\tilde{Q}H(G)$ is a subspace of $H^2_b(G; \mathbb{R})$. In [15] it was shown that $\tilde{Q}H(G)$ is infinite-dimensional for any hyperbolic group $G$. Recent results in this direction, involving both wider classes of groups and more general coefficient modules, include [20] and [2]. If $G$ is a non-abelian right-angled Artin group then $\tilde{Q}H(G)$ is infinite-dimensional (via a retraction onto a free subgroup). The quasimorphisms defined in this paper include an infinite collection that is linearly independent in $\tilde{Q}H(G)$; see Proposition 4.7. These appear to be different from the quasimorphisms one obtains via retractions.

We have mentioned that the median property of CAT(0) cube complexes is used to control the defect of our quasimorphisms. The use of medians in this context originated in [10], where they are used to define a bounded cohomology class (the median class) which has good functorial properties. This class is defined, and is non-trivial, whenever one has a non-elementary group action on a finite-dimensional CAT(0) cube complex. One consequence, among many others, is that $H^2_b(G; M)$ is non-trivial for any such group, for a suitably defined coefficient module $M$.

Our upper bound of 12 for the defect of the quasimorphisms $\hat{\phi}_\gamma$ can actually be lowered to 6 in the special case when the CAT(0) cube complex is 1–dimensional; see Remark 4.6. This statement then coincides with Theorem 6.6 of [12], and thus we obtain a new proof of the latter result.

**Methods**

The fundamental result upon which most of our arguments depend is the existence of *equivariant Euclidean embeddings*, proved in Proposition 5.4.
To state this result, we first note that every element $g \in G$ has a minimal subcomplex $M_g \subseteq X$, and if $g$ is hyperbolic then this subcomplex admits a $\langle g \rangle$–invariant product decomposition $M_g \cong M_g^{\text{ess}} \times X_g^{\text{fix}}$. The action of $g$ on $X_g^{\text{fix}}$ is trivial and every edge in $M_g^{\text{ess}}$ is on a combinatorial axis for $g$. We call $M_g^{\text{ess}}$ the essential minimal set for $g$. Furthermore, we show that $M_g^{\text{ess}}$ is always a finite-dimensional CAT(0) cube complex. However, $M_g^{\text{ess}}$ is not always a convex subcomplex of $X$. We denote by $X_g^{\text{ess}}$ its convex hull in $X$ and refer to $X_g^{\text{ess}}$ as the essential characteristic set for $g$. The subcomplex $X_g^{\text{ess}}$ is in general much more complicated than $M_g^{\text{ess}}$ and can have infinite dimension. In Section 3, we give a complete characterization of when $X_g^{\text{ess}}$ is finite-dimensional and when $X_g^{\text{ess}}$ and $M_g^{\text{ess}}$ are the same.

Proposition 5.4 states that under suitable assumptions there is a $\langle g \rangle$–equivariant embedding of $X_g^{\text{ess}}$ into $\mathbb{R}^d$, where $d = \dim X_g^{\text{ess}}$. That is, there is an embedding of cube complexes $X_g^{\text{ess}} \hookrightarrow \mathbb{R}^d$ such that the action of $\langle g \rangle$ on $X_g^{\text{ess}}$ extends to an action on $\mathbb{R}^d$ (preserving its standard cubing). Furthermore, the embedding induces a bijection between the half-spaces of $X_g^{\text{ess}}$ and those of $\mathbb{R}^d$.

It is well known that any interval in a CAT(0) cube complex admits an embedding into $\mathbb{R}^d$ for some $d$. This result is proved using Dilworth’s theorem on partially ordered sets of finite width; see [5] for details. What is new in our result is the equivariance. In order to prove it, we first state and prove an equivariant version of Dilworth’s theorem, Lemma 5.3.

An important aspect of the equivariant Euclidean embedding is that it provides a geometric framework for understanding the fine structure of the set of half-spaces of $X_g^{\text{ess}}$, considered as a partially ordered set. This set becomes identified with the set of half-spaces of $\mathbb{R}^d$, and the partial ordering from $X_g^{\text{ess}}$ is determined by the knowledge of which cubes in $\mathbb{R}^d$ are occupied by $X_g^{\text{ess}}$ (cf. Remark 6.1). Tools such as the Quadrant Lemma and the Elbow Lemma (see Section 6) can be used to retrieve information about the partial ordering. These tools become available once $X_g^{\text{ess}}$ has been embedded into $\mathbb{R}^d$.

An outline of the paper

In Section 2 we present background on several topics, including quasimorphisms and stable commutator length, CAT(0) cube complexes, and right-angled Artin groups.
In Section 3 we define the essential minimal set and the essential characteristic set, and establish their properties. We determine when they agree, and when the latter has finite dimension.

In Section 4 we define non-transverse actions. For such actions we also define the quasimorphisms $\hat{\psi}_\gamma$ and $\varphi_\gamma$ and establish the bounds on defect, using medians. We construct an infinite linearly independent set in $\mathcal{QH}(A_\Gamma)$, for any non-abelian right-angled Artin group $A_\Gamma$.

In Section 5 we prove the equivariant Dilworth theorem, and apply it to prove the existence of equivariant Euclidean embeddings of essential characteristic sets.

In Section 6 we introduce quadrants and prove two basic results, the Quadrant Lemma and the Elbow Lemma. These are the primary tools used for studying the essential characteristic set $X^\text{ess}_g$ once it has been equivariantly embedded into $\mathbb{R}^d$.

In Section 7 we discuss RAAG-like actions on CAT(0) cube complexes.

In Sections 8 and 9 we carry out the rather intricate arguments needed to show that $\hat{\varphi}_\gamma(g) \geq 1$ for the appropriate choice of $\gamma$. Essentially all of the effort in these sections is devoted to showing that $X^\text{ess}_g$ contains no $G$–translate of $\gamma$.

2. Preliminaries

In this section we establish notation and background for the rest of the paper. We start with the topics of quasimorphisms and stable commutator length. For more detail see [7]. Then we give some background on CAT(0) cube complexes, focusing on the structure of their half spaces and their median structure. More information on these topics can be found in [11, 18, 23, 24, 25]. The section concludes with a brief overview of right-angled Artin groups and properties of their associated CAT(0) cube complexes. These properties lead to the notion of RAAG-like actions, to be defined in Section 7.

Notation. — Throughout the paper we use the symbols “$\subset$” and “$\supset$” to denote strict inclusion only.

Quasimorphisms and stable commutator length

Let $G$ be any group. A map $\varphi: G \to \mathbb{R}$ is a quasimorphism on $G$ if there is a constant $D \geq 0$ such that for all $g, h \in G$,

$$|\varphi(gh) - \varphi(g) - \varphi(h)| \leq D.$$
The smallest $D$ that satisfies the inequality above is called the \textit{defect} of $\varphi$. It is immediate that a quasimorphism is a homomorphism if and only if its defect is 0.

A quasimorphism $\varphi$ is \textit{homogeneous} if $\varphi(g^n) = n\varphi(g)$ for all $g \in G$ and $n \in \mathbb{Z}$. Given any quasimorphism $\varphi$, its \textit{homogenization} $\widehat{\varphi}$ is defined by

$$
\widehat{\varphi}(g) = \lim_{n \to \infty} \frac{\varphi(g^n)}{n}.
$$

It is straightforward to check $\widehat{\varphi}$ is a homogeneous quasimorphism. Its defect can be estimated as follows:

\textbf{Lemma 2.1.} — If $\varphi$ is a quasimorphism of defect at most $D$, then its homogenization has defect at most $2D$.

Two maps $\varphi, \psi : G \to \mathbb{R}$ are uniformly close if there exists $D \geq 0$ such that $|\varphi(g) - \psi(g)| \leq D$ for all $g \in G$. It is easy to check that any map uniformly close to a quasimorphism is a quasimorphism. Further, the following statement holds:

\textbf{Lemma 2.2.} — If $\varphi$ is uniformly close to a quasimorphism $\psi$, then $\widehat{\varphi} = \widehat{\psi}$.

\textbf{Proof.} — By assumption, there exists $D \geq 0$ such that $|\varphi(g) - \psi(g)| \leq D$ for all $g \in G$. Then

$$
|\widehat{\varphi}(g) - \widehat{\psi}(g)| = \left| \lim_{n \to \infty} \frac{\varphi(g^n)}{n} - \lim_{n \to \infty} \frac{\psi(g^n)}{n} \right|
$$

$$
= \lim_{n \to \infty} \frac{|\varphi(g^n) - \psi(g^n)|}{n}
$$

$$
\leq \lim_{n \to \infty} \frac{D}{n} = 0.
\qedhere
$$

Now denote by $[G,G]$ the commutator subgroup of $G$. Given an element $g \in [G,G]$, the \textit{commutator length} $\text{cl}(g)$ of $g$ is the minimal number of commutators whose product equals $g$. The commutator length of the identity element is 0. For any $g \in [G,G]$, the \textit{stable commutator length} of $g$ is

$$
\text{scl}(g) = \lim_{n \to \infty} \frac{\text{cl}(g^n)}{n}.
$$

Note that $\text{scl}(g^n) = n\text{scl}(g)$ for all $n \in \mathbb{Z}$ and $g \in G$. This formula allows one to define scl for elements that are only virtually in $[G,G]$. By convention, $\text{scl}(g) = \infty$ if no power of $g$ lies in $[G,G]$.

The relationship between stable commutator length and quasimorphisms on $G$ is expressed by Bavard duality [1]. We state the easier direction below:
Lemma 2.3 (Easy direction of Bavard Duality). — For any $g \in [G,G]$, if $\varphi$ is a homogeneous quasimorphism on $G$ with defect at most $D$, then
\[ \text{scl}(g) \geq \frac{\varphi(g)}{2D}. \]

CAT(0) cube complexes

A cube of dimension $d$ is an isometric copy of $[0,1]^d$ with the standard Euclidean metric. A face of a cube is obtained by fixing any number of coordinates to be 0 or 1. This is naturally a cube of the appropriate dimension. A midcube is the subset of the cube obtained by fixing one of the coordinates to be $1/2$.

A cube complex $X$ is a space obtained from a collection of cubes with some faces identified via isometries. The dimension of $X$ is the dimension of a maximal dimensional cube if it exists; otherwise the dimension of $X$ is infinite. We equip $X$ with the path metric induced by the Euclidean metric on each cube. By Gromov’s link condition, $X$ is non-positively curved if and only if the link of every vertex of $X$ is a flag complex. A cube complex $X$ is CAT(0) if and only if it is non-positively curved and simply connected.

Let $X$ be a CAT(0) cube complex. By an edge path of length $n$ we will mean a sequence of vertices $x_0, \ldots, x_n$, such that adjacent vertices $x_i$ and $x_{i+1}$ are joined by an edge of $X$. If $p = x_0, \ldots, x_n$ and $q = y_0, \ldots, y_m$ are two edge paths with $x_n = y_0$, then their concatenation is the edge path $p \cdot q = x_0, \ldots, x_n, y_1, \ldots, y_m$.

We will ignore the CAT(0) metric on $X$ and consider the combinatorial metric on its vertex set, which measures distance $d(x,y)$ between two vertices $x$ and $y$ as the minimal length of an edge path joining them. An edge path from $x$ to $y$ is a geodesic if it has length $d(x,y)$. An infinite sequence of vertices in $X$ is a geodesic if every finite consecutive subsequence is a geodesic.

A hyperplane in $X$ is a connected subset whose intersection with each cube of $X$ is either empty or is a midcube. This set always divides $X$ into two disjoint components. The closure of a component is called a half-space $H$ of $X$. The closure of the other component is denoted by $\overline{H}$. We denote by $\partial H$ the boundary hyperplane of $H$ and note that $\partial H = \partial \overline{H}$.

A subcomplex $C \subseteq X$ is convex if every geodesic in $X$ between two of its vertices is contained entirely in $C$. If $Y \subseteq X$ is any subcomplex, the convex hull $C(Y)$ of $Y$ is the smallest convex subcomplex containing $Y$. 

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Equivalently, it is the largest subcomplex of $X$ that is contained in the intersection of all half-spaces containing $Y$.

For any vertices $x, y \in X$, we will denote by $C(x, y)$ the convex hull $C \{x, y\}$.

A hyperplane $\partial H$ is dual to an edge (or vice versa) if $\partial H$ intersects the edge. A half-space $H$ is dual to an edge if $\partial H$ is. A cube $C$ is dual to a hyperplane $\partial H$ if $C$ contains an edge dual to $\partial H$. The neighborhood of $\partial H$ is the union $N(\partial H)$ of all cubes dual to $\partial H$. By [18, Theorem 2.12], $N(\partial H)$ is convex. Further, there is a an involution on $N(\partial H)$ that fixes $\partial H$ pointwise and swaps the endpoints of each edge dual to $\partial H$ (in fact, $N(\partial H) \cong \partial H \times [0, 1]$).

Let $\mathcal{H}(X)$ be the collection of half-spaces of $X$. This is partially ordered by inclusion. We say two half-spaces are nested if they are linearly ordered; they are tightly nested if they are nested and there is no third half-space that lies properly between them. The map $\mathcal{H}(X) \to \mathcal{H}(X)$ sending $H$ to $\overline{H}$ is an order-reversing involution.

Two half-spaces $H, H'$ of $X$ are transverse, denoted by $H \bowtie H'$, if all four intersections

$$H \cap H', \quad H \cap \overline{H}', \quad \overline{H} \cap H, \quad \overline{H} \cap \overline{H'},$$

are non-empty. When this happens, then there is a cube $C$ in $X$ such that $\partial H \cap C$ and $\partial H' \cap C$ are different midcubes of $C$. More generally, if $H_1, \ldots, H_n$ are pairwise transverse, then there is a cube $C$ in $X$ of dimension $n$ such that $\partial H_1 \cap C, \ldots, \partial H_n \cap C$ are the $n$ midcubes of $C$.

Given two vertices $x, y \in X$, the interval between $x$ and $y$ is

$$[x, y] = \{H \in \mathcal{H} : y \in H, x \in \overline{H}\}.$$ 

Two distinct half-spaces $H, H' \in [x, y]$ are always either nested or transverse. The interval $[y, x]$ is exactly the set of half spaces $\{\overline{H} : H \in [x, y]\}$.

An oriented edge $e = (x, y)$ is an edge whose vertices $x, y$ have been designated as initial and terminal respectively. Given an edge path $x_0, \ldots, x_n$, each edge $(x_i, x_{i+1})$ receives an induced orientation with $x_i$ initial and $x_{i+1}$ terminal. For any oriented edge $e = (x, y)$, the half space dual to $e$ is the unique half-space in the interval $[x, y]$; it is dual to $e$ considered as an unoriented edge, and it contains $y$ but not $x$.

An edge path is a geodesic if and only if it crosses no hyperplane twice. Two geodesics from $x$ to $y$ determine the same set of half-spaces $[x, y]$, and every half-space $H \in [x, y]$ is dual to some edge on every geodesic from $x$ to $y$. Therefore, the combinatorial distance $d(x, y)$ is the same as the cardinality of $[x, y]$. See [25, Theorem 4.13] for more details.
Ultrafilters

Suppose $\sigma$ is a function assigning to each hyperplane $h$ in $X$ a half-space $H$ with $\partial H = h$. Then $\sigma$ is an ultrafilter if $\sigma(h)$ and $\sigma(h')$ have non-trivial intersection for every pair of hyperplanes $h, h'$. An alternative viewpoint is to simply specify the image of $\sigma$, as a subset of $\mathcal{H}(X)$ that contains exactly one half-space from each pair $\{H, H\}$, such that no two elements are disjoint. For this reason, $\sigma$ is sometimes called an ultrafilter “on $\mathcal{H}(X)$”.

For each vertex $v$ of $X$ there is a principal ultrafilter of $v$, defined by choosing $\sigma(h)$ to be the half-space with boundary $h$ containing $v$. Neighboring vertices define principal ultrafilters that differ on a single hyperplane (the one that is dual to the edge separating the vertices). Conversely, if two principal ultrafilters differ on a single hyperplane, then the corresponding vertices bound an edge, dual to that hyperplane. Since $X$ is connected, any two principal ultrafilters will differ on finitely many hyperplanes. Indeed, the number of such hyperplanes is precisely the distance between the two vertices.

The principal ultrafilters admit an intrinsic characterization: an ultrafilter $\sigma$ on $\mathcal{H}(X)$ is principal if and only if it satisfies the descending chain condition: whenever $\{h_i\}$ is a sequence of hyperplanes such that $\sigma(h_i) \supseteq \sigma(h_{i+1})$ for all $i$, the sequence is eventually constant. It follows that if an ultrafilter differs from a principal one on finitely many hyperplanes, it will also be principal.

Knowledge of the principal ultrafilters on $\mathcal{H}(X)$ completely determines $X$ as a CAT(0) cube complex. The Sageev construction is the name for the process of building a cube complex from its partially ordered set of half-spaces. The 1–skeleton of $X$ is determined from principal ultrafilters as already described, and cubes are added whenever their 1–skeleta are present [25].

More generally, let $\mathcal{H}$ be any partially ordered set with an order-reversing free involution $H \mapsto \overline{H}$, such that every interval is finite. The Sageev construction yields a CAT(0) cube complex $X(\mathcal{H})$ whose half-spaces correspond to $\mathcal{H}$ as a partially ordered set with involution [24]. It is often convenient to think of vertices of $X$ as principal ultrafilters, and to identify $X$ with the result of the Sageev construction performed on $\mathcal{H}(X)$.

Medians

Given three vertices $x, y, z \in X$, there is a unique vertex $m = m(x, y, z)$ called the median such that $[a, b] = [a, m] \cup [m, b]$ for all pairs $\{a, b\} \subset$
\{x, y, z\}. For completeness we sketch the proof, since the standard refer-

As an ultrafilter, \( m \) is defined by simply assigning to each hyperplane
the half-space which contains either two or three of the vertices \( \{x, y, z\} \).
Two such half-spaces cannot be disjoint, so this rule does indeed define an
ultrafilter. This ultrafilter is principal (i.e. it defines a vertex) because it
differs from the principal ultrafilter of \( x \) on finitely many hyperplanes: if \( H \)
is chosen by \( m \) and \( x \not\in H \), then \( y, z \in H \); hence \( H \in [x, y] \cap [x, z] \), a finite
set. Finally, given \( a, b \in \{x, y, z\} \), every half-space containing \( a \) and \( b \) also
contains \( m \), by definition. Thus, no hyperplane can separate \( m \) from \( a \) and
\( b \), and therefore \([a, b] = [a, m] \cup [m, b]\).

A vertex \( z \) lies on a geodesic edge path from \( x \) to \( y \) if and only if \( z =
m(x, z, y) \). Therefore, \( z \in C(x, y) \) if and only \( z = m(x, z, y) \).

**Segments**

By a segment \( \gamma \) of length \( n \) we will mean a chain of half-spaces \( H_1 \supset
H_2 \supset \cdots \supset H_n \) such that \( H_i \) and \( H_{i+1} \) are tightly nested for all \( i =
1, \ldots, n - 1 \). The inverse of \( \gamma \) is the segment \( \overline{\gamma} : \overline{H_n} \supset \overline{H_{n-1}} \supset \cdots \supset \overline{H_1} \).

Let \( \gamma \) and \( \gamma' \) be segments. We write \( \gamma > \gamma' \) if every half-space in \( \gamma \)
contains every half-space in \( \gamma' \). We say that \( \gamma \) and \( \gamma' \) are nested if either
\( \gamma > \gamma' \) or \( \gamma' > \gamma \).

**Definition 2.4.** — Two segments \( \gamma \) and \( \gamma' \) are said to overlap if either
\( \gamma \cap \gamma' \neq \emptyset \) or there exist \( H \in \gamma \) and \( H' \in \gamma' \) with \( H \cap H' \). Otherwise, they
are non-overlapping.

**Lemma 2.5.** — Suppose \( \gamma_1 \) and \( \gamma_2 \) are non-overlapping segments that
are contained in \([x, y]\). Then \( \gamma_1 \) and \( \gamma_2 \) are nested.

**Proof.** — As mentioned above, any two half-spaces in \([x, y]\) are either
nested or transverse. Therefore, since \( \gamma_1 \) and \( \gamma_2 \) are non-overlapping, their
union is linearly ordered by inclusion. The result follows, since each \( \gamma_i \) is a
segment.

**Right-angled Artin groups**

Let \( \Gamma \) be a simplicial graph (i.e. a simplicial complex of dimension at
most 1), with vertex set \( V(\Gamma) \) and edge set \( E(\Gamma) \). The right-angled Artin
group $A_\Gamma$ is defined to be the group with generating set $V(\Gamma)$ and relations $\{[v, w] : \{v, w\} \in E(\Gamma)\}$. That is, two generators commute if and only if they bound an edge in $\Gamma$, and there are no other defining relations.

There is a naturally defined non-positively curved cube complex which is a $K(A_\Gamma, 1)$ complex, obtained as a union of tori corresponding to complete subgraphs of $\Gamma$ (see Davis [13, 11.6], for example). The universal cover $X_\Gamma$ is a CAT(0) cube complex with a free action by $A_\Gamma$. The oriented edges of $X_\Gamma$ can be labeled by the generators of $A_\Gamma$ and their inverses in a natural way: each such edge is a lift of a loop representing that generator (or its inverse).

This labeling has the property that two oriented edges are in the same $A_\Gamma$–orbit if and only if their labels agree. Also, the oriented edges that are dual to any given half-space will always have the same label, so the label may be assigned to the half-space itself. Half-spaces in the same $A_\Gamma$–orbit will have the same label.

The half-space labels lead to several useful observations. Each 2–cell of $X_\Gamma$ is a square whose boundary is labeled by a commutator $[v, w]$, with $v \neq w$. It follows that no two half-spaces with the same label can be transverse in $X_\Gamma$. Since no label equals its inverse, $A_\Gamma$ acts without inversion on $X_\Gamma$. Some additional properties of $X_\Gamma$ related to the edge-labeling will be discussed in Section 7.

3. Automorphisms and characteristic sets

In this section we discuss automorphisms of CAT(0) cube complexes and their characteristic sets. We define the essential characteristic set and the essential minimal set of a hyperbolic automorphism, and we determine the structures of these sets. The latter set is always finite-dimensional, whereas the former is a subcomplex which plays an essential role throughout the paper. Toward the end of the section, we characterize when these sets agree (Proposition 3.17) and when the essential characteristic set is finite-dimensional (Corollary 3.19).

Basic notions

Following Haglund [18], an automorphism $g$ of a CAT(0) cube complex $X$ acts with inversion if there is a half-space $H$ such that $g(H) = \overline{H}$. When this occurs, $g$ stabilizes the hyperplane $\partial H$. For any automorphism $g$ of $X$,
the action of $g$ on the cubical subdivision of $X$ is always without inversion. Note, however, that for some of our results, we will not be free to perform this modification; see Remark 7.2.

For an automorphism $g$ of $X$, the translation distance of $g$ is $\ell_g = \min_{x \in X} d(x, gx)$, where $x$ ranges over the vertices of $X$. If $g$ and all of its powers act without inversion, we say that $g$ is hyperbolic if $\ell_g > 0$ and elliptic otherwise. Haglund showed that when $g$ is hyperbolic, there is an infinite combinatorial geodesic in $X$ that is preserved by $g$, on which $g$ acts as a translation of magnitude $\ell_g$. Any such geodesic will be called a combinatorial axis for $g$. It has a natural orientation, relative to which the translation by $g$ is in the forward direction. Note that $g$ and $g^{-1}$ have the same combinatorial axes, but they determine opposite orientations.

Haglund also showed that any two combinatorial axes for $g$ cross the same hyperplanes, in the same directions. That is, the set of half-spaces that are dual to oriented edges in any axis is independent of the choice of axis. We define the positive half-space axis of $g$:

$$A_g^+ = \left\{ H \in \mathcal{H}(X) : \begin{array}{c} H \text{ is dual to a positively oriented edge} \\
\text{in a combinatorial axis for } g \end{array} \right\}. $$

We also define the negative half-space axis $A_g^- = \{ \overline{H} : H \in A_g^+ \}$; note that $A_g^- = A_{g^{-1}}^+$. The full half-space axis is $A_g = A_g^+ \cup A_g^-$. If $L$ is a combinatorial axis for $g$, then for every $H \in A_g^+$, the intersection $L \cap H$ is a ray containing the attracting end of $L$ (since $L$ crosses $\partial H$ exactly once). Note also that $gH \neq H$ for all $H \in A_g$, for otherwise $g$ would fix the unique edge of $L$ dual to $H$, contradicting hyperbolicity of $g$.

Remark 3.1. — For any distinct half-spaces $H, H' \in A_g^+$, either $H \cap H'$, $H \subset H'$, or $H' \subset H$. The only other possibilities are that $\overline{H} \subset H$ or $\overline{H'} \subset H'$, but these imply that either $H \cap H'$ or $\overline{H} \cap \overline{H'}$ is empty. But every combinatorial axis for $g$ meets both of these sets in an infinite ray.

Remark 3.2. — For any $H \in A_g^+$ and $n > 0$, if $H$ and $g^nH$ are not transverse, then $H \supseteq g^nH$. To see this, let $L$ be any oriented combinatorial axis for $g$. Let $e = (x, y)$ be the oriented edge on $L$ dual to $H$. Then $e$ lies on a geodesic edge path from $x$ to $g^n x$. In other words, $H \in [x, g^n x]$, and so $g^n x \in H$. Since $x \not\in H$, $g^n x \notin g^n H$. It follows that $H \supseteq g^n H$ (rather than $H \subset g^n H$).

Let $G$ be a group acting on $X$ by automorphisms. We will always assume (here and for the rest of the paper) that all elements of $G$ act without inversion. Under this assumption, Haglund showed that every element $g \in G$ is either elliptic or hyperbolic.
The minimal set, the characteristic set, and their product decompositions

**Definition 3.3.** — For any $g \in G$, the minimal set of $g$ is the full subcomplex $M_g \subseteq X$ generated by the vertices of $X$ that realize the translation distance of $g$.

Since $g$ and all of its powers act without inversion, there are two types of behavior for $M_g$. If $g$ is elliptic then $M_g$ is the subcomplex of fixed points of $g$. If $g$ is hyperbolic then $M_g$ is the smallest full subcomplex containing all combinatorial axes for $g$. It is non-empty, and every vertex of $M_g$ is on a combinatorial axis, by [18, Corollary 6.2].

Next we define three more sets of half-spaces when $g \in G$ is hyperbolic:

- $S_g = \{ H \in \mathcal{H} : H$ contains every combinatorial axis of $g \}$
  
- $S_g = \{ H \in \mathcal{H} : H$ contains $M_g \}$,

- $\mathcal{A}_g = \{ H \in \mathcal{H} : H \not\in A_g$ and $H$ contains no combinatorial axis of $g \}$

- $\mathcal{T}_g = \{ H \in \mathcal{H} : H \not\in A_g$ and $\partial H$ separates two combinatorial axes of $g \}$.

Recall that the half-spaces not in $A_g$ are exactly those whose boundary hyperplanes do not cross any axis. Thus the aforementioned sets define a partition of $\mathcal{H}(X)$:

$$\mathcal{H}(X) = A_g \cup S_g \cup \mathcal{S}_g \cup T_g.$$  

**Remark 3.4.** — For any group $\Gamma$ acting on $X$, Caprace and Sageev have defined a decomposition of $\mathcal{H}(X)$ into $\Gamma$–essential, $\Gamma$–half-essential, and $\Gamma$–trivial half-spaces [9]. It can be shown that when $\Gamma = \langle g \rangle$ (with $g$ hyperbolic), these three collections of half-spaces coincide with $A_g$, $(S_g \cup \mathcal{S}_g)$, and $T_g$, respectively.

Using this perspective, some of the results below can be derived from results in [9] and [10]. Specifically, Lemma 3.7 is observed in Remark 3.4 of [9], and Lemma 3.8 can be derived from Lemma 2.6 of [10] (see also [16, Remark 2.11]).

For completeness, we include elementary proofs of these results, using the definitions of $A_g$, $S_g$, $\mathcal{S}_g$, and $T_g$ given above.

**Lemma 3.5.** — Suppose $g \in G$ is hyperbolic. If $H \in A_g$ and $K \in T_g$ then $H \cap K$.

**Proof.** — Let $L$, $L'$ be combinatorial axes of $g$ such that $L \subset K$ and $L' \subset \overline{K}$. Every axis meets both $H$ and $\overline{H}$. Thus all four intersections $K \cap H$, $K \cap \overline{H}$, $\overline{K} \cap H$, and $\overline{K} \cap \overline{H}$ are non-empty.  

\[ \square \]
Definition 3.6. — If \( g \in G \) is hyperbolic, the characteristic set of \( g \) is the convex hull of \( M_g \), denoted \( X_g \). Equivalently, \( X_g \) is the largest subcomplex of \( X \) contained in \( \bigcap_{H \in S_g} H \).

The collections of half-spaces \( A_g \) and \( T_g \) define CAT(0) cube complexes \( X_g^{\text{ess}} = X(A_g) \) and \( X_g^{\text{ell}} = X(T_g) \) by the Sageev construction, called the essential characteristic set and the elliptic factor respectively.

Lemma 3.7. — Suppose \( g \in G \) is hyperbolic. Then there is a \( \langle g \rangle \)-equivariant isomorphism of cube complexes \( X_g \cong X_g^{\text{ess}} \times X_g^{\text{ell}} \).

Proof. — First note that since \( A_g \triangleleft T_g \), there is an isomorphism \( X_g^{\text{ess}} \times X_g^{\text{ell}} \cong X(A_g \cup T_g) \), by [9, Lemma 2.5]. We shall define an embedding \( X(A_g \cup T_g) \hookrightarrow X \) and show that its image is \( X_g \).

The map is defined by extending each principal ultrafilter on \( A_g \cup T_g \) to an ultrafilter on \( \mathcal{H}(X) \) by including every half-space in \( S_g \). These half-spaces have non-trivial intersection with every half-space in \( A_g \cup T_g \), and also with each other, so this rule does indeed define an ultrafilter. Moreover, no half-space in \( S_g \) is contained in any half-space of \( A_g \cup T_g \), and \( S_g \) itself contains no descending chains: for each \( H \in S_g \), \( \partial H \) is separated from \( M_g \) by only finitely many hyperplanes. Therefore the descending chain condition is still satisfied. Thus, each vertex of \( X(A_g \cup T_g) \) is mapped to a vertex of \( X \). It is clear that adjacent vertices map to adjacent vertices, so the map is an embedding of cube complexes.

Next, the vertices of \( X_g \) are exactly the vertices whose principal ultrafilters include all half-spaces of \( S_g \). These are exactly the vertices in the image of our map, so this image is \( X_g \).

Equivariance holds because the \( \langle g \rangle \)-actions on \( X(A_g) \), \( X(T_g) \), and \( X(\mathcal{H}(X)) \) are all simultaneously induced by the action of \( \langle g \rangle \) on the half-spaces of \( X \). \( \Box \)

The next result concerns crossing of half-spaces of \( A_g \). Namely, two such half-spaces cross in \( X_g^{\text{ess}} \) if and only if they cross in \( X \):

Lemma 3.8. — Suppose \( g \in G \) is hyperbolic. If \( H, H' \in A_g \) and \( H \triangleleft H' \) in \( X \), then \( H \triangleleft H' \) in \( X_g^{\text{ess}} \). That is, there is a square \( S \subset X_g^{\text{ess}} \) containing edges \( e, e' \) that are dual to \( H \) and \( H' \) respectively.

Proof. — Recall that \( X_g^{\text{ess}} = X(A_g) \). We may embed \( X_g^{\text{ess}} \) as a convex subcomplex of \( X \) in such a way that the induced map on half-spaces \( A_g \to \mathcal{H}(X) \) is inclusion; this follows from Lemma 3.7, by choosing a vertex \( v \in X_g^{\text{ell}} \) and identifying \( X_g^{\text{ess}} \) with \( X_g^{\text{ess}} \times \{v\} \) in \( X_g \).

There is a combinatorial retraction \( X \to X_g^{\text{ess}} \) defined in terms of ultrafilters by restriction: each principal ultrafilter on \( \mathcal{H}(X) \) is sent to its
intersection with $A_g$. The resulting ultrafilter still satisfies the descending chain condition, and therefore defines a vertex in $X_g^\text{ess}$. Two adjacent vertices of $X$ will either map to adjacent vertices or to the same vertex. This map extends to cubes, and each cube maps to a cube in $X_g^\text{ess}$ by a coordinate projection. More specifically, an edge in $X$ is collapsed if and only if its dual half-spaces are not in $A_g$. It follows that if a square in $X$ is dual to two half-spaces in $A_g^+$, then its image in $X_g^\text{ess}$ is also a square, dual to the same two half-spaces. Thus, if $H, H' \in A_g^+$ are transverse in $X$, they are transverse in $X_g^\text{ess}$. □

Next we continue to examine the structure of $X_g$.

**Lemma 3.9.** — Suppose $g \in G$ is hyperbolic. Then $g$ acts as an elliptic automorphism of $X_g^\text{ell}$.

**Proof.** — If not, any axis $L$ of $g$ acting on $X_g = X_g^\text{ess} \times X_g^\text{ell}$ would project onto an axis in $X_g^\text{ell}$, and $L$ would then cross a hyperplane bounding a half-space in $T_g$. However, no axis of $g$ crosses such a hyperplane. □

Accordingly, there is a non-empty subcomplex $X_g^\text{fix} \subseteq X_g^\text{ell}$ consisting of the fixed points of the $\langle g \rangle$–action on $X_g^\text{ell}$. It is a subcomplex because $\langle g \rangle$ acts without inversion.

**Lemma 3.10.** — Suppose $g \in G$ is hyperbolic. Then there is a $\langle g \rangle$–invariant subcomplex $M_g^\text{ess} \subseteq X_g^\text{ess}$ such that $M_g = M_g^\text{ess} \times X_g^\text{fix}$ under the identification of $X_g$ with $X_g^\text{ess} \times X_g^\text{ell}$.

The subcomplex $M_g^\text{ess}$ is called the essential minimal set for $g$.

**Proof.** — If $x$ is a vertex of $M_g$ then no half-space of $T_g$ separates $x$ from $gx$, since $x$ and $gx$ are on a combinatorial axis. Thus the principal ultrafilters at $x$ and at $gx$ agree on half-spaces in $T_g$. That is, $g$ fixes the second coordinate of $x$ in $X_g^\text{ess} \times X_g^\text{ell}$. Therefore $M_g \subseteq X_g^\text{ess} \times X_g^\text{fix}$.

Let $M_g^\text{ess}$ be the projection of $M_g$ onto the first factor of $X_g^\text{ess} \times X_g^\text{ell}$, so $M_g \subseteq M_g^\text{ess} \times X_g^\text{fix}$. Since $\langle g \rangle$ acts trivially on $X_g^\text{fix}$, any two vertices of $M_g^\text{ess} \times X_g^\text{fix}$ with the same first coordinate are moved the same distance by $g$. It follows that every vertex of $M_g^\text{ess} \times X_g^\text{fix}$ is moved distance $\ell_g$, and hence is in $M_g$. Since $M_g$ is the full subcomplex spanned by its vertices, we have $M_g = M_g^\text{ess} \times X_g^\text{fix}$. Further, $\langle g \rangle$–invariance of $M_g^\text{ess}$ is clear, because both $M_g$ and its product structure are $\langle g \rangle$–invariant. □

**Lemma 3.11.** — Suppose $g \in G$ is hyperbolic. Let $e$ be an edge of $M_g$ which projects to an edge in the factor $M_g^\text{ess}$. Then $e$ is on a combinatorial axis of $g$. ANNALES DE L’INSTITUT FOURIER
Proof. — We prove the contrapositive. Let $e = (x, y)$ where $x$ and $y$ are vertices of $M_g$. If $e$ is not on any combinatorial axis, then $y$ is not on any geodesic from $x$ to $gx$, so $y \not= m(x, y, gx)$. There must be a half-space containing $y$ but not $x$ or $gx$. The half-space $H$ dual to $e$ is the only possibility, since $[x, y] = \{H\}$.

Similarly, $x$ is not on any geodesic from $y$ to $gy$, so there must be a half-space containing $x$ but not $y$ or $gy$. This can only be $H$, since $[y, x] = \{\overline{H}\}$.

Thus $\partial H$ separates $gx$ from $gy$, and hence is dual to $ge$; therefore $g\partial H = \partial H$. Since $g$ is not an inversion, we have that $gH = H$. Thus $H \not\in A_g$ and $e$ does not project to an edge in $M^\text{ess}_g$. \qed

Relationship between $X^\text{ess}_g$ and $M^\text{ess}_g$

The convex hull of $M^\text{ess}_g \subseteq X^\text{ess}_g$ is $X^\text{ess}_g$. To see this, note that every edge of $M^\text{ess}_g$ is dual to a half-space of $X^\text{ess}_g$, by Lemma 3.11; and conversely, every half-space in $A^+_g$ is dual to an edge in an axis, and hence to an edge in $M^\text{ess}_g$. Hence no half-space of $X^\text{ess}_g$ contains $M^\text{ess}_g$, and therefore $\mathcal{C}(M^\text{ess}_g)$ is the intersection of the empty set of half-spaces of $X^\text{ess}_g$.

In this section, we will establish the basic structure of $M^\text{ess}_g$ and address when $M^\text{ess}_g$ and $X^\text{ess}_g$ are the same.

**Definition 3.12.** — Let $C$ be any cube in $X^\text{ess}_g$ and let $A$ be the set of elements in $A^+_g$ dual to the edges of $C$. Let $x, y$ be the two vertices of $C$ such that $A = [x, y]$. We will call $x$ the minimal vertex of $C$ and $y$ the maximal vertex of $C$.

**Lemma 3.13.** — Let $C \times \{v\}$ be a cube in $M^\text{ess}_g \times \{v\} \subseteq M^\text{ess}_g \times X^\text{fix}_g$ with minimal and maximal vertices $x$ and $y$. Then $[x, y] \subseteq [x, gx]$. Thus, $y$ lies on some combinatorial axis of $g$ containing $x$. This axis lies inside $M^\text{ess}_g \times \{v\}$.

Proof. — Let $e = (x, z)$ be any oriented edge in $C \times \{v\}$ with initial vertex $x$, and let $H \in [x, y]$ be the half-space dual to $e$. Since $C \subseteq M^\text{ess}_g$, the edge $e$ lies on a combinatorial axis of $g$. In particular, the vertex $z$ lies on a geodesic edge path from $x$ to $gx$. Since this geodesic can cross $\partial H$ only once, $gx \in H$. In other words, $H \in [x, gx]$. This is true for every $H \in [x, y]$, so $[x, y] \subseteq [x, gx]$. For the last conclusion, let $\alpha$ be the concatenation of geodesic edge paths from $x$ to $y$ and from $y$ to $gx$. Then $\alpha$ does not cross any hyperplane twice, since such a hyperplane would separate $y$ from $x$ and $gx$. The concatenation of $\alpha$ and its $g$–translates is a combinatorial axis.
containing $x$ and $y$. The axis lies in $M^\text{ess}_g \times \{v\}$ by $\langle g \rangle$–invariance of the product decomposition $M^\text{ess}_g \times X^\text{fix}_g$.

We now show that $M^\text{ess}_g$ is always finite-dimensional.

**Lemma 3.14.** — Suppose $g \in G$ is hyperbolic. Then $M^\text{ess}_g$ is finite-dimensional, with dimension bounded by the translation distance $\ell_g$ of $g$.

**Proof.** — Recall that the distance $d(x, y)$ between two vertices is the same as the cardinality of $[x, y]$. Thus, for any $x \in M^\text{ess}_g$, the cardinality of $[x, gx]$ is the same as the translation distance $\ell_g$. Let $C$ be any cube in $M^\text{ess}_g$, let $v$ be any vertex of $X^\text{fix}_g$, and let $x$ and $y$ be the minimal and maximal vertices of $C \times \{v\}$ in $M^\text{ess}_g \times X^\text{fix}_g$. The dimension of $C$ is the same as the cardinality of $[x, y]$. By Lemma 3.13, we always have $[x, y] \subseteq [x, gx]$, so the dimension of $C$ is bounded by $\ell_g$. This is true for all $C$ in $M^\text{ess}_g$, whence the result. □

Our goal now is to relate $M^\text{ess}_g$ and $X^\text{ess}_g$. It turns out that $X^\text{ess}_g$ may have infinite dimension. An easy example showing that $M^\text{ess}_g$ and $X^\text{ess}_g$ can have different dimensions is the glide reflection in $\mathbb{R}^2$ defined by $$g(x, y) = (y + 1, x).$$ Then $g$ has translation length 1, so $M^\text{ess}_g$ is 1–dimensional by Lemma 3.14, but $X^\text{ess}_g = \mathbb{R}^2$. See Figure 3.1.

![Figure 3.1. A glide reflection $g$ with a unique combinatorial axis. We have $\dim(M^\text{ess}_g) = 1$ and $\dim(X^\text{ess}_g) = 2$.](image)

This example can be promoted to one in which $X^\text{ess}_g$ has infinite dimension. Consider $\mathbb{R}^\mathbb{Z}$ with its standard integer cubing. Fix the origin $o = (0, 0, \ldots)$ and consider the subcomplex $X \subset \mathbb{R}^\mathbb{Z}$ generated by the
vertices in $\mathbb{R}^Z$ having at most finitely many non-zero coordinates. Then $X$ is an infinite-dimensional CAT(0) cube complex. Given $x \in X$, let $x_i$ denote its $i$–th coordinate. Let $g: X \to X$ be defined by $g(x)_0 = x_1 + 1$ and $g(x)_j = x_{j+1}$ for all other $j$. Again, $g$ has translation length 1, and $M^\text{ess}_g$ is 1–dimensional, consisting of a single combinatorial axis with vertices $\{g^n(o)\}$.

Letting $H = [o, go]$, the set of half-spaces $\{H, gH, \ldots, g^{d-1}H\}$ are pairwise transverse, and the $d$–dimensional cube $C$ they cross in is contained in $M^\text{ess}_g$. In particular, since $\ell_g = d$, we see that $M^\text{ess}_g$ has dimension exactly $d$. Now $X^\text{ess}_g$ is infinite-dimensional, since $M^\text{ess}_g \subset X^\text{ess}_g = X^\text{ess}_g$ for all $d > 0$. Note that in this example, $g$ has a combinatorial axis in $X$, but it has no CAT(0) axis; see [4, Example II.8.28].

The above discussion leads to the next definition.

**Definition 3.15.** — If $g \in G$ is hyperbolic, we say that $\langle g \rangle$ acts non-transversely on $X^\text{ess}_g$ if, for every $H \in A^+_g$, $H$ and $gH$ are not transverse in $X^\text{ess}_g$. Note that this occurs if and only if $H$ and $gH$ are not transverse in $X$, by Lemma 3.8.

Note that while the inclusion $M^\text{ess}_g \hookrightarrow X^\text{ess}_g$ induces a bijection on their sets of half-spaces, the partial orderings induced by inclusion on these two sets may be very different; equality holds if and only if $M^\text{ess}_g = X^\text{ess}_g$. In the following, we will establish some criteria for a square in $X^\text{ess}_g$ to not be in $M^\text{ess}_g$.

**Lemma 3.16.** — Suppose $g \in G$ is hyperbolic. Then:

1. If $H$ and $gH$ are transverse in $X^\text{ess}_g$, then any square in which they cross cannot be contained in $M^\text{ess}_g$.
2. Let $e$ and $e'$ be edges in $M^\text{ess}_g$ with dual half-spaces $H, H' \in A^+_g$. If $e$ and $e'$ bound a square in $X^\text{ess}_g$ which is not contained in $M^\text{ess}_g$, then either $gH = H'$ or $gH' = H$.

**Proof.** — Let $S$ be a square in $X^\text{ess}_g$ in which $H$ and $gH$ cross. Let $x$ be the minimal vertex of $S$. If $S$ lies in $M^\text{ess}_g$, then by Lemma 3.13, $H$ and $gH$ are in $[x, gx]$, which is a contradiction. This shows (1).

For (2), let $S$ be the square in $X^\text{ess}_g$ bounded by $e$ and $e'$. Let $x$ and $y$ be respectively the minimal and maximal vertices of $S$. Let $z$ be the vertex at which $e$ and $e'$ are incident. We claim that $z$ is distinct from $x$ and $y$. Since the union of $e$ and $e'$ contains three corners of $S$, exactly one corner of $S$, the one opposite $z$, is not contained in $M^\text{ess}_g$. If $z = x$, then $y$ must be the corner not in $M^\text{ess}_g$. But in this case, both half-spaces $H$ and $H'$ are contained in $[x, gx]$, by Lemma 3.11, so $y = m(x, y, gx)$. This means that $y$ lies on a
combinatorial axis for \( g \), so \( y \) is in \( M^\text{ess}_g \), a contradiction. Similarly, if \( z = y \), then \( x = m(g^{-1}y, x, y) \), so \( x \in M^\text{ess}_g \), again a contradiction. Therefore \( x, y, \) and \( z \) are distinct and lie in \( M^\text{ess}_g \). Now, without loss of generality, assume that \( [x, z] = H \) and \( [z, y] = H' \). Note that \( z = m(x, z, gx) \) and \( y = m(y, y, ggz) \). Since \( S \) is not contained in \( M^\text{ess}_g \), \( H' \notin [x, gx] \). On the other hand, \( H' \in [z, ggz] \). Since \( [z, ggz] = [z, gx] \cup [gx, ggz] \), we must have \( H' = [gx, ggz] = gH \).

\[\]

**Proposition 3.17.** — Suppose \( g \in G \) is hyperbolic. Then \( M^\text{ess}_g = X^\text{ess}_g \) if and only if \( \langle g \rangle \) acts non-transversely on \( X^\text{ess}_g \).

\[\]

**Proof.** — If \( H \cap gH \) for some \( H \in A^+_g \), then, by Lemma 3.16(1), any square in \( X^\text{ess}_g \) in which they cross cannot lie in \( M^\text{ess}_g \). Therefore, \( M^\text{ess}_g = X^\text{ess}_g \) implies that \( \langle g \rangle \) acts non-transversely on \( X^\text{ess}_g \).

Now suppose \( \langle g \rangle \) acts non-transversely on \( X^\text{ess}_g \). We claim that for any edge \( e = (x, y) \) in \( X^\text{ess}_g \), if \( x \in M^\text{ess}_g \) then \( y \in M^\text{ess}_g \). To see this, let \( H = [x, y] \). Replacing \( g \) by \( g^{-1} \) if necessary, we may assume that \( H \in A^+_g \). If \( y \notin M^\text{ess}_g \), then \( y \neq m(x, y, gx) \). In particular, \( H \notin [x, gx] \). But \( H \) must be contained in \( [g^n x, g^{n+1} x] \) for some \( n \in \mathbb{Z} \), and for this \( n \) we have \( g^{-n} H \in [x, gx] \). Note that \( n > 0 \), since \( x \notin H \). Because \( \langle g \rangle \) acts non-transversely, \( g^{-n} H \) and \( H \) cannot be transverse, and so \( g^{-n} H \supset H \). Since \( x \notin g^{-n} H \) and \( H \) is the only half space separating \( x \) and \( y \), we must have \( y \notin g^{-n} H \). But this contradicts the fact that \( y \in H \). This finishes the proof of the claim.

To finish the argument, it suffices to observe that the 1-skeleton of \( X^\text{ess}_g \) is connected, and therefore every vertex of \( X^\text{ess}_g \) is in \( M^\text{ess}_g \). 

**Remark 3.18.** — If \( \langle g \rangle \) acts non-transversely on \( X^\text{ess}_g \), then \( M^\text{ess}_{g^n} = M^\text{ess}_g \) for all \( n \geq 1 \), because \( X^\text{ess}_{g^n} = X^\text{ess}_g \). The latter equality holds because any axis for \( g \) is an axis for \( g^n \), and therefore \( A_{g^n} = A_g \).

**Corollary 3.19.** — Suppose \( g \in G \) is hyperbolic. The following statements are equivalent.

1. There is an integer \( k > 0 \) such that \( \langle g^k \rangle \) acts non-transversely on \( X^\text{ess}_g \).
2. \( X^\text{ess}_g = M^\text{ess}_{g^k} \) for some \( k > 0 \).
3. \( X^\text{ess}_g \) is finite-dimensional.

**Proof.** — First we show that (1) \(\implies\) (2). Suppose that \( g^k \) acts non-transversely on \( X^\text{ess}_g \). Since \( X^\text{ess}_g = X^\text{ess}_{g^k} \), \( g^k \) also acts non-transversely on \( X^\text{ess}_{g^k} \). By Proposition 3.17, \( M^\text{ess}_{g^k} = X^\text{ess}_{g^k} \).

The implication (2) \(\implies\) (3) follows from Lemma 3.14.
Now we show that \((3) \implies (1)\). Suppose \(X_g^{\text{ess}}\) has dimension \(d\). For every \(H \in A_g^+\), we claim that \(H \supset g^n H\) for some \(n\) satisfying \(0 < n \leq d\). Since \(X_g^{\text{ess}}\) has dimension \(d\), the half-spaces
\[
H, gH, g^2H, \ldots, g^dH
\]
cannot all be pairwise transverse. Thus there exist \(i, j\) with \(0 \leq i < j \leq d\) such that \(g^i H \supset g^j H\), or equivalently, \(H \supset g^{j-i} H\). Finally, taking \(k = d!\), we have that \(n \mid k\) whenever \(0 < n \leq d\), and therefore \(H \supset g^k H\) for all \(H \in A_g^+\). Thus \((g^k)\) acts non-transversely on \(X_g^{\text{ess}}\). \(\square\)

Even though \(M_g^{\text{ess}}\) is not always a convex subspace of \(X\), it is still always CAT(0), which we show next. The proof will make use of Lemma 3.16(2).

**Proposition 3.20.** Suppose \(g \in G\) is hyperbolic. Then the cube complex \(M_g^{\text{ess}}\) is CAT(0).

**Proof.** Denote by \(\mathcal{H}\) the set of half-spaces \(A_g\) with partial order induced by \(M_g^{\text{ess}}\). That is: \(H, H' \in \mathcal{H}\) are incomparable (or transverse) if and only if there is a square in \(M_g^{\text{ess}}\) in which they cross, and \(H \supset H'\) if and only if \(H \cap M_g^{\text{ess}} \supset H' \cap M_g^{\text{ess}}\). Apply the Sageev construction to \(\mathcal{H}\) to obtain a CAT(0) cube complex \(X(\mathcal{H})\). There is a natural injective map \(f: M_g^{\text{ess}} \to X(\mathcal{H})\) defined by sending every vertex in \(M_g^{\text{ess}}\) to its associated principal ultrafilter on \(\mathcal{H}\). This map identifies \(\mathcal{H}\) with the set of half-spaces of \(X(\mathcal{H})\). Let \(Y\) be the image of \(M_g^{\text{ess}}\). We now proceed to show that \(Y = X(\mathcal{H})\), which will imply that \(M_g^{\text{ess}}\) is CAT(0).

We claim that for any edge \(e = (y, y')\) in \(X(\mathcal{H})\), if \(y \in Y\) then \(y' \in Y\). The result follows, since the 1–skeleton of \(X(\mathcal{H})\) is connected. To prove the claim, let \(H \in \mathcal{H}\) be the half-space dual to \(e\). Replacing \(g\) by \(g^{-1}\) if necessary, we may assume that \(H \in \mathcal{H}^+\). Let \(x \in M_g^{\text{ess}}\) be such that \(f(x) = y\). Since \(H\) must appear in every axis of \(g\) passing through \(x\) and \(x \notin H\), there exists a geodesic path \(x = x_0, \ldots, x_{n+1} = x'\) in \(M_g^{\text{ess}}\) such that \(H = [x_n, x_{n+1}]\). If \(n = 0\), then \(f(x_1) = y'\) and we are done. Now suppose that \(n > 0\). Let \(H_i = [x_i, x_{i+1}]\) for each \(i\). If \(H_i \supset H\) for some \(i < n\), then since \(x \notin H\), \(f(x) = y \notin H_i\). But \(y' \in H_i\), and hence \(y' \notin H_i\), but this is impossible as \(y\) and \(y'\) are separated by exactly one half-space \(H\). Thus \(H_i \cap H\) for \(i = 0, \ldots, n - 1\). We claim now that for each \(i\), there is a square \(S_i\) in which \(H_i\) and \(H\) cross, and \(x_i\) is the minimal vertex of \(S_i\). Let \(e_i = (x_i, x_{i+1})\) for each \(i\). By assumption, \(e_{n-1}\) and \(e_n\) are dual to two transverse half-space \(H_{n-1}\) and \(H_n\). If they do not bound a square in \(M_g^{\text{ess}}\), then by Lemma 3.16, \(gH_{n-1} = H_n\) and there is no square in \(M_g^{\text{ess}}\) in which \(H_{n-1}\) and \(H_n\) can cross. This contradicts that \(H_{n-1}\) and \(H_n\) are transverse in \(M_g^{\text{ess}}\), so \(e_{n-1}\) and \(e_n\) must bound a square \(S_{n-1}\) in \(M_g^{\text{ess}}\).
By the same reasoning, the edge $e'$ parallel to $e_n$ in $S_{n-1}$ and $e_{n-2}$ bound $S_{n-2}$, in which $x_{n-2}$ is the minimal vertex. Repeating in this way, we find the square $S_0$, with minimal vertex $x_0$ and in which $H_0$ and $H$ cross. In $S_0$ there is an edge $(x_0, v)$ dual to $H$, and $f(v) = y'$. □

The following proposition will be used in the next section.

**Proposition 3.21.** — Suppose $g \in G$ is hyperbolic, and that $\langle g \rangle$ acts non-transversely on $X^\text{ess}_g$. Let $C$ be a cube in $X^\text{ess}_g$ of maximal dimension, $A$ the set of half-spaces in $A^+_g$ dual to $C$, and $o$ the minimal vertex of $C$. Then the following statements hold.

1. For every pair of half-spaces $H, H' \in A$, either $H \owns gH'$ or $H \supset gH'$.
2. $K \in [o, go]$ if and only if there exist $H, H' \in A$ such that $H \supset K \supset gH'$.
3. For every $K \in A^+_g$, there exist $r, s \in \mathbb{Z}$ and $H, H' \in A$ such that $g^rH \supset K \supset g^sH'$.

**Proof.** — Since $X^\text{ess}_g = M^\text{ess}_g$ (by Proposition 3.17), there is an axis $L$ for $g$ containing $o$. It follows that $o \not\in gH'$, because $o \not\in H'$ (the unique edge $e$ in $L$ dual to $H'$ separates $o$ from $ge$). Let $o^+$ be the maximal vertex of $C$. By Lemma 3.13, $o^+$ is on a geodesic from $o$ to $go$. Suppose $H$ and $gH'$ are not transverse. Then $o^+ \not\in gH'$, because all half-spaces in $[o, o^+]$ are transverse. Now $o^+ \in H - gH'$, showing that $H \nsubseteq gH'$. Thus $H \supset gH'$ and (1) holds.

For statement (2), note that $A \subseteq [o, go]$, again by Lemma 3.13. If $H \supset K \supset gH'$ for some $H, H' \in A$, then $o \not\in K$ and $go \in K$, and therefore $K \in [o, go]$. On the other hand, both $C$ and $gC$ have maximal dimension, so for every $K \in [o, go]$, there exist $H, H' \in A$ such that $H$ and $gH'$ are comparable (or equal) to $K$. Because $A \subseteq [o, go]$ and $gA \cap [o, go] = \emptyset$, we must have $H \supset K \supset gH'$.

Finally, for (3), we observe that

$$A^+_g = \bigcup_{n \in \mathbb{Z}} [g^n o, g^{n+1} o].$$

Suppose $K \in [g^n o, g^{n+1} o]$. Applying (2) to $g^{-n} K$, there exist $H, H' \in A$ such that $g^n H \supset K \supset g^{n+1} H'$. Since $\langle g \rangle$ acts non-transversely, we also have $g^{n-1} H \supset g^n H$. The conclusion follows. □
4. Non-transverse actions and efficient quasimorphisms

Here we give a general construction of a large family of quasimorphisms on groups acting on CAT(0) cube complexes. For the construction to succeed (i.e. to achieve bounded defect) we require one assumption.

**Definition 4.1.** — Let $X$ be a CAT(0) cube complex with an action by $G$. The action is non-transverse if it is without inversion and also satisfies: there do not exist $H \in \mathcal{H}(X)$, $g \in G$ with $H \pitchfork gH$.

This definition agrees with the earlier Definition 3.15 in the case of $\langle g \rangle$ acting on $X^\text{ess}_g$. First, such an action is always without inversion. Also, if $H \in A_g$ and $H$ and $gH$ are not transverse, then $H$ and $g^kH$ are not transverse for any $k$.

Let $X$ be a CAT(0) cube complex with a non-transverse action by $G$. Let $\gamma$ be a segment in $X$, and consider the set $G\gamma = \{g\gamma : g \in G\}$; elements of this set are called copies of $\gamma$. Define the map $c_\gamma : X^2 \to \mathbb{Z}$ which assigns to each pair $(x,y)$ the maximal cardinality of a pairwise non-overlapping collection of copies of $\gamma$ in $[x,y]$.

Define

$$\omega_\gamma(x,y) = c_\gamma(x,y) - c_\gamma(y,x).$$

Observe that $\omega_\gamma(y,x) = -\omega_\gamma(x,y)$ and $\omega_\gamma(gx,gy) = \omega_\gamma(x,y)$ for all $g \in G$.

**Lemma 4.2.** — If the action is non-transverse, then for all $x,y,z \in X$ with $y = m(x,y,z)$, there is a bound

$$|\omega_\gamma(x,z) - \omega_\gamma(x,y) - \omega_\gamma(y,z)| \leq 2.$$

**Proof.** — By definition,

$$|\omega_\gamma(x,z) - \omega_\gamma(x,y) - \omega_\gamma(y,z)| = \left| \left( c_\gamma(x,z) - c_\gamma(x,y) - c_\gamma(y,z) \right) - \left( c_\gamma^-(x,z) - c_\gamma^-(x,y) - c_\gamma^-(y,z) \right) \right|.$$

It will suffice to show that

$$c_\gamma(x,z) \leq c_\gamma(x,y) + c_\gamma(y,z) + 1 \quad (4.2)$$

and

$$c_\gamma(x,y) + c_\gamma(y,z) \leq c_\gamma(x,z) + 1, \quad (4.3)$$

together with analogous statements for $\gamma$. 
Let \( \{g_1\gamma, \ldots, g_n\gamma\} \) be a collection of non-overlapping copies of \( \gamma \) in \([x, z]\) of cardinality \( n = c_{\gamma}(x, z) \). By Lemma 2.5 these copies are pairwise nested, and hence up to re-indexing we can assume that

\[
(4.4) \quad g_1\gamma > \cdots > g_n\gamma.
\]

If \( g_k\gamma \notin [x, y] \cup [y, z] \) for some \( k \), then \( y \) separates two half-spaces in \( g_k\gamma \). It follows from (4.4) that \( g_i\gamma \subseteq [x, y] \) for every \( i < k \) and \( g_i\gamma \subseteq [y, z] \) for every \( i > k \). Thus \( c_{\gamma}(x, y) + c_{\gamma}(y, z) \geq n - 1 \), proving (4.2).

Now let \( k = c_{\gamma}(x, y) \) and \( \ell = c_{\gamma}(y, z) \). Let \( A = \{g_1\gamma, \ldots, g_k\gamma\} \) be a non-overlapping collection of copies of \( \gamma \) in \([x, y]\) and \( B = \{g_{k+1}\gamma, \ldots, g_{k+\ell}\gamma\} \) a non-overlapping collection of copies in \([y, z]\). As above, by Lemma 2.5, we may re-index \( A \) and \( B \) to arrange that

\[
(4.3) \quad g_1\gamma > \cdots > g_k\gamma \quad \text{and} \quad g_{k+1}\gamma > \cdots > g_{k+\ell}\gamma.
\]

We claim that \( g_i\gamma \) and \( g_j\gamma \) (with \( i < j \)) cannot overlap unless \( i = k \) and \( j = k+1 \). Discarding \( g_k\gamma \), then obtain a non-overlapping collection in \([x, z]\) of cardinality \( k + \ell - 1 \), proving (4.3).

To prove the claim, suppose that \( g_i\gamma \in A \) and \( g_j\gamma \in B \) overlap. Then there are half-spaces \( H, H' \in \gamma \) such that \( g_iH \cap g_jH' \in X \). If \( i < k \) then \( g_kH' \cap g_jH' \), because \( g_iH \supset g_kH' \) and \( y \in g_kH' - g_jH' \). However, this contradicts the assumption of a non-transverse action. Hence \( i = k \).

Similarly, if \( j > k + 1 \) then \( g_kH \cap g_{k+1}H \) because \( g_{k+1}H \supset g_jH' \) and \( y \in g_kH - g_{k+1}H \). Again, this contradicts non-transversality of the action, and therefore \( j = k + 1 \). This proves the claim, and equation (4.3). Finally, note that the analogues of (4.2) and (4.3) for \( \overline{\gamma} \) are entirely similar. \( \square \)

Next define \( \delta\omega_{\gamma}(x, y, z) = \omega_{\gamma}(x, y) + \omega_{\gamma}(y, z) + \omega_{\gamma}(z, x) \).

**Lemma 4.3.** — *If the action is non-transverse, then for all \( x, y, z \in X \) there is a bound \(|\delta\omega_{\gamma}(x, y, z)| \leq 6 \).*

**Proof.** — Let \( m = m(x, y, z) \). By the previous lemma,

\[
|\omega_{\gamma}(a, b) - \omega_{\gamma}(a, m) - \omega_{\gamma}(m, b)| \leq 2,
\]
where \(a, b \in \{x, y, z\}\) are distinct. Then
\[
|\delta \omega_\gamma(x, y, z)| = |\omega_\gamma(x, y) + \omega_\gamma(y, z) + \omega_\gamma(z, x) \\
+ \omega_\gamma(x, m) - \omega_\gamma(x, m) + \omega_\gamma(y, m) \\
- \omega_\gamma(y, m) + \omega_\gamma(z, m) - \omega_\gamma(z, m)|
\]
\[
\leq |\omega_\gamma(x, y) - \omega_\gamma(x, m) - \omega_\gamma(m, y)| \\
+ |\omega_\gamma(y, z) - \omega_\gamma(y, m) - \omega_\gamma(m, z)| \\
+ |\omega_\gamma(z, x) - \omega_\gamma(z, m) - \omega_\gamma(m, x)|
\]
\[
\leq 6. \quad \Box
\]

At this point we are ready to define quasimorphisms associated to \(\gamma\). We will define two functions, \(\psi_\gamma\) and \(\phi_\gamma\), which produce the same homogeneous quasimorphism \(\hat{\psi}_\gamma = \hat{\phi}_\gamma\). The second function \(\phi_\gamma\) has the definition we want to use, but \(\psi_\gamma\) is needed to establish the bound on defect.

Fix a base vertex \(x_O \in X\) and define \(\psi_\gamma : G \to \mathbb{R}\) by
\[
(4.5) \quad \psi_\gamma(g) = \omega_\gamma(x_O, gx_O).
\]

Next, for each \(g \in G\) choose a vertex \(x_g \in X_g\). Define \(\phi_\gamma : G \to \mathbb{R}\) by
\[
(4.6) \quad \phi_\gamma(g) = \omega_\gamma(x_g, gx_g).
\]

**Lemma 4.4.** — If the action is non-transverse, then \(\psi_\gamma\) is a quasimorphism of defect at most 6.

**Proof.** — For any \(g_1, g_2 \in G\) we have
\[
|\psi_\gamma(g_1 g_2) - \psi_\gamma(g_1) - \psi_\gamma(g_2)|
\]
\[
= |\omega_\gamma(x_O, g_1 g_2 x_O) - \omega_\gamma(x_O, g_1 x_O) - \omega_\gamma(x_O, g_2 x_O)| \\
= |\omega_\gamma(x_O, g_1 g_2 x_O) + \omega_\gamma(g_2 x_O, g_1 x_O) + \omega_\gamma(g_2 x_O, x_O)| \\
= |\omega_\gamma(x_O, g_1 g_2 x_O) + \omega_\gamma(g_1 x_O, x_O) + \omega_\gamma(g_1 g_2 x_O, g_1 x_O)| \\
= |\delta \omega_\gamma(x_O, g_1 g_2 x_O, g_1 x_O)|
\]
\[
\leq 6,
\]
by Lemma 4.3. \(\Box\)

**Lemma 4.5.** — If the action is non-transverse, then \(\psi_\gamma - \phi_\gamma\) is uniformly bounded. Hence \(\phi_\gamma\) is a quasimorphism, \(\hat{\phi}_\gamma = \hat{\psi}_\gamma\), and \(\phi_\gamma\) has defect at most 12.
Proof. — For any \( g \in G \) we have

\[
\begin{align*}
|\psi_\gamma(g) - \varphi_\gamma(g)| &= |\omega_\gamma(x_O, gx_O, x_g) - \omega_\gamma(x_O, g x_O, x_g) + \omega_\gamma(g x_O, x_g) - \omega_\gamma(g x_O, x_g)| \\
&\leq |\omega_\gamma(x_O, gx_O) + \omega_\gamma(g x_O, x_g)| \\
&\leq |\omega_\gamma(x_O, gx_O) + \omega_\gamma(g x_O, x_g)| + |\delta_\omega_\gamma(g x_O, x_g)| \\
&\leq 12,
\end{align*}
\]

by Lemma 4.3. This shows that \( \psi_\gamma - \varphi_\gamma \) is uniformly bounded. The other conclusions follow immediately from Lemma 2.2 and Lemma 2.1. \( \square \)

Note that the equality \( \hat{\varphi}_\gamma = \hat{\psi}_\gamma \) also implies that this quasimorphism is independent of the choices of basepoints used to define \( \varphi_\gamma \) and \( \psi_\gamma \).

Remark 4.6. — The bounds in the preceding lemmas can be improved by a factor of 2 in the special case where \( X \) is a 1-dimensional CAT(0) cube complex (that is, a simplicial tree). In this case, half-spaces are never transverse, so two segments overlap if and only if they have non-empty intersection. We obtain an improvement in equation (4.3), which becomes instead

\[
(4.3')
\]

since there is no need to discard \( g_k \gamma \) from the collection of segments in \([x, z]\). This leads to the bounds

\[
|\omega_\gamma(x, z) - \omega_\gamma(x, y) - \omega_\gamma(y, z)| \leq 1
\]

in Lemma 4.2, \( |\delta_\omega_\gamma(x, y, z)| \leq 3 \) in Lemma 4.3, and a defect of at most 6 in Lemma 4.5. Thus we have a new proof of Theorem 6.6 of [12], which is the statement that these quasimorphisms have defect at most 6.

At this point, one could enhance Theorem A to say that \( \text{scl}(g) \geq 1/12 \) when \( X \) is a tree, but this already follows from Theorem 6.9 of [12].

Bounded cohomology of right-angled Artin groups

Recall that for any group \( G \), we denote by \( \widetilde{QH}(G) \) the space of homogeneous quasimorphisms on \( G \), modulo homomorphisms. It is a subspace of the second bounded cohomology \( H^2_b(G; \mathbb{R}) \).
If $G$ is a non-abelian right-angled Artin group, then there is a retraction onto a non-abelian free subgroup $H$, which induces injections $H^2_b(H;\mathbb{R}) \hookrightarrow H^2_b(G;\mathbb{R})$ and $\widetilde{QH}(H) \hookrightarrow \widetilde{QH}(G)$. Therefore the spaces $H^2_b(G;\mathbb{R})$ and $\widetilde{QH}(G)$ are infinite-dimensional (we thank the referee for suggesting this viewpoint). The next result provides another way of seeing this, using the quasimorphisms $\hat{\varphi}_\gamma$. We note that the quasimorphisms obtained below appear to be quite different from those arising via the retraction to $H$, even though their restrictions to $H$ agree.

**Proposition 4.7.** — Let $G = A_\Gamma$ be a non-abelian right-angled Artin group, and $X$ the natural cube complex on which $G$ acts. Then there is an infinite family $\{\gamma_i\}$ of segments in $\mathcal{H}(X)$ such that the homogeneous quasimorphisms $\{\hat{\varphi}_{\gamma_i}\}$ are linearly independent in $\widetilde{QH}(G)$.

**Proof.** — Let $a, b$ be standard generators of $G$ which generate a free subgroup $H < G$. We shall show that every “non-overlapping” Brooks quasimorphism on $H$ is the restriction of a quasimorphism $\hat{\varphi}_\gamma$ for some $\gamma$. By [22, Proposition 5.1] there is an infinite linearly independent family of Brooks quasimorphisms in $\widetilde{QH}(H)$, and their extensions will be independent in $\widetilde{QH}(G)$.

If $w$ is a reduced word in $a, b$, the non-overlapping Brooks quasimorphism $\hat{B}_w : \langle a, b \rangle \rightarrow \mathbb{R}$ is the homogenization of the quasimorphism $B_w = C_w - c_w$, where $C_w(g)$ is the maximal number of disjoint subwords of $g$ (considered as a reduced word) which equal $w$. In the 1–skeleton of $X$ there is an edge path labeled by the word $w$, starting at a vertex $x$ and ending at $y$. Because $a$ and $b$ do not commute, no two half-spaces dual to this segment can cross. Thus $[x, y]$ is a segment, which we denote by $\gamma(w)$. Modulo the $G$–action on $X$, $\gamma(w)$ is uniquely determined by $w$.

We claim that $B_w(g) = \varphi_{\gamma(w)}(g)$ for every $g \in H$, and therefore $\hat{B}_w$ is the restriction of $\hat{\varphi}_{\gamma(w)}$ to $H$. If an element $g \in H$ is considered as a reduced word, it has a combinatorial axis in $X$ which is labeled by $g^\infty$. The half-spaces dual to this axis never cross, and so the partial ordering on $A_g^+$ is a linear ordering. Thus $X^\text{ess}_g$ is one-dimensional and the axis is an embedded copy of $X^\text{ess}_g$ in $X_g \subset X$. Let $x_g$ be a vertex on this axis at the beginning of the word $g$; this is the basepoint for the definition of $\varphi_{\gamma(w)}(g)$. Now segments in $[x_g, gx_g]$ correspond bijectively with subwords of $g$ via the labelling, and so $B_w(g) = \varphi_{\gamma(w)}(g)$. \qed
5. Dilworth’s theorem and equivariant embeddings

Let \( P \) be a partially ordered set. A \textit{chain} in \( P \) is a subset that is linearly ordered. A chain is \textit{maximal} if it is not properly contained in another chain. An \textit{antichain} in \( P \) is a subset such that no two elements are comparable to each other. The \textit{width} of \( P \) is the maximal cardinality of an antichain (which may be \( \infty \)).

**Lemma 5.1** (Dilworth’s theorem). — Let \( P \) be a partially ordered set. If \( P \) has width \( d < \infty \) then there is a partition of \( P \) into \( d \) chains. Furthermore, there is such a partition such that one of the chains is maximal.

This first conclusion is the traditional statement of the theorem. The second claim can be proved using Hausdorff’s maximal principle.

The partition of \( P \) into chains provided by the theorem will be called a \textit{Dilworth partition}.

**Definition 5.2.** — Let \( P \) be a partially ordered set that admits an order-preserving free action by an infinite cyclic group \( \langle g \rangle \). Let \( A \) be an antichain in \( P \). We say \( A \) is \( \langle g \rangle \)-descending if \( ga \not> a' \) for all \( a, a' \in A \). We say that \( A \) spans \( P \) if for each \( p \in P \) there exist \( a, a' \in A \) and \( r, s \in \mathbb{Z} \) such that \( g^r a > p > g^s a' \).

We further define the subsets

\[ [A, gA] = \{ p \in P : x \geq p \geq y \text{ for some } x, y \in (A \cup gA) \}, \]

which equals

\[ \{ p \in P : x \geq p \geq y \text{ for some } x \in A, y \in gA \} \]

if \( A \) is \( \langle g \rangle \)-descending, and

\[ [A, gA] = [A, gA] - gA, \quad (A, gA) = [A, gA] - A. \]

**Lemma 5.3** (Equivariant Dilworth theorem). — Let \( P \) be a partially ordered set of width \( d < \infty \) with an order-preserving free action by an infinite cyclic group \( \langle g \rangle \). Suppose further that there is an antichain \( A \) of cardinality \( d \) that is both \( \langle g \rangle \)-descending and spans \( P \). Then there is a \( \langle g \rangle \)-invariant partition of \( P \) into \( d \) chains whose intersection with \( [A, gA] \) is a Dilworth partition which includes a maximal chain in \( [A, gA] \).

**Proof.** — Apply Lemma 5.1 to the partially ordered set \( [A, gA] \) to obtain a partition by chains \( [A, gA] = Q_1 \cup \cdots \cup Q_d \), with \( Q_1 \) maximal in \( [A, gA] \). Each \( Q_i \) contains exactly one element of \( A \) and one of \( gA \), since these
are antichains of cardinality $d$. We claim that these are the maximal and minimal elements, respectively, of $Q_i$.

Suppose the unique element $a$ of $A \cap Q_i$ is not maximal in $Q_i$. If $p \in Q_i$ satisfies $p > a$ then, since $p \in (A, gA)$, we must have $x > p$ for some $x \in A$. Then $x > p > a$, contradicting that $A$ is an antichain. By a similar argument, the unique element of $gA \cap Q_i$ is minimal in $Q_i$.

Now label the elements of $A$ and define a permutation $\sigma$ as follows: $a_i$ is the maximal element of $Q_i$ and $ga_{\sigma(i)}$ is the minimal element of $Q_i$, for $i = 1, \ldots, d$. Define the sets

$$P_i = \bigcup_{k \in \Z} g^kQ_{\sigma^k(i)}$$

for each $i$. Note that for each $k$, the element $g^k a_{\sigma^k(i)}$ is both the minimum of $g^{-k}Q_{\sigma^{k-1}(i)}$ and the maximum of $g^k Q_{\sigma^k(i)}$. Hence $P_i$ is a chain, being a concatenation of chains. Since $\langle g \rangle$ acts freely on $P$, the chains $P_i$ are disjoint. Their union is the set $\bigcup_{k \in \Z} g^k[A, gA]$. It is immediate that $gP_{\sigma(i)} = P_i$, so the partition of $\bigcup_{k \in \Z} g^k[A, gA]$ by the chains $P_i$ is preserved by $g$.

Given $p \in P$, let $a, a', r, s$ be given such that $g^ra > p > g^sa'$. First we claim that $s > r$. If not, then $r > s$. Writing $a = a_i$ we have $g^r a_i < g^{-1} a_{\sigma^{-1}(r)} < \cdots < g^s a_{\sigma^{-s}(r)}$, whence $g^s a' < g^s a_{\sigma^{-s}(r)}$, a contradiction since $g^s A$ is an antichain.

Next we show that $p \in \bigcup_{k \in \Z} g^k[A, gA]$, by induction on $s - r$. Clearly we may assume that $p \not\in \bigcup_{k \in \Z} g^k A$. If $s - r = 1$ then we already have $p \in g^r A$. If $s - r > 1$ then consider the (maximal) antichain $g^{r+1} A$. It contains an element $g^{r+1} a''$ which is comparable to $p$, by maximality. Then either $g^r a > p > g^{r+1} a''$ or $g^{r+1} a'' > p > g^s a'$, and in either case the induction hypothesis yields the conclusion that $p \in \bigcup_{k \in \Z} g^k[A, gA]$.

\[\square\]

**Equivariant Euclidean embeddings**

Let $\R^d$ be equipped with its standard integer cubing. Given a coordinate $i$ and an integer $n$, we define:

$$H^i_n = \{(x_1, \ldots, x_d) \in \R^d : x_i \geq n + 1/2\}.$$ 

Note that $H^i_n$ and $H^i_n$ are transverse in $\R^d$ if and only if $i \neq j$. We also define $\mathcal{H}^i = \{H^i_n : n \in \Z\}$, and set

$$\mathcal{H}^+(\R^d) = \mathcal{H}^1 \sqcup \cdots \sqcup \mathcal{H}^d.$$
The set of half-spaces of $\mathbb{R}^d$ is $\mathcal{H}(\mathbb{R}^d) = \mathcal{H}^+(\mathbb{R}^d) \cup \mathcal{H}^- (\mathbb{R}^d)$, where $\mathcal{H}^-(\mathbb{R}^d) = \{ \overline{H} : H \in \mathcal{H}^+(\mathbb{R}^d) \}$.

**Proposition 5.4.** Let $g \in G$ be hyperbolic and suppose $\langle g \rangle$ acts non-transversely on $X_g^{\text{ess}}$. Let $C$ be a cube in $X_g^{\text{ess}}$ of dimension $d = \dim(X_g^{\text{ess}})$ and let $A$ be the set of elements of $A_g^+$ dual to the edges of $C$. Then there exist a $\langle g \rangle$–action on $\mathbb{R}^d$ and a $\langle g \rangle$–equivariant isometric embedding $\phi: X_g^{\text{ess}} \hookrightarrow \mathbb{R}^d$ satisfying the following properties:

1. $\phi(C) = [0,1]^d \subset \mathbb{R}^d$.
2. The induced map $\phi_*: A_g \rightarrow \mathcal{H}(\mathbb{R}^d)$ is a bijection, with $\phi_*(A_g^+) = \mathcal{H}^+(\mathbb{R}^d)$.
3. The set $[A, gA] \cap \phi_+^{-1}(\mathcal{H}^1)$ is tightly nested in $X_g^{\text{ess}}$.
4. $[A, gA] = [0,go]$, where $o$ is the minimal vertex of $C$.

By property (2), we can henceforth identify elements of $A_g^+$ with their corresponding half-spaces in $\mathcal{H}^+(\mathbb{R}^d)$ and we shall denote the corresponding decomposition as $A_g^+ = \mathcal{H}^1 \cup \cdots \cup \mathcal{H}^d$. By property (3), every subsegment of $[A, gA] \cap \mathcal{H}^1$ is tightly nested in $A_g^+$. We will call $\gamma = [A, gA] \cap \mathcal{H}^1$ the taut segment of the embedding; $[A, gA] \cap \mathcal{H}^1$ the extended taut segment; and the map $\phi$ a taut $\langle g \rangle$–equivariant embedding of $X_g^{\text{ess}}$ into $\mathbb{R}^d$.

**Proof of Proposition 5.4.** Let $P = A_g^+$ be partially ordered by inclusion; note that this partial ordering is preserved by $\langle g \rangle$. It has width $d$ since $X_g^{\text{ess}}$ has dimension $d$, and $A$ is an antichain of cardinality $d$. By Proposition 3.21 (1), $A$ is $\langle g \rangle$–descending. By Proposition 3.21 (3), $A$ spans $P$. We also have that $[A, gA] = [0, go]$, by Proposition 3.21 (2), and therefore (4) holds.

Now apply Lemma 5.3 to $P$ to obtain a $\langle g \rangle$–invariant partition of $P$ into $d$ chains $P_1, \ldots, P_d$. Without loss of generality, we may assume that $P_1 \cap [A, gA]$ is a maximal chain in $[A, gA]$. Note that each chain $P_i$ is bi-infinite, since $\langle g \rangle$ acts freely on it.

For each $i$, let $K_i$ be the unique element of $P_i \cap A$. There is an order-preserving bijection $P_i \rightarrow \mathcal{H}^i$ induced by sending $K_i$ to $H_i^0$. The resulting bijection $A_g^+ \rightarrow \mathcal{H}^+(\mathbb{R}^d)$ extends to a bijection $\phi_*: A_g \rightarrow \mathcal{H}(\mathbb{R}^d)$ in an obvious way.

We now define an isometric embedding $\phi: X_g^{\text{ess}} \hookrightarrow \mathbb{R}^d$ whose induced map on half-spaces is $\phi_*$. For any $x \in \mathbb{R}^d$, denote by $x_i$ its $i$–th coordinate. Let $v \in X_g^{\text{ess}}$ be any vertex. For each $i$, let $K \in P_i$ be the largest element such that $v \notin K$. Define $\phi(x)_i = n$, where $\phi_*(K) = H^n_i$. This defines an embedding of the vertices of $X_g^{\text{ess}}$ into $\mathbb{R}^d$. Two vertices $v$ and $w$ in $X_g^{\text{ess}}$ bound an oriented edge $(v, w)$ dual to $K \in P_i$ if and only if $\phi(w)_i = \phi(v)_i+1$.
and $\phi(w)_j = \phi(v)_j$ for all $j \neq i$. Therefore $\phi$ extends to an embedding of the 1–skeleton of $X^\text{ess}_g$, and hence extends to all of $X^\text{ess}_g$. It is immediate that $\phi$ induces the same map on half-spaces as $\phi_*$, so property (2) holds. By construction, $\phi$ is mapped to the origin and the vertex of $C$ opposite $o$ is mapped to $(1, \ldots, 1)$, so (1) holds.

By $\langle g \rangle$–invariance of the partition, there is a permutation $\sigma$ such that $gP_{\sigma(i)} = P_i$. For each $i$ let $n_i = \phi(g(o))_i$. That is, $n_i$ is the shift given by the bijection $g: P_\sigma(i) \to P_i$, relative to the basepoints $K_\sigma(i)$ and $K_i$. Then, for every vertex $v \in X^\text{ess}_g$, we have

$$\phi(g(v))_i = \phi(v)_{\sigma(i)} + n_i.$$

This allows us to define an action of $\langle g \rangle$ on $\mathbb{R}^d$: for every $x \in \mathbb{R}^d$ let $g(x)_i = x_{\sigma(i)} + n_i$. By construction, $\phi$ is $\langle g \rangle$–equivariant.

For property (3), note that $[A, gA] \cap \phi^{-1}(\mathcal{H}^1) = P_1 \cap [A, gA]$. Suppose $K' \supset K \supset K''$ for some $K \in A_g$ and $K', K'' \in P_1 \cap [A, gA]$. There is a unique $i \in \mathbb{Z}$ such that $K \in [g^iA, g^{i+1}A]$. If $i < 0$, then $K \supset H$ for some $H \in A$, which contradicts $K' \supset K$. If $i > 0$, then $gH \supset K$ for some $H \in A$. But $gH \supset K$ contradicts $K \supset K''$, so $K \in [A, gA]$. By maximality, $K \in P_1 \cap [A, gA]$. This shows that $P_1 \cap [A, gA]$ is tightly nested. □

**An example**

Let $A_\Gamma$ be the right-angled Artin group with $\Gamma$ the pentagon graph:

$$A_\Gamma = \langle a, b, c, d, e | [a, b] = [b, c] = [c, d] = [d, e] = [e, a] = 1 \rangle.$$

The element $g = abcd e$ is hyperbolic, and part of its essential characteristic set $X^\text{ess}_g$ is shown in Figure 5.1. The figure also demonstrates the equivariant embedding $X^\text{ess}_g \hookrightarrow \mathbb{R}^2$. The action of $g$ on $\mathbb{R}^2$ (extending the natural action on $X^\text{ess}_g$) is by a glide reflection whose axis is a diagonal line through the center of the figure. The $A_\Gamma$–invariant labeling of the edges of $X^\text{ess}_g$ by generators of $A_\Gamma$ is also shown. For this particular choice of $g$, the essential characteristic set has the property that the equivariant embedding $X^\text{ess}_g \hookrightarrow \mathbb{R}^2$ is unique, up to a change of coordinates in $\mathbb{R}^2$ by a cubical automorphism. The action on $\mathbb{R}^2$ is always by a glide reflection, for this $g$. Other elements have characteristic sets that may embed in more than one way, with $g$ acting on $\mathbb{R}^2$ either as a translation or a glide reflection (depending on the embedding).
Figure 5.1. The subcomplex $X^\text{ess}_g$ embedded in $\mathbb{R}^2$ for the element $g = abcde$ in the pentagon RAAG. The extended action of $g$ on $\mathbb{R}^2$ is by a glide reflection. The three blue half-spaces (with labels $a$, $c$, $e$) are taken to the three red half-spaces.

**The staircase**

Our goal in the rest of the paper will be to associate to each hyperbolic element $g$ a segment $\gamma$ such that $\hat{\phi}_\gamma(g) \geq 1$. Bavard Duality then will allow us to conclude that $\text{scl}(g) \geq 1/24$. Here we illustrate one of the difficulties in finding such segments.

Consider $\mathbb{R}^2$ with its standard integer cubing, and let $X$ be the subcomplex obtained by removing all vertices $(x, y) \in \mathbb{Z}^2$ with $y < x - 1$ (see Figure 5.2). We will refer to $X$ as the staircase.

Let $G = \langle g \rangle$, where $g$ is the restriction of the translation $(x, y) \mapsto (x + 2, y + 2)$ to $X$. Note that $X = X_g = X^\text{ess}_g$. Let $x_g = (0, 0)$. Consider the two half-spaces

$$H_1 = \{(x, y) \in X : y \geq 1/2\} \quad \text{and} \quad H_2 = \{(x, y) \in X : x \geq 3/2\}$$

shown in blue on the left hand side of Figure 5.2. The set $\gamma = \{H_1, H_2\}$ is a segment in $[x_g, g x_g]$ (recall that this means $\gamma$ is tightly nested). For any
positive integer \( n \), \( g^n H_1 \) and \( H_2 \) are transverse, so \( \gamma \) and \( g^n \gamma \) overlap. It follows that \( c_\gamma(g^n) = 1 \) for all \( n \), which means that \( \hat{c}_\gamma(g) \leq 0 \).

A better choice of segment \( \gamma \subset [x_g, gx_g] \) is shown on the right hand side of Figure 5.2. The half-space \( H_1 \) has been replaced by \( \{(x, y) \in X : x \geq 1/2 \} \). In this case, \( \gamma \) and \( g\gamma \) do not overlap, and in fact \( c_\gamma(g^n) = n \) for all positive \( n \).

This example indicates that from the point of view of an equivariant Euclidean embedding, one should choose a segment \( \gamma \) which lies in a single coordinate direction in \( \mathbb{R}^d \) to ensure that \( c_\gamma(g^n) \) grows linearly with \( n \). (Keeping \( c_\gamma(g^n) \) bounded is a much more serious hurdle to be dealt with in Sections 8 and 9.) It is for this reason that we required one of the chains in the Dilworth partition to be maximal in Lemma 5.3, leading to property (3) in Proposition 5.4. This property ensures that in at least one coordinate direction of \( \mathbb{R}^d \), consecutive half-spaces in \( \mathbb{R}^d \) are tightly nested in \( X^{\text{ess}}_g \), and therefore define segments in \( X^{\text{ess}}_g \).

6. Quadrants

In this section we present two basic tools for working with equivariant Euclidean embeddings: the Quadrant Lemma and the Elbow Lemma. They are useful in determining which cubes in \( \mathbb{R}^d \) are occupied by \( X^{\text{ess}}_g \). Let \( x_i \) and \( x_j \) be coordinates of \( \mathbb{R}^d \). We will denote by \( p_{ij} : \mathbb{R}^d \to \mathbb{R}^2 \) the projection of \( \mathbb{R}^d \) onto the \( x_i x_j \)-coordinate plane.
Consider a \( g \)-equivariant embedding \( X^\text{ess}_g \hookrightarrow \mathbb{R}^d \), where \( d = \dim X^\text{ess}_g \). Recall that via this embedding we identify elements of \( A^+_g \) with their corresponding half-spaces \( \mathcal{H}^+ \) in \( \mathcal{H}(\mathbb{R}^d) \). We will generally suppress the embedding itself and will treat \( X^\text{ess}_g \) as a subcomplex of \( \mathbb{R}^d \).

**Remarks 6.1.**

(a). — Recall from Lemma 3.8 that if \( H, H' \in A^+_g \) then \( H \) and \( H' \) are transverse in \( X \) if and only if they are transverse in \( X^\text{ess}_g \). When this occurs, they will also be transverse in \( \mathbb{R}^d \), but not conversely.

(b). — Expressing these two half-spaces as \( H_i^m \) and \( H_j^m \), the subcomplex \( p_{ij}(X^\text{ess}_g) \) of \( \mathbb{R}^2 \) contains the square \([n, n+1] \times [m, m+1]\) if and only if \( H_i^m \) and \( H_j^m \) are transverse in \( X^\text{ess}_g \). To see this, note that the latter occurs if and only if \( \partial H_i^m \) and \( \partial H_j^m \) cross in some square in \( X^\text{ess}_g \subseteq \mathbb{R}^d \). If they cross in the square \( S \), then the image of \( S \) in \( \mathbb{R}^2 \) is a cube which is dual to both \( H_i^m \) and \( H_j^m \), which must be the square \([n, n+1] \times [m, m+1]\).

(c). — If \( H, H' \in A^+_g \) then \( H \) and \( H' \) are (tightly) nested in \( X \) if and only if they are (tightly) nested in \( X^\text{ess}_g \). If they are nested in \( \mathbb{R}^d \) then they are nested in \( X^\text{ess}_g \), but not conversely. There is no a priori relation between being tightly nested in \( X \) and being tightly nested in \( \mathbb{R}^d \). Half-spaces \( H \) and \( H' \) may be tightly nested in \( X \) and not tightly nested in \( \mathbb{R}^d \), and vice versa.

**Definition 6.2.** — A quadrant in \( \mathbb{R}^d \) is an open set of the form

\[
\{(x_1, \ldots, x_d) : x_i < n \text{ and } x_j > m\}
\]

where \( i \neq j \) and \( m, n \in \mathbb{Z} \). Often, one of the coordinates \( x_i \) or \( x_j \) will be designated as the horizontal coordinate. If \( x_i \) is horizontal, then the quadrant above is called a northwest quadrant, and if \( x_j \) is horizontal, it is called a southeast quadrant.

**Lemma 6.3 (Quadrant Lemma).** — Let \( H_i^m, H_j^m \in \mathcal{H}^+ \) be half-spaces with \( i \neq j \) and suppose \( x_i \) is horizontal. Then one of the following holds:

1. \( H_i^m \) and \( H_j^m \) are transverse in \( X^\text{ess}_g \);
2. \( H_i^m \supset H_j^m \) in \( X^\text{ess}_g \) and \( X^\text{ess}_g \) is disjoint from the northwest quadrant \( \{x_i < n + 1, \ x_j > m\} \);
3. \( H_i^m \subset H_j^m \) in \( X^\text{ess}_g \) and \( X^\text{ess}_g \) is disjoint from the southeast quadrant \( \{x_i > n, \ x_j < m + 1\} \).

The quadrant in case 2 or 3 that is disjoint from \( X^\text{ess}_g \) will be called the quadrant generated by \( H_i^m \) and \( H_j^m \).
Put another way, if $p_{ij}(X^{\text{ess}})\) does not contain the square $[n, n + 1] \times [m, m + 1]$, then it does not meet the quadrant generated by that square; see Figure 6.1.

Whenever $H \in \mathcal{H}^i$, $K \in \mathcal{H}^j$ are nested in $X^{\text{ess}}$ with $i \neq j$, denote by $Q(H, K)$ the quadrant generated by this pair of half-spaces. By definition, it is always disjoint from $X^{\text{ess}}$.

**Proof.** — If the first alternative does not hold, then the corresponding half-spaces in $X^{\text{ess}}$ are nested, by Remark 3.1. That is, one of $H_n^i \cap X^{\text{ess}}$, $H_m^j \cap X^{\text{ess}}$ contains the other. Suppose $H_n^i \cap X^{\text{ess}}$ contains $H_m^j \cap X^{\text{ess}}$. If a vertex $v = (v_1, \ldots, v_d)$ of $X^{\text{ess}}$ satisfies $v_j \geq m + 1$ then $v \in H_m^j \cap X^{\text{ess}}$, so $v \in H_n^i$. Hence $v_i \geq n + 1$, showing that $v \notin \{x_i \leq n, \ x_j \geq m + 1\}$. Thus the second alternative holds. Similarly, if $H_m^j \cap X^{\text{ess}}$ contains $H_n^i \cap X^{\text{ess}}$, then the third alternative holds. □

**Figure 6.1. The Quadrant Lemma:** if $X^{\text{ess}}$ avoids the interior of a square, it also avoids a northwest or southeast quadrant.
Lemma 6.4. — Suppose $H \in \mathcal{H}^i$ and $K, K' \in A^+_q - \mathcal{H}^i$ are such that $K, K'$ are tightly nested and the pairs $H, K$ and $H, K'$ are nested in $X^g_{\text{ess}}$. Let $x_i$ be horizontal. Then the quadrants $Q(H, K)$ and $Q(H, K')$ both face northwest or both face southeast.

Proof. — Suppose without loss of generality that $K \subset K'$. If $Q(H, K)$ faces northwest and $Q(H, K')$ faces southeast, then $K \subset H$ and $H \subset K'$ by the Quadrant Lemma. Now $H$ violates the assumption that $K, K'$ are tightly nested. If $Q(H, K')$ faces northwest and $Q(H, K)$ faces southeast, then $K' \subset H$ and $H \subset K$. Hence $K' \subset K$, a contradiction. □

Lemma 6.5 (Elbow Lemma). — Suppose $H^i_n \subset H^j_m$ are tightly nested in $X^g_{\text{ess}}$ where $i \neq j$. Then the edges $\{n\} \times [m, m+1]$ and $[n, n+1] \times \{m\}$ are contained in $p_{ij}(X^g_{\text{ess}})$.

The two edges form an “elbow” at the corner of the quadrant $Q(H^i_n, H^j_m) = \{x_i > n, \ x_j < m+1\}$ (and $X^g_{\text{ess}}$ avoids this quadrant, by the Quadrant Lemma).

Proof. — Designate $x_i$ as the horizontal coordinate. We consider the edge $\{n\} \times [m, m+1]$ (the other case being entirely similar).

If the square $[n-1, n] \times [m, m+1]$ is in $p_{ij}(X^g_{\text{ess}})$, then so is the edge $\{n\} \times [m, m+1]$ and we are done. If not, then the half-spaces $H^i_{n-1}$ and $H^j_m$ are nested in $X^g_{\text{ess}}$. We cannot have $H^i_{n-1} \subset H^j_m$ in $X^g_{\text{ess}}$, because $H^i_n \subset H^i_{n-1}$ and $H^j_m, H^j_{m-1}$ are tightly nested. Therefore, $H^j_m \subset H^i_{n-1}$ in $X^g_{\text{ess}}$. By the Quadrant Lemma, the northwest quadrant generated by the square $[n-1, n] \times [m, m+1]$ is disjoint from $p_{ij}(X^g_{\text{ess}})$. Similarly, since $H^i_n \subset H^j_m$, the southeast quadrant generated by the square $[n, n+1] \times [m, m+1]$ is also disjoint from $p_{ij}(X^g_{\text{ess}})$. The edge $\{n\} \times [m, m+1]$ now provides the only passage across the strip $\mathbb{R} \times [m, m+1]$. It must be in $p_{ij}(X^g_{\text{ess}})$, or $X^g_{\text{ess}}$ could not contain an axis. □

Remark 6.6. — The Quadrant Lemma and the Elbow Lemma do not use the fact the embedding $X^g_{\text{ess}} \hookrightarrow \mathbb{R}^d$ is equivariant. These results hold (with $X^g_{\text{ess}}$ replaced with $Y$) whenever $Y$ is a convex subcomplex of a CAT(0) cube complex $X$ and there is a Euclidean embedding $Y \hookrightarrow \mathbb{R}^d$ that induces a bijection between $\mathcal{H}(Y)$ and $\mathcal{H}(\mathbb{R}^d)$.

7. RAAG-like actions on cube complexes

Recall from Section 2 that every right-angled Artin group $A_{\Gamma}$ acts on a CAT(0) cube complex $X_{\Gamma}$, and that the oriented edges of $X_{\Gamma}$ admit an
\(A_{\Gamma}\)-invariant labeling by the generators and their inverses. Also, there is an induced \(A_{\Gamma}\)-invariant labeling of the half-spaces of \(X_{\Gamma}\).

As noted earlier, properties of the half-space labeling lead to many useful observations about \(X_{\Gamma}\) and its \(A_{\Gamma}\)-action. The definition below is based on some of these properties of \(X_{\Gamma}\).

**Definition 7.1.** — Let \(X\) be a CAT(0) cube complex with an action by \(G\). The action is RAAG-like if it is without inversion and also satisfies:

1. there do not exist \(H \in \mathcal{H}(X)\), \(g \in G\) with \(H \cap gH\),
2. there do not exist tightly nested \(H, H' \in \mathcal{H}(X)\), \(g \in G\) with \(H \cap gH'\),
3. there do not exist \(H \in \mathcal{H}(X)\), \(g \in G\) with \(H\) and \(gH\) tightly nested.

When the \(G\)-action on \(X\) is understood, we may simply say that \(X\) is RAAG-like.

**Remark 7.2.** — If one has a \(G\)-action on \(X\) with an inversion, it is customary to perform a cubical subdivision to obtain an action without inversion. We note here that the resulting action will never be RAAG-like, since it will violate property 7.1(3).

**Lemma 7.3.** — For every simplicial graph \(\Gamma\), the action of \(A_{\Gamma}\) on \(X_{\Gamma}\) is RAAG-like.

**Proof.** — We have already observed in Section 2 that \(A_{\Gamma}\) acts without inversion on \(X_{\Gamma}\). We have also observed that since boundaries of squares in \(X_{\Gamma}\) are labeled by commutators \([v, w]\) with \(v \neq w\), no two half-spaces in \(X_{\Gamma}\) with the same label can cross. Property (1) follows immediately.

For (2), suppose \(H, H'\) are tightly nested half-spaces in \(X_{\Gamma}\). Then there is a vertex \(x \in X_{\Gamma}\) and a pair of edges \(e, e'\) both incident to \(x\), such that \(e\) is dual to \(H\) and \(e'\) is dual to \(H'\) (modulo orientations). Since \(H\) and \(H'\) do not cross, the edges \(e\) and \(e'\) are not in the boundary of a common square; hence their labels do not commute in \(A_{\Gamma}\). It follows that no two half-spaces bearing these labels (or their inverses) can cross. In particular, \(H\) and \(gH'\) cannot cross for any \(g \in A_{\Gamma}\).

For (3), suppose \(H\) and \(gH\) are tightly nested for some \(H \in \mathcal{H}(X_{\Gamma})\), \(g \in A_{\Gamma}\). Switching \(H\) and \(gH\) if necessary, we may assume that \(H \subset gH\). Since they are tightly nested, there is a pair of (oriented) edges \(e, e'\) with common initial vertex \(x\) such that \(e\) is dual to \(H\) and \(e'\) is dual to \(gH\). Then \(e\) and \(e'\) bear the same label \(v\), since the half-space labeling is \(A_{\Gamma}\)-invariant. However, vertices in \(X_{\Gamma}\) have exactly one edge incident to them with any
Given label (being lifts of the same oriented edge of \( K(A, 1) \) at the same initial vertex). This contradiction establishes property (3). \( \square \)

**Remark 7.4.** — The properties of Definition 7.1 correspond precisely to the defining properties of special cube complexes due to Haglund and Wise [19], as enumerated in [26]. More specifically, if \( G \) acts freely on a CAT(0) cube complex \( X \), then the action is RAAG-like if and only if \( X/G \) is special.

The properties correspond as follows. Property (1) means that immersed hyperplanes in \( X/G \) are embedded (and hence can simply be called hyperplanes). \( G \) acting on \( X \) without inversion means that all hyperplanes in \( X/G \) are two-sided. Property (2) means that pairs of hyperplanes in \( X/G \) do not inter-osculate. Property (3) means that hyperplanes in \( X/G \) do not self-osculate.

**Remark 7.5.** — Note that Definition 7.1(1) in particular means that the action of \( G \) on \( X \) is non-transverse. Therefore, for any hyperbolic element \( g \in G \), the action of \( \langle g \rangle \) on \( X^\text{ess}_g \) is non-transverse. Hence, by Proposition 3.17, \( X^\text{ess}_g = M^\text{ess}_g \) for all hyperbolic elements \( g \in G \).

**8. Tightly nested segments in the essential characteristic set**

In Section 6, we presented some general tools for studying equivariant Euclidean embeddings of \( X^\text{ess}_g \). Here we develop more specialized results to be used in proving the main theorem. Generally speaking, these results deal with situations where there is a tightly nested segment \( \sigma \subset \mathcal{A}^+_g \) in one coordinate direction \( \mathcal{H}^i \), and an element \( f \in G \) such that \( f\sigma \subset \mathcal{A}^+_g \).

For the rest of this section and the next section, we will assume that \( X \) is a CAT(0) cube complex with a RAAG-like \( G \)-action.

Fix a hyperbolic element \( g \in G \) and apply Proposition 5.4 to obtain a taut \( \langle g \rangle \)-equivariant embedding \( X^\text{ess}_g \hookrightarrow \mathbb{R}^d \). Recall that a cube of maximal dimension \( C \subset X^\text{ess}_g \) is mapped to \([0, 1]^d \subset \mathbb{R}^d\), and we identify \( \mathcal{A}^+_g \) with \( \mathcal{H}^+(\mathbb{R}^d) = \mathcal{H}^1 \sqcup \cdots \sqcup \mathcal{H}^d \). The set of half-spaces in \( \mathcal{A}^+_g \) dual to \( C \) is denoted \( \mathcal{A} \), and \( [A, gA] \cap \mathcal{H}^1 = \{ H^1_0, \ldots, H^1_n \} \) is a tightly nested segment in \( \mathcal{A}^+_g \). Since \( \langle g \rangle \) acts non-transversely on \( X^\text{ess}_g \), we also have \( [A, gA] = [o, go] \), where \( o \) denotes the origin in \( \mathbb{R}^d \).

**Remark 8.1.** — Since the action is assumed to be RAAG-like, property 7.1(1) implies that if \( H \in \mathcal{H}^i \) and \( hH \in \mathcal{H}^j \) with \( i \neq j \) for some
$H \in A_g^+, h \in G$, then the quadrant $Q(H, hH)$ exists. Property 7.1(2) implies that if in addition $H$ and $H' \in \mathcal{H}^i$ are tightly nested in $X^\text{ess}_g$, then the quadrant $Q(H', hH)$ exists. (Recall that, by definition, $Q(H, K)$ is always disjoint from $X^\text{ess}_g$.)

When discussing a quadrant $Q$ of the form $Q(H, hH)$, if $H$ and $H' \in \mathcal{H}^i$ are tightly nested in $\mathcal{X}^\text{ess}_g$, then the quadrant $Q(H', hH)$ exists. (Recall that, by definition, $Q(H, K)$ is always disjoint from $\mathcal{X}^\text{ess}_g$.)

When discussing a quadrant $Q$ of the form $Q(H, hH)$, if $H$ and $H' \in \mathcal{H}^i$ are tightly nested in $\mathcal{X}^\text{ess}_g$, then the quadrant $Q(H', hH)$ exists. (Recall that, by definition, $Q(H, K)$ is always disjoint from $\mathcal{X}^\text{ess}_g$.)

The first two results below will be used to generate contradictions. The first lemma states that when a certain configuration occurs (involving both a northwest and southeast quadrant) then there is a tightly nested segment that is forced to overlap with a copy of its reverse. The second lemma says that the latter event is impossible. Several of the arguments in the remainder of the paper have the goal of showing that a quadrant faces a particular way (northwest or southeast), with the aim of creating the forbidden configuration, and thereby a contradiction.

**Lemma 8.2.** — Let $\sigma = \{K_0, \ldots, K_m\} \subset \mathcal{H}^i$ be tightly nested in $X^\text{ess}_g$ and suppose that $f\sigma \subset A_g^+$ for some $f \in G$. Let $x_i$ be horizontal. Suppose there exist $j \leq j'$ such that $fK_j, fK_{j'} \notin \mathcal{H}^i$ and $Q(K_j, fK_j)$ faces northwest while $Q(K_{j'}, fK_{j'})$ faces southeast. Then there is a non-trivial subsegment $\alpha \subset \sigma$ such that $f\alpha \subset \mathcal{H}^i$ and $\alpha$ overlaps.

**Proof.** — First note that if $j = j'$ then $X^\text{ess}_g$ avoids both of the quadrants

$$\{x_i < n + 1, x_j > m\} \text{ and } \{x_i > n, x_j < m + 1\}$$

for some $n, m \in \mathbb{Z}$. But then $X^\text{ess}_g$ avoids the set $\{n < x_i < n + 1\}$ and cannot contain an axis for $g$. Thus $j < j'$.

For any index $k$, the quadrant $Q(K_k, fK_k)$ is defined if and only if $fK_k \notin \mathcal{H}^i$, by Remark 8.1. We may choose $j, j'$ to be an innermost pair having the stated properties. Then, for any $k$ between $j$ and $j'$, we have $fK_k \in \mathcal{H}^i$.

Since the pair $K_{j'-1}, K_{j'}$ are tightly nested, there is an extended quadrant $Q(K_{j'-1}, fK_{j'})$ which faces southeast (cf. Remark 8.1). There is also an extended northwest quadrant $Q(K_{j+1}, fK_j)$, since $K_j, K_{j+1}$ are tightly nested.

If $j' = j + 1$ then $fK_j$ and $fK_{j'}$ are tightly nested and Lemma 6.4 says that both quadrants $Q(K_j, fK_j)$ and $Q(K_j, fK_{j'}) = Q(K_{j'-1}, fK_{j'})$ face the same way. However, these face northwest and southeast respectively. Therefore, $j' > j + 1$ and the segment $\alpha = \{K_{j+1}, \ldots, K_{j'-1}\}$ is non-trivial.
Note that \( f\alpha \subset \mathcal{H}^i \) by the choice of \( j, j' \). We proceed now to use the Elbow Lemma 6.5 to constrain the location of \( f\alpha \) along \( \mathcal{H}^i \). In coordinates we have \( K_j = H^i_a \) and \( K'_j = H^i_b \) for some integers \( a < b \), and
\[
\alpha = \{K_{j+1}, \ldots, K_{j'-1}\} = \{H^i_{a+1}, \ldots, H^i_{b-1}\}.
\]
Write \( f\alpha = \{H^i_c, \ldots, H^i_{c+|\alpha|-1}\} \) for some \( c \in \mathbb{Z} \).

Let \( fK_{j'} = H^i_e \in \mathcal{H}^{i'} \) where \( i' \neq i \) and \( e \in \mathbb{Z} \). Applying the Elbow Lemma to the tightly nested pair \( \{fK_{j'-1}, fK_{j'}\} = \{H^i_e, H^i'_e\} \), we find that the edge \( \{c\} \times [e, e+1] \) lies in \( p_{i'}(X^\text{ess}_g) \). Since \( X^\text{ess}_g \) avoids the quadrant \( Q(K_{j'-1}, fK_{j'}) = \{x_i > b - 1, x_{i'} < e + 1\} \), we conclude that \( c \leq b - 1 \). See Figure 8.1.

![Figure 8.1](image-url)

**Figure 8.1.** The vertical position of the elbow is aligned with the top of the quadrant \( Q(K_{j'-1}, fK_{j'}) \) as shown. The horizontal position is aligned with the left end of \( f\alpha \). Since the elbow is outside the quadrant, \( f\alpha \) cannot be entirely to the right of \( \alpha \).

Now redefine \( i' \) and \( e \) such that \( fK_j = H^i_e \in \mathcal{H}^{i'} \) (with \( i' \neq i \)). Applying the Elbow Lemma to the tightly nested pair \( \{fK_j, fK_{j+1}\} = \{H^i_e, H^i_{c+|\alpha|-1}\} \), we find that \( p_{i'}(X^\text{ess}_g) \) contains the edge \( \{c+|\alpha|\} \times [e, e+1] \). Now \( X^\text{ess}_g \) avoids the quadrant \( Q(K_{j+1}, fK_{j}) = \{x_i < a + 2, x_{i'} > e\} \), and therefore \( c + |\alpha| \geq a + 2 \).
The inequalities $c \leq b - 1$ and $c + |\alpha| \geq a + 2$ say precisely that $\alpha$ and $f \sigma$ overlap.

The conclusion of the preceding lemma leads directly to a contradiction:

**Lemma 8.3.** — Let $\alpha \subset \mathcal{H}^i$ be tightly nested in $X^\text{ess}_g$ and suppose that $h\alpha \subset \mathcal{H}^i$ for some $h \in G$. Then $\alpha$ and $h\alpha$ cannot overlap.

**Proof.** — Write $\alpha = \{H_a, \ldots, H_{a+k}\}$ and $h\alpha = \{H_{b-k}, \ldots, H_b\}$ for some $a, b \in \mathbb{Z}$. Then, $hH_{a+j} = \overline{H}_{b-j}$ for each $j$. The transformation $a + j \mapsto b - j$ either fixes $c$ or exchanges $c$ and $c + 1$, for some $c \in \mathbb{Z}$. If $\alpha$ and $h\alpha$ overlap then $H_c$ (and $H_{c+1}$ in the second case) are in $\alpha \cap h\alpha$. In the first case $h$ inverts $H_c$, contrary to the assumption that $G$ acts on $X$ without inversion. In the second case $h\overline{H}_c = H_{c+1}$, violating property 7.1(3). Thus $\alpha$ and $h\alpha$ cannot overlap. 

The next results perform a technical step that will be used repeatedly in the course of proving the main theorem. They also yield corollaries showing that under certain conditions, quadrants face in particular directions.

**Lemma 8.4** (Southeast quadrant shifting). — Let $\sigma = \{K_0, \ldots, K_m\} \subset \mathcal{H}^i$ be tightly nested in $X^\text{ess}_g$ and suppose there is an $f \in G$ such that $f\sigma \subset A^+_g$ and $f\sigma \not\subset \mathcal{H}^i$. Let $x_i$ be horizontal and let $k$ be the smallest index such that $fK_k \not\subset \mathcal{H}^i$. Suppose the quadrant $Q(K_k, fK_k)$ faces southeast, so that

$$Q(K_k, fK_k) = \{x_i > a + k, \; x_j > b + 1\}$$

for some $j \neq i, a, b \in \mathbb{Z}$. Then

1. $X^\text{ess}_g$ also avoids the larger quadrant $Q = \{x_i > a - k, \; x_j < b + 1\}$.
2. If $k > 0$ then $fK_0 \subset \mathcal{H}^i$ and $K_0 \subset fK_0$.

**Proof.** — If $k = 0$ then $Q = Q(K_k, fK_k)$ and there is nothing to prove, so assume that $k > 0$. It is implicit from the description of $Q(K_k, fK_k)$ that $K_k = H^i_{a+k}$ and $fK_k = H^i_b$. Let $\alpha = \{K_0, \ldots, K_{k-1}\}$ be the initial segment of $\sigma$ before $K_k$ and note that $f\sigma \subset \mathcal{H}^i$. Writing $f\alpha = \{H^i_{c-k}, \ldots, H^i_{c-1}\}$ for the appropriate $c \in \mathbb{Z}$, we have $fK_{k-1} = H^i_{c-k}$.

Applying the Elbow Lemma to the tightly nested pair $\{fK_{k-1}, fK_k\} = \{H^i_{c-k}, H^i_b\}$, we find that $p_{ij}(X^\text{ess}_g)$ contains the edge $e = \{c - k\} \times [b, b+1]$.

Since $e$ avoids the quadrant $Q(K_k, fK_k)$, we must have $c - k \leq a + k$. In fact, by Remark 8.1, $e$ avoids the extended quadrant $Q(K_{k-1}, fK_k) = \{x_i > a + k - 1, \; x_j < b + 1\}$, and so $c - k < a + k$. Thus $f\alpha$ cannot be entirely to the right of $\alpha$ in $\mathcal{H}^i$. By Lemma 8.3 $f\alpha$ cannot overlap with $\alpha$ and so it must lie entirely to its left. That is, $c \leq a$. See Figure 8.2.
Figure 8.2. The elbow is aligned with the left endpoint of \( f\alpha \) and the top side of the quadrant \( Q(K_{k-1}, fK_k) \). Hence \( f\alpha \) is not to the right of \( \alpha \). Since \( \alpha \) and \( f\alpha \) cannot overlap, we have \( c \leq a \). The elbow now generates a larger, “shifted” quadrant.

Now note that the quadrant generated by \( fK_{k-1} \) and \( fK_k \) (and avoided by \( X^{\text{ess}}_g \)) is

\[
Q(fK_{k-1}, fK_k) = \{ x_i > c - k, x_j < b + 1 \}
\supseteq \{ x_i > a - k, x_j < b + 1 \},
\]

proving (1). Finally, note that \( K_0 = H^i_a \) and \( fK_0 = H^i_{c-1} \), and (2) is clear since \( c - 1 < a \). □

**Corollary 8.5.** — Let \( \sigma = \{ K_0, \ldots, K_m \} \subset \mathcal{H}^i \) be tightly nested in \( X^{\text{ess}}_g \) and suppose there is an \( f \in G \) such that \( f\sigma \subset A^+_g \) and \( f\sigma \notin \mathcal{H}^i \). Let \( x_i \) be horizontal and let \( k \) be the smallest index such that \( fK_k \notin \mathcal{H}^i \). Suppose there is a vertex \( v \) in \( X^{\text{ess}}_g \) such that \( v \in K_0 \) and \( v \notin fK_k \). Then the quadrant \( Q(K_k, fK_k) \) faces northwest.

**Proof.** — Set \( K_0 = H^i_a \) for some \( a \in \mathbb{Z} \), so \( K_k = H^i_{a+k} \). We assume \( fK_k \notin \mathcal{H}^i \), so there exists \( j \neq i \) and \( b \in \mathbb{Z} \) such that \( fK_k = H^j_b \). Suppose \( Q(K_k, fK_k) \) faces southeast; that is:

\[
Q(K_k, fK_k) = \{ x_i > a + k, x_j < b + 1 \}.
\]
By Lemma 8.4(1), $X_g^{\text{ess}}$ also avoids the larger quadrant

$$Q = \{x_i > a - k, \ x_j < b + 1\}.$$ 

Since $v \notin fK_k$, $v_j < b$. But $v \in K_0$, so $v_i \geq a + 1$. So $v \in Q$, which is a contradiction. Therefore, $Q(K_k, fK_k)$ faces northwest. □

The next two results are completely analogous to the previous two, with the same proofs:

**Lemma 8.6 (Northwest quadrant shifting).** — Let $\sigma = \{K_0, \ldots, K_m\} \subset H^i$ be tightly nested in $X_g^{\text{ess}}$ and suppose there is an $f \in G$ such that $f\sigma \subset A^+_g$ and $f\sigma \not\subset H^i$. Let $x_i$ be horizontal and let $k$ be the largest index such that $fK_k \not\subset H^i$. Suppose the quadrant $Q(K_k, fK_k)$ faces northwest, so that

$$Q(K_k, fK_k) = \{x_i < a - (m - k), \ x_j > b\}$$

for some $j \neq i$, $a, b \in \mathbb{Z}$. Then

1. $X_g^{\text{ess}}$ also avoids the larger quadrant

   $$Q = \{x_i < a + (m - k), \ x_j > b\}.$$ 

2. If $k < m$ then $fK_m \in H^i$ and $K_m \supset fK_k$.

**Corollary 8.7.** — Let $\sigma = \{K_0, \ldots, K_m\} \subset H^i$ be tightly nested in $X_g^{\text{ess}}$ and suppose there is an $f \in G$ such that $f\sigma \subset A^+_g$ and $f\sigma \not\subset H^i$. Let $x_i$ be horizontal and let $k$ be the largest index such that $fK_k \not\subset H^i$. Suppose there is a vertex $v$ in $X_g^{\text{ess}}$ such that $v \notin K_m$ and $v \in fK_k$. Then the quadrant $Q(K_k, fK_k)$ faces southeast.

## 9. Proof of the main theorem

Our goal in this section is to prove Theorem A from the Introduction, which we restate here:

**Theorem 9.1.** — Let $X$ be a CAT(0) cube complex with a RAAG-like action by $G$. Then $\text{scl}(g) \geq 1/24$ for every hyperbolic element $g \in G$.

We continue with the same notation as in the previous section. Fix a taut equivariant embedding $X_g^{\text{ess}} \hookrightarrow \mathbb{R}^d$. Let $C$ be the cube in $X_g^{\text{ess}}$ mapped to $[0, 1]^d$ under the equivariant embedding. Let $A$ be the set of half-spaces in $A^+_g$ dual to $C$, so that $[A, gA]$ is a fundamental domain for the action of $\langle g \rangle$ on $A^+_g$. We have $[A, gA] = [o, go]$, where $o \in \mathbb{R}^d$ is the origin. Identify $H(\mathbb{R}^d)$ with $A_g$. Recall that by property (3) of Proposition 5.4,
the extended taut segment \([A, gA] \cap \mathcal{H}^1\) is tightly nested in \(X_g^{\text{ess}}\). Write \([A, gA] \cap \mathcal{H}^1 = \{H_0^1, \ldots, H_n^1\}\).

Most of this section is devoted to finding a tightly nested subsegment \(\gamma \subseteq [A, gA] \cap \mathcal{H}^1\) such that \(\gamma > g\gamma\) and no copy of \(\gamma\) appears in \(A_g^+\). Once we find such a \(\gamma\), then Theorem 9.1 follows immediately; details are laid out in the proof at the end of this section. To arrange that \(\gamma > g\gamma\), we may have to pass to a proper subsegment of \([A, gA] \cap \mathcal{H}^1\). On the other hand, if \(\gamma\) is short, it is more likely for \(A_g^+\) to contain a copy of \(\gamma\). Our approach, therefore, is to use a maximal \(g\)-nested segment, defined below.

After discussing maximal \(g\)-nested segments, we proceed to show that for such a segment \(\gamma\), no copy of \(\gamma\) can lie in \(A_g^+\). First we prove Lemmas 9.4 and 9.5, which are technical statements used to show that quadrants face a particular way, under appropriate conditions. Next comes Proposition 9.6, which states that if \(h\gamma \subset A_g^+\), then \(h\gamma\) cannot lie entirely in \(\mathcal{H}^1\). Hence \(h\gamma\) contains half-spaces in \(A_g^+\) outside of \(\mathcal{H}^1\). Such a half-space generates a quadrant, by property 7.1(1). In Propositions 9.7 and 9.8 we prove that the first such quadrant faces northwest, and the last such quadrant faces southeast. In this way, the forbidden configuration of Lemma 8.2 is created, resulting in a contradiction.

Maximal \(g\)-nested segments

**Definition 9.2.** — A subsegment \(\gamma = \{H_1^1, \ldots, H_r^1\}\) of \([A, gA] \cap \mathcal{H}^1\) is said to be \(g\)-nested if \(\gamma > g\gamma\) in \(X_g^{\text{ess}}\). It is a maximal \(g\)-nested segment if it is \(g\)-nested and is not properly contained in another \(g\)-nested subsegment of \([A, gA] \cap \mathcal{H}^1\).

Figure 5.1 shows an example where the full segment \(\gamma = [A, gA] \cap \mathcal{H}^1\) is not \(g\)-nested; this is the segment of blue half-spaces labeled \(a, c, e\). In this example, the subsegment consisting of the pair labeled \(a, c\) is a maximal \(g\)-nested segment, as is the pair labeled \(c, e\).

Note that for every \(H \in A_g^+\) we have \(H \supset gH\) in \(X_g^{\text{ess}}\) by Remark 3.2 and Property 7.1(1). Thus every subsegment of \([A, gA] \cap \mathcal{H}^1\) of length 1 is \(g\)-nested. It follows that every \(H \in [A, gA] \cap \mathcal{H}^1\) is contained in a maximal \(g\)-nested segment.

**Lemma 9.3.** — Let \(\gamma = \{H_1^1, \ldots, H_r^1\}\) be a maximal \(g\)-nested subsegment of \([A, gA] \cap \mathcal{H}^1\). Then the following two statements hold:

1. Either \(\ell = 0\) or \(H_{\ell-1}^1 \cap g^{-1}H_\ell^1\) in \(X_g^{\text{ess}}\).
2. Either \(r = n\) or \(gH_\ell^1 \cap H_{r+1}^1\) in \(X_g^{\text{ess}}\).
Proof. — Suppose $\ell > 0$. If $H^1_{\ell-1}$ and $g^{-1} H^1_r$ are not transverse in $X^\text{ess}_g$, then they are nested in $X^\text{ess}_g$ by Remark 3.1. Since $o \in g^{-1} H_r - H_{\ell-1}$, this means that $g^{-1} H^1_r \supset H^1_{\ell-1}$ in $X^\text{ess}_g$, which is equivalent to $H^1_r \supset g H^1_{\ell-1}$. Let $\gamma' = \{H_{\ell-1}, \ldots, H^1_r\}$. We have:

$$H^1_{\ell-1} \supset \cdots \supset H^1_r \supset g H^1_{\ell-1} \supset \cdots \supset g H^1_r.$$  

So $\gamma'$ is $g$-nested and $\gamma'$ properly contains $\gamma$, violating maximality of $\gamma$. Similarly, if $r < n$ and $g H^1_r$ and $H^1_{r+1}$ are not transverse, then the segment \{ $H^1_\ell, \ldots, H^1_{r+1}$ \} is $g$-nested and contains $\gamma$.

We now proceed with the main steps of the proof of Theorem 9.1. The primary goal is to show that a maximal $g$-nested segment in $[A, gA] \cap \mathcal{H}$ never appears in $A^+_g$ in the reverse direction. The next two lemmas are technical steps that are needed along the way.

Lemma 9.4. — Let $\gamma = \{H^1_\ell, \ldots, H^1_1\}$ be a maximal $g$-nested subsegment of $[A, gA] \cap \mathcal{H}$. Suppose $h \gamma \subset A^+_g$ and $h \gamma \not\subset \mathcal{H}$, for some $h \in G$. Suppose $\ell > 0$. Let $x_1$ be horizontal and let $j$ be the smallest integer between $\ell$ and $r$ such that $h H^1_j \not\subset \mathcal{H}$. Then either the quadrant $Q(H^1_\ell, h H^1_j)$ faces northwest, or there is a vertex $v$ in $X^\text{ess}_g$ such that $v \notin g^{-1} H^1_r$ and $v \in h H^1_\ell$.

Proof. — By Lemma 9.3, since $\ell > 0$, $H^1_{\ell-1} \cap g^{-1} H^1_r$ in $X^\text{ess}_g$. Therefore, there exists a square $S$ in $X^\text{ess}_g$ in which they cross. Let $v$ be the unique vertex of $S$ with $v_1 = \ell$ and $v \notin g^{-1} H^1_r$. We now show that $v \in h H^1_\ell$ under the assumption that $Q(H^1_\ell, h H^1_j)$ faces southeast.

Let $h H^1_j = H^1_b$ for some $i \neq 1$ and $b \in \mathbb{Z}$. By assumption, $X^\text{ess}_g$ avoids the quadrant

$$Q(H^1_\ell, h H^1_j) = \{x_1 > j, x_i < b + 1\}.$$  

Since $\ell > 0$ and $j \geq \ell$, the half-spaces $H^1_{\ell-1}$ and $H^1_j$ are tightly nested. Thus, by Remark 8.1, $X^\text{ess}_g$ must further avoid the extended quadrant

$$Q(H^1_{\ell-1}, h H^1_j) = \{x_1 > j - 1, x_i < b + 1\}.$$  

If $j = \ell$, then for $v$ to lie outside of $Q(H^1_{\ell-1}, h H^1_j)$, we must have $v_i \geq b + 1$, so $v \in H^1_{b+1} = h H^1_\ell$.

If $j > \ell$, then applying Lemma 8.4(2) using

$$\{K_0, \ldots, K_m\} = \{H^1_\ell, \ldots, H^1_r\}, \quad i = 1, \quad k = j, \quad f = h, \quad \sigma = \gamma, \quad a = 0$$  

we obtain that $h H^1_\ell \in \mathcal{H}$ and $h H^1_\ell \supset H^1_\ell$. In coordinates, this means that $h H^1_\ell = H^1_c$ for some $c < \ell = v_1$. Thus, $v \in H^1_c = h H^1_\ell$. □
The next lemma is completely analogous to the previous one, with a similar proof.

Lemma 9.5. — Let \( \gamma = \{H^1_1, \ldots, H^1_r\} \) be a maximal \( g \)-nested subsegment of \( [A, gA] \cap \mathcal{H}^1 \). Suppose \( h\gamma \subset A^+_g \) and \( h\gamma \not\subset \mathcal{H}^1 \), for some \( h \in G \). Suppose \( r < n \). Let \( x_1 \) be horizontal and let \( j \) be the largest integer between \( \ell \) and \( r \) such that \( hH^1_j \not\subset \mathcal{H}^1 \). Then either the quadrant \( Q(H^1_j, hH^1_j) \) faces southeast, or there is a vertex \( v \) in \( X_g^{\text{ess}} \) such that \( v \in gH^1_{\ell} \) and \( v \notin hH^1_r \).

The next three propositions will form the main body of the argument. The first one shows that if a reverse copy of a maximal \( g \)-nested segment appears in \( A^+_g \), then it cannot lie entirely within \( \mathcal{H}^1 \).

Proposition 9.6. — Let \( \gamma = \{H^1_1, \ldots, H^1_r\} \) be a maximal \( g \)-nested subsegment of \( [A, gA] \cap \mathcal{H}^1 \). Suppose \( h\gamma \subset A^+_g \) for some \( h \in G \), and that \( hH^1_r \in [A, gA] \). Then \( h\gamma \not\subset \mathcal{H}^1 \).

Proof. — If not then \( h\gamma \subset \mathcal{H}^1 \). Write \( h\gamma = \{H^1_a, \ldots, H^1_{a+|\gamma|-1}\} \), where \( a \geq 0 \) because \( hH^1_r \in [A, gA] \).

Since \( \gamma \) and \( h\gamma \) cannot overlap (by Lemma 8.3), there are two possibilities for the location of \( h\gamma \) along \( \mathcal{H}^1 \).

The first case is that \( a + |\gamma| < \ell \) (i.e. \( h\gamma \) is to the left of \( \gamma \)). In particular \( \ell > 0 \) and therefore \( H^1_\ell \cap g^{-1}H^1_r \) in \( X_g^{\text{ess}} \), by Lemma 9.3. Let \( g^{-1}H^1_r = H^i_b \) for some \( i \neq 1, b \in \mathbb{Z} \). Note that \( b < 0 \) because \( g^{-1}H^1_r \) contains the origin \( o \). The projection \( p_{11}(X_g^{\text{ess}}) \) contains the square \([\ell-1, \ell] \times [b, b+1]\), which is dual to both \( H^i_{\ell-1} \) and \( g^{-1}H^1_r \). Thus there is a vertex \( v \in X_g^{\text{ess}} \) such that \( v_1 = \ell \) and \( v_i = b \).

By property 7.1(1) the half-spaces \( g^{-1}H^1_r \) and \( hH^1_r = H^1_a \) are not transverse in \( X_g^{\text{ess}} \), and hence they generate a quadrant \( Q \) disjoint from \( X_g^{\text{ess}} \). However, the quadrant \( \{x_1 > a, x_i < b+1\} \) contains \( v \) and the quadrant \( \{x_1 < a+1, x_i > b\} \) contains \( o \). These are the two possibilities for \( Q \) and thus we have a contradiction (since \( v, o \in X_g^{\text{ess}} \)).

The second case is that \( r < a \) (i.e. \( h\gamma \) is to the right of \( \gamma \)). Note that \( a \leq n \) since \( hH^1_r \in [A, gA] \). Hence \( r < n \), and \( gH^1_{\ell} \cap H^1_{r+1} \) in \( X_g^{\text{ess}} \) by Lemma 9.3. Now redefine \( i \neq 1 \) and \( b \in \mathbb{Z} \) such that \( g\gamma \subset \mathcal{H}^i \) and \( gH^1_{\ell} = H^i_b \). Then \( p_{11}(X_g^{\text{ess}}) \) contains the square \([r+1, r+2] \times [b, b+1]\) dual to \( H^1_{r+1} \) and \( H^i_b \). Let \( v \in X_g^{\text{ess}} \) be a vertex such that \( v_1 = r+1 \) and \( v_i = b+1 \).

Let \( x_1 \) be horizontal. By property 7.1(1) the half-spaces \( gH^1_{\ell} \) and \( hH^1_{\ell} = H^1_{a+|\gamma|-1} \) are not transverse in \( X_g^{\text{ess}} \), and hence they generate a quadrant.
Q disjoint from $X^\text{ess}_g$. The northwest quadrant $\{x_1 < a + |\gamma|, x_i > b\}$ contains $v$, and therefore cannot be disjoint from $X^\text{ess}_g$. Thus $Q(gh^1_\ell, hH^1_\ell) = Q(hH^1_\ell, gh^1_\ell)$ faces southeast.

Again using property 7.1(1), the half-spaces $gH^1_\ell$ and $hH^1_\ell$ are not transverse in $X^\text{ess}_g$ and generate a quadrant $Q(gH^1_\ell, hH^1_\ell) = Q(hH^1_\ell, gH^1_\ell)$ disjoint from $X^\text{ess}_g$. If it faces southeast then it must be $\{x_1 > a, x_i < b + |\gamma|\}$. We have $go \notin gH^1_r$ because $o \notin H^1_r$, and $go \in hH^1_r$ because $hH^1_r \in [A, gA] = [o, go]$. Therefore $go$ is in this southeast quadrant. Since $go \in X^\text{ess}_g$, we conclude that $Q(hH^1_r, gH^1_r)$ faces northwest.

Now apply Lemma 8.2 using

$$\{K_0, \ldots, K_m\} = \{hH^1_r, \ldots, hH^1_\ell\}, \ i = 1, \ f = gh^{-1}, \ j = 1, \ j' = m$$

to obtain a contradiction via Lemma 8.3.

The next two propositions also deal with a reverse copy of a maximal $g$–nested segment in $A_g^+$. By the previous proposition, there must be a half-space in the segment which lies outside of $\mathcal{H}^1$. Such a half-space will generate a quadrant, by property 7.1(1). The two propositions say that the first such quadrant always faces northwest, and the last such quadrant always faces southeast.

**Proposition 9.7.** — Let $\gamma = \{H^1_\ell, \ldots, H^1_r\}$ be a maximal $g$–nested subsegment of $[A, gA] \cap \mathcal{H}^1$. Suppose $h\gamma \subset A^+_g$, $hH^1_r \in [A, gA]$, and $h\gamma \notin \mathcal{H}^1$ for some $h \in G$. Let $x_1$ be horizontal. Let $j$ be the smallest integer between $\ell$ and $r$ such that $hH^1_j \notin \mathcal{H}^1$. Then the quadrant $Q(H^1_j, hH^1_j)$ faces northwest.

**Proof.**

**Case 1: $\ell = 0$.** — In other words, $\gamma = \{H^1_0, \ldots, H^1_r\}$. Let $v$ be the vertex of $X^\text{ess}_g$ with coordinates $v_1 = 1$ and $v_k = 0$ for all $k > 1$. Note that $v \in H^1_0$ and $H^1_0$ is the only element in $[A, gA]$ with this property. Therefore, since $hH^1_r \in [A, gA]$, if $v \in hH^1_r$, then we must have $hH^1_r = H^1_0$. But this contradicts that $\gamma$ and $h\gamma$ cannot overlap by Lemma 8.3, so $v \notin hH^1_r$. Since $hH^1_r \supset hH^1_j$, $v \notin hH^1_j$. Now apply Corollary 8.5 using

$$\{K_0, \ldots, K_m\} = \{H^1_0, \ldots, H^1_r\}, \ i = 1, \ f = h, \ K_k = H^1_j,$$

to obtain that $Q(H^1_j, hH^1_j)$ must face northwest.

**Case 2: $\ell > 0$.** — We will assume $Q(H^1_j, hH^1_j)$ faces southeast and derive a contradiction. By Lemma 9.4, there exists a vertex $v$ in $X^\text{ess}_g$ such that
we obtain that
\[ h \subseteq g^{-1}H^1_r \text{ and } v \in hH^1_\ell. \]
Note for any \( j \) between \( \ell \) and \( r \), \( hH^1_\ell \subset hH^1_j \), so 
\[ v \in hH^1_j. \]

Let \( i \) be the coordinate with \( g^{-1} \gamma \subset \mathcal{H}^i \). If \( hH^1_j \in \mathcal{H}^i \), then \( g^{-1}H^1_r \)
and \( hH^1_j \) are parallel in \( \mathbb{R}^d \), and hence are nested in \( X^\text{ess}_g \). Since \( hH^1_r \in [A,gA] \), we have \( o \notin hH^1_j \). Then, since \( j < r \) we have \( hH^1_r \supset hH^1_j \), and therefore \( o \notin hH^1_j \). However, \( o \in g^{-1}H^1_r \) and therefore \( g^{-1}H^1_r \supset hH^1_j \). This
contradicts the existence of \( v \). Therefore, we may assume \( hH^1_j \notin \mathcal{H}^i \).

We now forget coordinate \( x_1 \) and designate \( x_i \) to be the horizontal coordinate. Since \( h\gamma \) is not entirely contained in \( \mathcal{H}^i \), there is a largest integer \( j' \) between \( \ell \) and \( r \) such that \( hH^1_{j'} \notin \mathcal{H}^i \). Since \( v \notin g^{-1}H^1_r \) and \( v \in hH^1_{j'} \), by Corollary 8.7 using
\[ \{K_0, \ldots, K_m\} = \{g^{-1}H^1_1, \ldots, g^{-1}H^1_r\}, \quad f = hg, \quad K_k = g^{-1}H^1_{j'} \]
we obtain that \( Q(g^{-1}H^1_1, hH^1_{j'}) \) faces southeast. That is, \( hH^1_{j'} \supset g^{-1}H^1_r \),
but this is impossible since \( o \in g^{-1}H^1_r \) and \( o \notin hH^1_{j'} \). This yields a contradiction under the assumption that \( Q(H^1_r, hH^1_j) \) faces southeast, as desired.

The next proposition is analogous to the previous one, but the situation is not entirely symmetric because of the assumption throughout that the largest half-space of \( h\gamma \) lies in \([A,gA]\). For this reason, the next proposition requires an independent proof.

**Proposition 9.8.** — Let \( \gamma = \{H^1_1, \ldots, H^1_r\} \) be a maximal \( g \)-nested subsegment of \([A,gA] \cap \mathcal{H}^1 \). Suppose \( h\gamma \subset A^+_g, hH^1_r \in [A,gA], \) and \( h\gamma \notin \mathcal{H}^1 \) for some \( h \in G \). Let \( x_1 \) be horizontal. Let \( j \) be the largest integer between \( \ell \) and \( r \) such that \( hH^1_j \notin \mathcal{H}^1 \). Then the quadrant \( Q(H^1_j, hH^1_j) \) faces southeast.

**Proof.** — In the following, let \( i \) and \( i' \) be the coordinates with \( g\gamma \subset \mathcal{H}^i \)
and \( hH^1_j \in \mathcal{H}^{i'} \). We will assume that \( Q(H^1_j, hH^1_j) \) faces northwest, that is, \( H^1_j \supset hH^1_j \), and derive a contradiction.

**Case 1: \( r = n \).** — In other words, \( \gamma = \{H^1_1, \ldots, H^1_n\} \).

We first consider the sub-case that \( j = n \). Recall that the extended segment
\[ [A,gA] \cap \mathcal{H}^1 = \{H^1_0, \ldots, H^1_n, H^1_{n+1}\} \]
is tightly nested; in particular, the pair \( \{H^1_n, H^1_{n+1}\} \) is tightly nested. Therefore, by Remark 8.1, \( H^1_{n+1} \) and \( hH^1_n \) must also generate a quadrant that faces northwest; in other words, \( H^1_{n+1} \supset hH^1_n \). Let \( go \) be the translate of
the origin by \( g \). Since \([A,gA] = [o,go]\) and \( H_{n+1}^1 \in gA\), we must have \( go \notin H_{n+1}^1 \). Thus, \( go \notin hH_n^1\), but this contradicts the assumption that \( hH_n^1 = hH_{n+1}^1 \in [A,gA]\).

Now suppose \( j < n \). By Lemma 8.6(2), using

\[
\{K_0, \ldots, K_m\} = \{H_1^1, \ldots, H_n^1\}, \quad i = 1, \quad f = h, \quad K_k = H_j^1,
\]

we obtain that \( hH_n^1 \in \mathcal{K}^1 \) and \( H_n^1 \supset hH_n^1 \). So we must have that \( hH_n^1 = H_b^1 \), for some \( b > n \). But this contradicts the assumption that \( hH_n^1 \in [A,gA] \cap \mathcal{K}^1 = \{H_0^1, \ldots, H_n^1\} \).

Case 2: \( r < n \). — In this case, we can apply Lemma 9.5 to the assumption that \( Q(H_j^1, hH_j^1) \) faces northwest, yielding a vertex \( v \) in \( X_g^{\text{ess}} \) with \( v \in gH^1_\ell \) and \( v \notin hH^1_r \).

If \( j = r \) and \( i = i' \), then \( gH^1_\ell \) and \( hH^1_r \) are parallel in \( \mathbb{R}^d \) and hence are nested in \( X_g^{\text{ess}} \). Since \( go \in hH^1_r \) and \( go \notin gH^1_\ell \), \( hH^1_r \supset gH^1_\ell \). But this contradicts the existence of \( v \).

In all other cases we claim \( hH^1_r \notin \mathcal{K}^i \). This is true when \( j = r \) and \( i \neq i' \), since \( hH^1_r = hH^1_j \in \mathcal{K}^i \). In the situation that \( j < r \), then by the choice of \( j \), the suffix \( \alpha = \{H_{j+1}^1, \ldots, H_r^1\} \) has \( h\alpha \subset \mathcal{K}^1 \). But since \( r < n \), \( gH^1_\ell \cap H^1_{r+1} \) by Lemma 9.3(2); in particular, since \( gH_\ell^1 \in \mathcal{K}^i \), we have \( i \neq 1 \). This shows that \( hH^1_r \notin \mathcal{K}^i \).

We now forget coordinate \( x_1 \) and designate \( x_i \) to be the horizontal coordinate. Let \( j' \) be the smallest integer between \( \ell \) and \( r \) such that \( hH^1_{j'} \notin \mathcal{K}^i \). Such \( j' \) exists since \( hH^1_r \notin \mathcal{K}^i \). Our goal now is to use \( go \) and \( v \) to determine which ways the quadrants \( Q(gH^1_{j'}, hH^1_{j'}) \) and \( Q(gH^1_r, hH^1_r) \) face.

Now set

\[
\{K_0, \ldots, K_m\} = \{gH_\ell^1, \ldots, gH^1_r\}, \quad f = hg^{-1}.
\]

Since \( go \notin gH^1_\ell \) and \( go \in hH^1_r \), by Corollary 8.7, where \( K_k = gH^1_\ell \), the quadrant \( Q(gH^1_\ell, hH^1_r) \) faces southeast. On the other hand, since \( v \in gH^1_\ell \) and \( v \notin hH^1_{j'} \), by Corollary 8.5, where \( K_k = gH^1_{j'} \), the quadrant \( Q(gH^1_{j'}, hH^1_r) \) faces northwest. Since \( j' \) is the smallest index between \( \ell \) and \( r \) for which \( hH^1_{j'} \notin \mathcal{K}^i \), and \( r \) is the largest index, the conclusion of Lemma 8.2 yields a non-trivial subsegment \( \alpha \subset g\gamma \) such that \( h\alpha \subset \mathcal{K}^i \) and \( \alpha \) and \( h\alpha \) overlap. But this is impossible by Lemma 8.3. This contradiction was obtained under the assumption that \( Q(H_j^1, hH_j^1) \) faces northwest, concluding the proof.

We now tie everything together for the proof of Theorem 9.1.
Proof of Theorem 9.1. — Given a hyperbolic element \( g \in G \), fix a taut \( \langle g \rangle \)-equivariant embedding \( X_g^{\text{ess}} \to \mathbb{R}^d \) using Proposition 5.4, as discussed in the beginning of Section 7. Let \( \gamma = \{H_1^1, \ldots, H_r^1\} \subseteq \langle A, gA \rangle \) be a maximal \( g \)-nested subsegment of \( \langle A, gA \rangle \cap \mathcal{H}^1 \).

Suppose \( h\gamma \in A^+_g \) for some \( h \in G \). Replacing \( h\gamma \) by a \( \langle g \rangle \)-translate if necessary, we can assume that \( hH_1^r \in \langle A, gA \rangle \). Declare \( x_1 \) to be the horizontal coordinate.

By Proposition 9.6, \( h\gamma \) cannot be entirely contained in \( \mathcal{H}^1 \). Let \( j \) be the smallest index such that \( hH_1^j \not\in \mathcal{H}^1 \). Then, by Proposition 9.7, the quadrant \( Q(H_1^j, hH_1^1) \) faces northwest. Let \( j' \) be the largest index such that \( hH_1^{j'} \not\in \mathcal{H}^1 \). By Proposition 9.8 the quadrant \( Q(H_1^{j'}, hH_1^1) \) faces southeast. Lemma 8.2 now provides a contradiction, via Lemma 8.3.

Therefore, no copy of \( \gamma \) appears in \( A^+_g \). Now consider the counting functions \( c_\gamma \) and \( c_\gamma \) from Section 7. We have \( c_\gamma(o, g^n o) = 0 \) for all \( n > 0 \). Since \( \gamma \) is \( g \)-nested we also have \( c_\gamma(o, g^n o) = n \) for \( n > 0 \). Choosing the basepoints \( x_{g^n} = o \) for all such \( n \) (noting that \( X_g \subseteq X_{g^n} \)), the resulting homogeneous quasimorphism \( \widehat{\phi}_\gamma \) has value 1 on \( g \). Since \( \widehat{\phi}_\gamma \) has defect at most 12, by Lemma 4.5, Bavard Duality (Lemma 2.3) tells us that \( \text{scl}(g) \geq 1/24 \). \( \square \)

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