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SINGULAR HECKE ALGEBRAS, MARKOV TRACES, AND HOMFLY-TYPE INVARIANTS

by Luis PARIS & Loïc RABENDA

ABSTRACT. — We define the singular Hecke algebra $\mathcal{H}(SB_n)$ as the quotient of the singular braid monoid algebra $\mathbb{C}(q)[SB_n]$ by the Hecke relations $\sigma_k^2 = (q - 1)\sigma_k + q$, $1 \leq k \leq n - 1$. We define the notion of Markov trace in this context, fixing the number $d$ of singular points, and we prove that a Markov trace determines an invariant on the links with $d$ singular points which satisfies some skein relation. Let $TR_d$ denote the set of Markov traces with $d$ singular points. This is a $\mathbb{C}(q, z)$-vector space. Our main result is that $TR_d$ is of dimension $d + 1$. This result is completed with an explicit construction of a basis of $TR_d$. Thanks to this result, we define a universal Markov trace and a universal HOMFLY-type invariant on singular links. This invariant is the unique invariant which satisfies some skein relation and some desingularization relation.

RéSUMÉ. — On définit l’algèbre de Hecke singulière $\mathcal{H}(SB_n)$ comme le quotient de l’algèbre de monoïde $\mathbb{C}(q)[SB_n]$ par les relations de Hecke $\sigma_k^2 = (q - 1)\sigma_k + q$, $1 \leq k \leq n - 1$. On définit la notion de trace de Markov dans ce cadre, en fixant le nombre $d$ de points singuliers, et on démontre qu’une trace de Markov détermine un invariant sur les entrelacs à $d$ points singuliers qui vérifie une relation d’écheveau. Soit $TR_d$ l’ensemble des traces de Markov à $d$ points singuliers fixés. C’est un espace vectoriel sur $\mathbb{C}(q, z)$. Notre résultat principal est que $TR_d$ est de dimension $d + 1$. Ce résultat est complété par une construction explicite d’une base de $TR_d$. Grâce à ces résultats, nous définissons une trace de Markov universelle et un invariant universel de type HOMFLY sur les entrelacs singuliers. Cet invariant est l’unique invariant qui vérifie une certaine relation d’écheveau et une certaine relation de désingularisation.

1. Introduction

The Hecke algebra $\mathcal{H}(B_n)$ of the symmetric group is a one parameter deformation of the symmetric group algebra studied in representation theory as well as in knot theory. Let $\mathbb{K} = \mathbb{C}(q)$ be the field of rational functions on

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a variable \( q \), and let \( B_n \) denote the braid group on \( n \) strands. Then \( \mathcal{H}(B_n) \) is the quotient of the group algebra \( \mathbb{K}[B_n] \) by the relations

\[
\sigma_k^2 = (q - 1)\sigma_k + q, \quad 1 \leq k \leq n - 1,
\]

where \( \sigma_1, \ldots, \sigma_{n-1} \) are the standard generators of \( B_n \).

Let \( z \) be a new variable. A Markov trace on the tower of algebras \( \{ \mathcal{H}(B_n) \}_{n=1}^{+\infty} \) is defined to be a collection of \( \mathbb{K} \)-linear maps

\[
\text{tr}_n: \mathcal{H}(B_n) \to \mathbb{K}(z), \quad n \geq 1,
\]

such that

- \( \text{tr}_n(\alpha\beta) = \text{tr}_n(\beta\alpha) \) for all \( \alpha, \beta \in B_n \) and all \( n \geq 1 \);
- \( \text{tr}_{n+1}(\beta) = \text{tr}_n(\beta) \) for all \( \beta \in B_n \subset B_{n+1} \) and all \( n \geq 1 \);
- \( \text{tr}_{n+1}(\beta\sigma_n) = z \cdot \text{tr}_n(\beta) \) for all \( \beta \in B_n \) and all \( n \geq 1 \).

Let \( \mathcal{L}_0 \) denote the set of (isotopy classes of) links in \( \mathbb{R}^3 \). According to Jones \cite{J}, a Markov trace \( T = \{ \text{tr}_n \}_{n=1}^{+\infty} \) on \( \{ \mathcal{H}(B_n) \}_{n=1}^{+\infty} \) determines a link invariant \( I_T: \mathcal{L}_0 \to \mathbb{K}(\sqrt{y}) \), where \( y = \frac{z - q_{1/2}}{q_z} \). On the other hand, by a result of Ocneanu (see \cite{J}, \cite{Oc}), there exists a unique Markov trace which takes the value 1 on the identity. In particular, the set of Markov traces form a one dimensional \( \mathbb{K}(z) \)-vector space spanned by the Ocneanu trace.

Let \( A \) be an abelian group, let \( I: \mathcal{L}_0 \to A \) be an invariant, and let \( t, x \in A \). We say that \( I \) satisfies the \((t, x)\) skein relation if

\[
t^{-1} \cdot I(L_+) - t \cdot I(L_-) = x \cdot I(L_0),
\]

for all links \( L_+, L_-, L_0 \in \mathcal{L}_0 \) that have the same link diagram except in a neighborhood of a crossing where they are as in Figure 1.1. It is well-known that there exists a unique invariant \( I: \mathcal{L}_0 \to \mathbb{C}[t^{-1}, x^{-1}] \) which satisfies the \((t, x)\) skein relation and which takes the value 1 on the trivial knot. This invariant is equal to \( I_T \) (up to a change of variables), where \( T \) is the Ocneanu trace, and it is called the HOMFLY polynomial (see \cite{Oc}, \cite{R}, \cite{J}, \cite{Z}).

![Figure 1.1. The links L+, L−, and L0.](image-url)
Our goal in this paper is to extend these constructions to the singular braids and links.

Let $SB_n$ denote the monoid of singular braids on $n$ strands. After some preliminaries on singular links and braids in Section 2, we develop the study of singular Hecke algebras, Markov traces, and related singular link invariants in Section 3. We define the singular Hecke algebra in a naïve way, as the quotient of the singular braid monoid algebra $K[SB_n]$ by the Hecke relations

$$\sigma_k^2 = (q - 1)\sigma_k + q, \quad 1 \leq k \leq n - 1.$$ 

For $d \geq 0$, let $S_dB_n$ denote the set of braids with $d$ singular points. The algebra $H(SB_n)$ has a natural graduation

$$H(SB_n) = \bigoplus_{d=0}^{+\infty} H(S_dB_n),$$

where $H(S_dB_n)$ is the linear subspace of $H(SB_n)$ spanned by $S_dB_n$. The algebra $H(SB_n)$ itself is of infinite dimension, but we show that each subspace $H(S_dB_n)$ of the graduation is of finite dimension over $K$ (see Proposition 3.1).

A Markov trace on the sequence $\{H(S_dB_n)\}_{n=1}^{+\infty}$ is defined in the same way as a Markov trace on $\{H(B_n)\}_{n=1}^{+\infty}$, Let $\mathcal{L}_d$ denote the set of (isotopy classes of) links with $d$ singular points. We prove that a Markov trace $T$ on $\{H(S_dB_n)\}_{n=1}^{+\infty}$ determines an invariant $I_T : \mathcal{L}_d \to \mathbb{K}(\sqrt{q})$ (see Proposition 3.3), and that this invariant satisfies the $(t, x)$ skein relation for $t = \sqrt{q}\sqrt{y}$ and $x = \sqrt{q} - \frac{1}{\sqrt{q}}$ (see Proposition 3.4). Conversely, any invariant $I : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ which satisfies the $(t, x)$ skein relation is of the form $I = I_T$, where $T$ is a Markov trace on $\{H(S_dB_n)\}_{n=1}^{+\infty}$ (with coefficients in $\mathbb{C}(\sqrt{q}, \sqrt{y})$).

Section 4 contains the main result of the paper. Let $\text{TR}_d$ denote the set of traces on $H(S_dB_n)$. This is a $\mathbb{K}(z)$-vector space. We prove that the dimension of $\text{TR}_d$ is $d + 1$, and construct an explicit basis of $\text{TR}_d$ (see Theorem 4.7).

Let $\mathcal{L}$ denote the set of all (isotopy classes of) singular links. Thanks to Section 4, we define in Section 5 a universal trace and a universal HOMFLY-type invariant $\hat{I} : \mathcal{L} \to \mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y]$, where $y, X, Y$ are variables. We prove that $\hat{I}$ distinguishes two singular links $L, L' \in \mathcal{L}_d$ (where $d$ is fixed) if and only if there exists an invariant $I : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ which satisfies the $(t, x)$ skein relation for $t = \sqrt{q}\sqrt{y}$ and $x = \sqrt{q} - \frac{1}{\sqrt{q}}$, and which distinguishes...
L and L’ (see Theorem 5.3). We also prove that \( \hat{I} \) is the unique invariant with values in \( \mathbb{C}[t^{\pm 1}, x^{\pm 1}, X, Y] \), which satisfies the \((t, x)\) skein relation and some desingularization relation, and which takes the value 1 on the trivial knot (see Proposition 5.4 and Theorem 5.5).

Our invariant \( \hat{I} \) is more or less equivalent to the invariant of Kauffman and Vogel defined in [9]. More precisely, the invariant of Kauffman and Vogel is a specialization of our invariant (see Lemma 5.6), but this specialization does not make much difference. Nevertheless, their approach is different from ours in the sense that they use singular Reidemeister moves to prove that their invariant is an invariant. They define some “generalized Hecke algebras” and define a Markov trace on this family of generalized Hecke algebras from which they can recover their invariant, but they definition of generalized Hecke algebra involves many relations besides the Hecke ones that are not natural in the context of an algebraic study.

Note that the notion of Markov traces to study singular braids and links is also present in [1], but the considered algebra in this paper is a one parameter deformation of \( \mathbb{C}[B_n] \), which is specially adapted to study Vassiliev invariants, but which has nothing to do with the Hecke relations.

2. Singular links and braids

Let \( n \geq 1 \), and let \( S_1, \ldots, S_n \) be \( n \) copies of the circle \( S^1 \). A singular link on \( n \) components is defined to be a smooth immersion \( L : S_1 \sqcup \cdots \sqcup S_n \to \mathbb{R}^3 \) whose image has finitely many singularities (called singular points) that are all ordinary double points. In this context, the admissible isotopies preserve the local structures. Moreover, the circle \( S^1 \) as well as the links are always assumed to be oriented.

Let \( \mathcal{P} = \{P_1, \ldots, P_n\} \) be a set of \( n \) punctures in \( \mathbb{R}^2 \) (except mention of the contrary, we will always assume \( P_k = (k, 0) \) for all \( 1 \leq k \leq n \)). A singular braid on \( n \) strands based at \( \mathcal{P} \) is defined to be a \( n \)-tuple \( \beta = (b_1, \ldots, b_n) \) of smooth paths, \( b_k : [0, 1] \to \mathbb{R}^2 \times [0, 1] \), such that:

- There exists a permutation \( \chi \in \text{Sym}_n \) such that \( b_k(0) = (P_k, 0) \) and \( b_k(1) = (P_{\chi(k)}, 1) \) for all \( 1 \leq k \leq n \).
- \( \beta_k(t) \) runs monotonically on the third coordinate for all \( 1 \leq k \leq n \).
- The image of \( \beta_1 \cup \cdots \cup \beta_n \) has finitely many singularities (called singular points) that are all ordinary double points.
The isotopy classes of singular braids form a monoid (and not a group) called the singular braid monoid on \(n\) strands and denoted by \(SB_n\). The monoid operation is the concatenation.

**Theorem 2.1** (Baez [1], Birman [2]). — The monoid \(SB_n\) has a monoid presentation with generators 
\[
\sigma_1, \ldots, \sigma_{n-1}, \sigma_1^{-1}, \ldots, \sigma_{n-1}, \tau_1, \ldots, \tau_{n-1},
\]
and relations
\[
\begin{align*}
\sigma_k \sigma_k^{-1} &= \sigma_k^{-1} \sigma_k = 1 & \text{for } 1 \leq k \leq n - 1, \\
\sigma_k \tau_k &= \tau_k \sigma_k & \text{for } 1 \leq k \leq n - 1, \\
\sigma_k \sigma_l \sigma_k &= \sigma_l \sigma_k \sigma_l & \text{if } |k - l| = 1, \\
\sigma_k \sigma_l \tau_k &= \tau_l \sigma_k \sigma_l & \text{if } |k - l| = 1, \\
\sigma_k \sigma_l &= \sigma_l \sigma_k & \text{if } |k - l| \geq 2, \\
\sigma_k \tau_l &= \tau_l \sigma_k & \text{if } |k - l| \geq 2, \\
\tau_k \tau_l &= \tau_l \tau_k & \text{if } |k - l| \geq 2.
\end{align*}
\]

The braid \(\sigma_k\) in the above presentation is the standard \(k\)-th generator of the braid group \(B_n\) (see Figure 2.1). The braid \(\tau_k\) is a singular braid with a single singular point which involves the \(k\)-th strand and the \((k + 1)\)-th strand (see Figure 2.1).

\[
\begin{align*}
\sigma_k &= \begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
k + 1 \\
k \\
k + 1 \\
\vdots \\
\vdots \\
\vdots
\end{array} & \tau_k &= \begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
k + 1 \\
k \\
k + 1 \\
\vdots \\
\vdots \\
\vdots
\end{array}
\end{align*}
\]

**Figure 2.1. Generators of \(SB_n\).**

From a singular braid \(\beta = (b_1, \ldots, b_n)\) one can construct a singular link, called the closure of \(\beta\) and denoted by \(\hat{\beta}\), connecting \((P_k, 0)\) with \((P_k, 1)\) for all \(1 \leq k \leq n\) as in Figure 2.2.

**Theorem 2.2** (Birman [2]). — Every singular link is a closed singular braid.

Now, consider the set \(\bigcup_{n=1}^{\infty} SB_n\) of all singular braids. We may often use the notation \((\beta, n)\) to denote a braid \(\beta \in SB_n\) in case we want to emphasize the number \(n\) of strands.
We say that two singular braids \((\alpha, n)\) and \((\beta, m)\) are connected by a Markov move if either
- \(n = m\), \(\alpha = \gamma_1\gamma_2\), and \(\beta = \gamma_2\gamma_1\), for some \(\gamma_1, \gamma_2 \in SB_n\); or
- \(n = m + 1\) and \(\alpha = \beta\sigma_m^{\pm1}\); or
- \(m = n + 1\) and \(\beta = \alpha\sigma_n^{\pm1}\).

**Theorem 2.3** (Gemein [5]). — Let \((\alpha, n)\) and \((\beta, m)\) be two singular braids. Then \(\hat{\alpha}\) and \(\hat{\beta}\) are isotopic if and only if \((\alpha, n)\) and \((\beta, m)\) are connected by a finite sequence of Markov moves.

### 3. Singular Hecke algebras, Markov traces, and singular link invariants

Recall that \(\mathbb{K} = \mathbb{C}(q)\) denotes the field of rational functions on a variable \(q\). We define the singular Hecke algebra \(\mathcal{H}(SB_n)\) to be the quotient of the monoid algebra \(\mathbb{K}[SB_n]\) by the relations

\[
\sigma_k^2 = (q - 1)\sigma_k + q, \quad 1 \leq k \leq n - 1.
\]

For \(d \geq 0\), we denote by \(S_dB_n\) the set of (isotopy classes of) singular braids on \(n\) strands with \(d\) singular points, and by \(\mathbb{K}[S_dB_n]\) the \(\mathbb{K}\)-linear subspace of \(\mathbb{K}[SB_n]\) spanned by \(S_dB_n\). Note that \(S_0B_n = B_n\) is the braid group, and \(\mathbb{K}[S_0B_n] = \mathbb{K}[B_n]\) is the group algebra of \(B_n\). We have the graduation

\[
\mathbb{K}[SB_n] = \bigoplus_{d=0}^{+\infty} \mathbb{K}[S_dB_n].
\]

The relations (3.1) that define the singular Hecke algebra involve only elements of degree zero, thus the graduation of \(\mathbb{K}[SB_n]\) induces a graduation.
of $H(SB_n)$:

$$H(SB_n) = \bigoplus_{d=0}^{+\infty} H(S_d B_n),$$

where $H(S_d B_n)$ is the $\mathbb{K}$-linear subspace of $H(SB_n)$ spanned by $S_d B_n$.

It is known that $H(B_n)$ has dimension $n!$, and has a basis $B_n$ which can be described as follows. For $n \geq 2$ we set

$$U_n = \{1, \sigma_{n-1}, \sigma_{n-1} \sigma_{n-2}, \ldots, \sigma_{n-1} \sigma_{n-2} \cdots \sigma_2 \sigma_1\}.$$ 

Then $B_n$ is defined by induction on $n$ by

$$B_1 = \{1\}, \quad B_n = \{\beta u ; \beta \in B_{n-1} \text{ and } u \in U_n\} \quad \text{if } n \geq 2.$$ 

The singular Hecke algebra $H(SB_n)$ is not of finite dimension, but each subspace $H(S_d B_n)$ of the graduation is of finite dimension. Indeed:

**Proposition 3.1.** — Let $d \geq 0$, and let $n \geq 2$. Let $C_{d,n}$ denote the set of singular braids of the form $\tau_{i_1} \cdots \tau_{i_d} \beta$, where $1 \leq i_j \leq n - 1$ for $1 \leq j \leq d$, and $\beta \in B_n$. Then $C_{d,n}$ spans $H(S_d B_n)$.

**Proof.** — Observe that the Hecke relation (3.1) implies that

$$\sigma_k^{-1} = q^{-1} \sigma_k - q^{-1}(q - 1), \quad \text{for all } 1 \leq k \leq n - 1.$$ 

Let $i, j \in \{1, \ldots, n - 1\}$ such that $|i - j| = 1$, and let $a \geq 1$. We calculate $\sigma_i^2 \tau_j^a$ in two ways. Firstly,

$$\sigma_i^2 \tau_j^a = \sigma_i \sigma_j^a \sigma_i = \sigma_i \sigma_j \sigma_i - q^{-1} \sigma_i^1 \sigma_j \sigma_i = q^{-1} \sigma_i \sigma_j \sigma_i - q^{-1} \sigma_j^2 \sigma_i = q^{-1} \sigma_i \sigma_j \sigma_i + (q - 1) \sigma_j^2 \sigma_i$$

These two equalities imply

$$(3.2) \quad \sigma_i \tau_j^a = q^{-1} \tau_j^a \sigma_i - q^{-1} \tau_i^a \sigma_j + \tau_j^a \sigma_i.$$

On the other hand, by Theorem 2.1, if $i, j \in \{1, \ldots, n - 1\}$ are such that $|i - j| \neq 1$, then

$$(3.3) \quad \sigma_i \tau_j^a = \tau_j^a \sigma_i.$$

Equalities (3.2) and (3.3) show that every element of $H(S_d B_n)$ is a linear combination of elements of the form $\tau_{i_1} \cdots \tau_{i_d} \omega$, where $1 \leq i_j \leq n - 1$ for $1 \leq j \leq d$, and $\omega \in H(B_n)$. Now, since $B_n$ is a basis of $H(B_n)$, we conclude
that every element of $\mathcal{H}(S_dB_n)$ is a linear combination of elements of the form $\tau_{i_1} \cdots \tau_{i_d} \beta$, where $1 \leq i_j \leq n - 1$ for $1 \leq j \leq d$, and $\beta \in B_n$. □

However, $C_{d,n}$ is not a basis of $\mathcal{H}(S_dB_n)$ in general. Indeed:

**Lemma 3.2.** Let $i, j \in \{1, \ldots, n-1\}$ such that $|i - j| = 1$, and let $a \geq 1$.

Then

\[ (3.5) \quad \tau_i^a(\sigma_i \sigma_j + \sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)) = \tau_j^a(\sigma_i \sigma_j + \sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)). \]

**Proof.** Recall the equality (3.2) in the proof of Proposition 3.1:

\[ \sigma_i \tau_j^a = q^{-1} \tau_j^a \sigma_i \sigma_j \sigma_i - q^{-1} \tau_i^a \sigma_i \sigma_j \sigma_i + \tau_j^a \sigma_i. \]

We multiply this equality on the right hand side by $\sigma_i^{-1} \tau_j^{-1}$ and we get

\[ \sigma_i \tau_j^a \sigma_i^{-1} \tau_j^{-1} = q^{-1} \tau_j^a \sigma_i - q^{-1} \tau_i^a \sigma_i + \tau_j^a \sigma_i^{-1} \]

\[ \Leftrightarrow \quad \sigma_i \tau_j^a \sigma_i^{-1} \tau_j^{-1} = q^{-1} \tau_j^a \sigma_i - q^{-1} \tau_i^a \sigma_i + q^{-1} \tau_j^a \sigma_j - q^{-1}(q - 1) \tau_j^a \]

\[ \Leftrightarrow \quad q^{-1} \sigma_j \tau_i^a - q^{-1}(q - 1) \tau_i^a = q^{-1} \tau_j^a \sigma_i - q^{-1} \tau_i^a \sigma_i + q^{-1} \tau_j^a \sigma_j - q^{-1}(q - 1) \tau_j^a \]

thus

\[ (3.5) \quad \sigma_j \tau_i^a = \tau_j^a (\sigma_i + \sigma_j - (q - 1)) - \tau_i^a (\sigma_i - (q - 1)). \]

Now, we apply twice (3.5) to $\sigma_i \sigma_j \tau_i^a$ and obtain

\[ \sigma_i \sigma_j \tau_i^a = \sigma_i \tau_j^a (\sigma_i + \sigma_j - (q - 1)) - \sigma_i \tau_i^a (\sigma_i - (q - 1)) \]

\[ = \tau_i^a (\sigma_i + \sigma_j - (q - 1))^2 \tau_j^a (\sigma_j - (q - 1))(\sigma_i + \sigma_j - (q - 1)) - \tau_i^a \sigma_i (\sigma_i - (q - 1)) \]

\[ = \tau_i^a (\sigma_i \sigma_j + \sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)) \]

\[ - \tau_j^a (\sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)). \]

Since $\sigma_i \sigma_j \tau_i^a = \tau_j^a \sigma_i \sigma_j$, it follows that

\[ \tau_i^a (\sigma_i \sigma_j + \sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)) = \tau_j^a (\sigma_i \sigma_j + \sigma_j \sigma_i - (q - 1) \sigma_i - (q - 1) \sigma_j + (q^2 - q + 1)). \]

\[ \Box \]

**Remark.** We do not know the dimension of $\mathcal{H}(S_dB_n)$ if $d \geq 1$ and $n \geq 3$.

We turn now to the definition of a Markov trace, but, before, we make the following remark.

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Remark. — The basis $B_n$ of $\mathcal{H}(B_n)$ can be viewed as a subset of $B_{n+1}$. This implies that the natural embedding $B_n \hookrightarrow B_{n+1}$ leads to an injective homomorphism $\mathcal{H}(B_n) \hookrightarrow \mathcal{H}(B_{n+1})$. In the case of singular Hecke algebras, the natural embedding $SB_n \hookrightarrow SB_{n+1}$ also leads to a homomorphism $\iota_n : \mathcal{H}(SB_n) \rightarrow \mathcal{H}(SB_{n+1})$, but we do not know whether this homomorphism is injective.

Let $z$ be a new variable. Let $d \geq 0$. A Markov trace on the sequence $\{\mathcal{H}(S_dB_n)\}_{n=1}^{\infty}$ is defined to be a collection of $\mathbb{K}$-linear maps

$$\text{tr}_n^d : \mathcal{H}(S_dB_n) \rightarrow \mathbb{K}(z), \quad n \geq 1,$$

such that

- $\text{tr}_n^d(\alpha\beta) = \text{tr}_n^d(\beta\alpha)$ for all singular braids $\alpha \in S_kB_n$ and $\beta \in S_lB_n$ such that $k + l = d$, and all $n \geq 1$;
- $\text{tr}_{n+1}^d \circ \iota_n = \text{tr}_n^d$ for all $n \geq 1$;
- $\text{tr}_{n+1}^d(\iota_n(\beta)\sigma_n) = z \cdot \text{tr}_n^d(\beta)$ for all $\beta \in S_lB_n$ and all $n \geq 1$.

Define a Markov trace on the sequence $\{\mathcal{H}(SB_n)\}_{n=1}^{\infty}$ to be a collection of $\mathbb{K}$-linear maps

$$\text{tr}_n : \mathcal{H}(SB_n) \rightarrow \mathbb{K}(z), \quad n \geq 1,$$

such that

- $\text{tr}_n(\alpha\beta) = \text{tr}_n(\beta\alpha)$ for all singular braids $\alpha, \beta \in SB_n$, and all $n \geq 1$;
- $\text{tr}_{n+1} \circ \iota_n = \text{tr}_n$ for all $n \geq 1$;
- $\text{tr}_{n+1}(\iota_n(\beta)\sigma_n) = z \cdot \text{tr}_n(\beta)$ for all $\beta \in SB_n$ and all $n \geq 1$.

Note that, if $T = \{\text{tr}_n\}_{n=1}^{\infty}$ is a Markov trace on $\{\mathcal{H}(SB_n)\}_{n=1}^{\infty}$, then, for all $d \geq 0$, the collection $T^d = \{\text{tr}_n^d = \text{tr}_n|_{\mathcal{H}(S_dB_n)}\}_{n=1}^{\infty}$ of restrictions is a Markov trace on $\{\mathcal{H}(S_dB_n)\}_{n=1}^{\infty}$. Conversely, a collection $\{T^d\}_{d=0}^{\infty}$, where $T^d$ is a Markov trace on $\{\mathcal{H}(S_dB_n)\}_{n=1}^{\infty}$ for all $d \geq 0$, determines a unique Markov trace on $\{\mathcal{H}(SB_n)\}_{n=1}^{\infty}$. So, both definitions of Markov traces are more or less equivalent. Now, since the number $d$ of singular points can be fixed in our study, we will mainly consider Markov traces with a fixed number of singular points in the remainder.

Remark. — We do not impose the condition $\text{tr}_1(1) = 1$ in the above definitions because this condition has no real meaning in the context of singular braids. Moreover, without this condition, the Markov traces on $\{\mathcal{H}(SB_n)\}_{n=1}^{\infty}$ (or on $\{\mathcal{H}(S_dB_n)\}_{n=1}^{\infty}$) form a $\mathbb{K}(z)$-vector space. This will be of importance in the remainder.

Let $L_d$ denote the set of (isotopy classes of) singular links with $d$ singular points. We fix a Markov trace $T = \{\text{tr}_n^d\}_{n=1}^{\infty}$ on $\{\mathcal{H}(S_dB_n)\}_{n=1}^{\infty}$, and turn
to define an invariant $I_T : \mathcal{L}_d \to \mathbb{K}((\sqrt{y}))$. We follow the same strategy as Jones in [7].

Let $\pi : SB_n \to \mathcal{H}(SB_n)$ denote the natural map, and let $\varepsilon : SB_n \to \mathbb{Z}$ be the homomorphism defined by

$$
\varepsilon(\sigma_i) = 1, \varepsilon(\sigma_i^{-1}) = -1, \varepsilon(\tau_i) = 0, \text{ for } 1 \leq i \leq n - 1.
$$

We consider the following change of variables:

$$
z = \frac{q - 1}{1 - qy} \quad \iff \quad y = \frac{z - q + 1}{qz}.
$$

For a braid $\beta \in S_dB_n$ we set

$$
I_T(\beta) = \left( \frac{q - 1}{1 - qy} \right)^{-n+1} \cdot (\sqrt{y})^{\varepsilon(\beta) - n+1} \cdot \text{tr}_n^d(\pi(\beta)).
$$

This is an element of $\mathbb{K}((\sqrt{y}))$.

**Proposition 3.3.** — Let $(\alpha, n)$ and $(\beta, m)$ be two singular braids with $d$ singular points. If $\hat{\alpha}$ is isotopic to $\hat{\beta}$, then $I_T(\alpha) = I_T(\beta)$.

**Proof.** — This is standard application of Theorem 2.3. 

For $L \in \mathcal{L}_d$, we choose a singular braid $(\beta, n)$ such that $\hat{\beta} = L$, and we set $I_T(L) = I_T(\beta)$. By Proposition 3.3, $I_T(L)$ is a well-defined invariant.

Let $A$ be an abelian group, let $I : \mathcal{L}_d \to A$ be an invariant, and let $t, x \in A$. We say that $I$ satisfies the $(t, x)$ skein relation if

$$
t^{-1} \cdot I(L_+) - t \cdot I(L_-) = x \cdot I(L_0),
$$

for all singular links $L_+, L_-, L_0 \in \mathcal{L}_d$ that have the same link diagram except in a neighborhood of a crossing where they are as in Figure 3.1.

![Figure 3.1. The singular links $L_+$, $L_-$, and $L_0$.](image_url)

Now, we set

$$
t = \sqrt{y} \cdot \sqrt{q}, \quad x = \sqrt{q} - \frac{1}{\sqrt{q}},
$$

and we define $\tilde{\text{tr}}_n^d : S_dB_n \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ by

$$
\tilde{\text{tr}}_n^d(\beta) = (\sqrt{q})^{-\varepsilon(\beta)} \cdot \text{tr}_n^d(\pi(\beta)).
$$
With these new notations $I_T(\beta)$ can be written

$$I_T(\beta) = \left(1 - \frac{t^2}{tx}\right)^{n-1} \cdot t^{e(\beta)} \cdot \tilde{t}_n^d(\beta).$$

**Proposition 3.4.** — The invariant $I_T : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ satisfies the $(t, x)$ skein relation.

**Proof.** — Let $L_+, L_-, L_0 \in \mathcal{L}_d$ be three singular links that have the same singular link diagram except in a neighborhood of a non-singular crossing where they are as in Figure 3.1. A careful reading of Birman’s proof of Theorem 2.3 shows that there exist a singular braid $(\beta, n)$ with $d$ singular points, and an index $1 \leq i \leq n - 1$, such that $L_+ = \beta \sigma_i$, $L_- = \beta \sigma_i^{-1}$, and $L_0 = \beta$. On the other hand, the Hecke relation (3.1) implies

$$\tilde{t}_n^d(\beta \sigma_i) = x \tilde{t}_n^d(\beta) + \tilde{t}_n^d(\beta \sigma_i^{-1}).$$

Hence,

$$t^{-1}I_T(L_+) - tI_T(L_-) = \left(1 - \frac{t^2}{tx}\right)^{n-1} t^{e(\beta)} (\tilde{t}_n^d(\beta \sigma_i) - \tilde{t}_n^d(\beta \sigma_i^{-1}))$$

$$= x \left(1 - \frac{t^2}{tx}\right)^{n-1} t^{e(\beta)} \tilde{t}_n^d(\beta)$$

$$= I_T(L_0).$$

□

Define a Markov trace on the sequence $\{\mathcal{H}(S_dB_n)\}_{n=1}^{+\infty}$ with coefficients in $\mathbb{K}$-linear maps

$$\text{tr}_n^d : \mathcal{H}(S_dB_n) \to \mathbb{C}(\sqrt{q}, \sqrt{y}), \quad n \geq 1,$$

such that

- $\text{tr}_n^d(\alpha \beta) = \text{tr}_n^d(\beta \alpha)$ for all singular braids $\alpha \in S_kB_n$ and $\beta \in S_lB_n$ such that $k + l = d$, and all $n \geq 1$;
- $\text{tr}_{n+1}^d \circ t_n = \text{tr}_n^d$ for all $n \geq 1$;
- $\text{tr}_{n+1}^d(t_n(\beta)\sigma_n) = z \cdot \text{tr}_n^d(\beta)$ for all $\beta \in S_dB_n$ and all $n \geq 1$.

Using the same trick as above, a Markov trace $T$ on the sequence $\{\mathcal{H}(S_dB_n)\}_{n=1}^{+\infty}$ with coefficients in $\mathbb{C}(\sqrt{q}, \sqrt{y})$ defines an invariant $I_T : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ which satisfies the $(t, x)$ skein relation for $t = \sqrt{y}\sqrt{q}$ and $x = \sqrt{q} - \frac{1}{\sqrt{q}}$. Now, the reverse of Proposition 3.4 is true in the following sense.

**Proposition 3.5.** — Let $I : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ be an invariant which satisfies the $(t, x)$ skein relation for $t = \sqrt{y}\sqrt{q}$ and $x = \sqrt{q} - \frac{1}{\sqrt{q}}$. Then there
exists a Markov trace $T$ on $\{\mathcal{H}(S_d B_n)\}_{n=1}^{+\infty}$ with coefficients in $\mathbb{C}(\sqrt{q}, \sqrt{y})$ such that $I = I_T$.

Proof. — Recall that $\pi : SB_n \to \mathcal{H}(SB_n)$ denotes the natural map, and that $\varepsilon : SB_n \to \mathbb{Z}$ is the homomorphism defined by $\varepsilon(\sigma_i) = 1$, $\varepsilon(\sigma_i^{-1}) = -1$, and $\varepsilon(\tau_i) = 0$, for $1 \leq i \leq n - 1$.

Let $\tilde{tr}_n^d : S_d B_n \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ be the map defined by

$$\tilde{tr}_n^d(\beta) = t^{-\varepsilon(\beta)} \cdot \left( \frac{1 - tx}{tx} \right)^{1-n} \cdot I(\hat{\beta}).$$

and let $tr_n^u : \mathbb{K}[S_d B_n] \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ be the $\mathbb{K}$-linear map defined by

$$tr_n^u(\beta) = (\sqrt{q})^{\varepsilon(\beta)} \cdot \tilde{tr}_n^d(\beta), \quad \text{for } \beta \in S_d B_n.$$

Thanks to the $(t, x)$ skein relation, it is easily checked that $tr_n^u : \mathbb{K}[S_d B_n] \to \mathbb{C}(\sqrt{q}, \sqrt{y})$ induces a $\mathbb{K}$-linear map $tr_n^d : \mathcal{H}(S_d B_n) \to \mathbb{C}(\sqrt{q}, \sqrt{y})$, and that $T = \{tr_n^d\}_{n=1}^{+\infty}$ is a Markov trace on $\{\mathcal{H}(S_d B_n)\}_{n=1}^{+\infty}$ with coefficients in $\mathbb{C}(\sqrt{q}, \sqrt{y})$. On the other hand, a direct calculation shows that $I = I_T$. □

4. The space of traces

For $d \geq 0$, we denote by $TR_d$ the set of all traces on $\{\mathcal{H}(S_d B_n)\}_{n=1}^{+\infty}$. This is a $\mathbb{K}(z)$-vector space. Note also that the space of all traces on $\{\mathcal{H}(S_B n)\}_{n=1}^{+\infty}$ is the completion of $TR = \oplus_{d=0}^{+\infty} TR_d$. We start our analysis recalling the following.

Theorem 4.1 (Ocneanu [7], [3]). — There exists a unique trace $T_0^0 = \{tr_n^0\}_{n=1}^{+\infty}$ on $\{\mathcal{H}(B_n)\}_{n=1}^{+\infty}$ such that $tr_1^0(1) = 1$.

Corollary 4.2. — $TR_0$ is a one-dimensional $\mathbb{K}(z)$-vector space spanned by $T_0^0$.

The above trace $T_0^0$ is called the Ocneanu trace. It will be a master piece in our study.

In this section we prove that $TR_d$ is of dimension $d + 1$ and construct an explicit basis $\{T_0^d, T_1^d, \ldots, T_d^d\}$ of $TR_d$.

We start with the definition of the Markov traces $T_k^d$, $0 \leq k \leq d$.

Let $g_0^d, g_1^d : \mathcal{H}(S_{d+1} B_n) \to \mathcal{H}(S_d B_n)$
be the $K$-linear maps defined as follows. Let $\beta \in S_{d+1}B_n$. Write $\beta$ in the form
\[
\beta = \alpha_0 \tau_{i_1} \alpha_1 \cdots \tau_{i_d} \alpha_d \tau_{d+1} \alpha_{d+1},
\]
where $1 \leq i_j \leq n - 1$ for $1 \leq j \leq d + 1$, and $\alpha_j \in B_n$ for $0 \leq j \leq d + 1$. Then
\[
g_0^d(\beta) = \sum_{j=1}^{d+1} \alpha_0 \tau_{i_1} \alpha_1 \cdots \tau_{i_{j-1}} \alpha_{j-1} \cdot \alpha_j \cdot \tau_{i_{j+1}} \alpha_{j+1} \cdots \tau_{i_d} \alpha_d \tau_{d+1} \alpha_{d+1},
\]
\[
g_1^d(\beta) = \sum_{j=1}^{d+1} \alpha_0 \tau_{i_1} \alpha_1 \cdots \tau_{i_{j-1}} \alpha_{j-1} \cdot \sigma_{i_j} \alpha_j \cdot \tau_{i_{j+1}} \alpha_{j+1} \cdots \tau_{i_d} \alpha_d \tau_{d+1} \alpha_{d+1}.
\]

It is easily seen from the presentation of $SB_n$ given in Theorem 2.1 that $g_0^d$ and $g_1^d$ are well-defined.

Let
\[
\Phi_0^d, \Phi_1^d : TR_d \to TR_{d+1}
\]
be the $K(z)$-linear maps defined as follows. Let $T = \{\text{tr}^d_n\}_{n=1}^{+\infty}$ be an element of $TR_d$. Then, for $\omega \in H(S_{d+1}B_n)$, we set
\[
\Phi_0^d(T)(\omega) = \text{tr}^d_n(g_0^d(w)), \quad \Phi_1^d(T)(\omega) = \text{tr}^d_n(g_1^d(w)).
\]
It is easily checked that $\Phi_0^d \circ \Phi_1^{d-1} = \Phi_1^d \circ \Phi_0^{d-1}$ for all $d \geq 1$.

Now, we define $T_k^d$ by induction on $d$. According to the previous notation, $T_0^0$ is the Ocneanu trace of Theorem 4.1. If $d \geq 1$, then
\[
T_k^d = \begin{cases} 
\Phi_0^{d-1}(T_{k-1}^{d-1}) & \text{if } k \leq d - 1, \\
\Phi_1^{d-1}(T_{d-1}^{d-1}) & \text{if } k = d.
\end{cases}
\]
Note that we also have $T_k^d = \Phi_1^{d-1}(T_{k-1}^{d-1})$ for all $1 \leq k \leq d - 1$.

**Theorem 4.3.** — Let $d \geq 0$. Then $\{T_0^d, T_1^d, \ldots, T_d^d\}$ is a linearly independent family of $TR_d$.

The following lemmas 4.4 to 4.6 are preliminaries to the proof of Theorem 4.3.

The submonoid of $B_n$ generated (as a monoid) by $\sigma_1, \ldots, \sigma_{n-1}$ is called the *positive braid monoid* and is denoted by $B_n^+$. By [4], it has a monoid presentation with generators $\sigma_1, \ldots, \sigma_{n-1}$ and relations
\[
\sigma_i \sigma_j \sigma_i = \sigma_j \sigma_i \sigma_j \quad \text{if } |i - j| = 1,
\]
\[
\sigma_i \sigma_j = \sigma_j \sigma_i \quad \text{if } |i - j| \geq 2.
\]

**Lemma 4.4.** — Let $n \geq 1$, and let $\beta \in B_n^+$. Then $T_0^0(\beta) \in \mathbb{Z}[q, z]$.
Proof. — Let $U_n$ denote the $\mathbb{Z}[q]$-submodule of $\mathcal{H}(B_n)$ spanned by $B_n^+$. We prove by induction on $n \geq 2$ that $U_n$ is actually spanned as a $\mathbb{Z}[q]$-module by $B_{n-1}^+ \cup \{\alpha \sigma_{n-1} \alpha'; \alpha, \alpha' \in B_{n-1}^+\}$.

Suppose $n = 2$. Then $U_2$ is spanned as a $\mathbb{Z}[q]$-module by $\{\sigma_1^a; a \geq 0\}$. Now, the Hecke relation (3.1) implies that

$$\sigma_1^a = (q-1)\sigma_1^{a-1} + q\sigma_1^{a-2}, \quad \text{for all } a \geq 2,$$

thus $U_2$ is spanned by $\{1, \sigma_1\}$.

Suppose $n \geq 3$. Let $V_n$ be the $\mathbb{Z}[q]$-submodule spanned by $B_{n-1}^+ \cup \{\alpha \sigma_{n-1} \alpha'; \alpha, \alpha' \in B_{n-1}^+\}$. Let $\beta \in B_n^+$. We write $\beta$ in the form

$$\beta = \beta_0 \sigma_{n-1} \beta_1 \cdots \sigma_{n-1} \beta_l,$$

where $\beta_0, \beta_1, \ldots, \beta_l \in B_{n-1}^+$, and prove that $\beta \in V_n$ by induction on $l$. The cases $l = 0$ and $l = 1$ are obvious. So, we can suppose that $l \geq 2$. By induction (on $n$), we can assume that either $\beta_1 \in B_{n-2}^+$, or $\beta_1 = \beta_1' \sigma_{n-2} \beta_1''$ for some $\beta_1', \beta_1'' \in B_{n-2}^+$. If $\beta_1 \in B_{n-2}^+$, then

$$\beta = \beta_0 \beta_1 \sigma_{n-1}^2 \beta_2 \sigma_{n-1} \beta_3 \cdots \sigma_{n-1} \beta_l = (q-1) \beta_0 \beta_1 \sigma_{n-1} \beta_2 \sigma_{n-1} \beta_3 \cdots \sigma_{n-1} \beta_l + q \beta_0 \beta_1 \beta_2 \sigma_{n-1} \beta_3 \cdots \sigma_{n-1} \beta_l,$$

thus, by induction (on $l$), we have $\beta \in V_n$. If $\beta_1 = \beta_1' \sigma_{n-2} \beta_1''$ for some $\beta_1', \beta_1'' \in B_{n-2}^+$, then

$$\beta = \beta_0 \beta_1' \sigma_{n-2} \beta_1'' \beta_2 \sigma_{n-1} \beta_3 \cdots \sigma_{n-1} \beta_l$$

$$= (\beta_0 \beta_1') \sigma_{n-1} (\sigma_{n-2} \beta_1'' \beta_2) \sigma_{n-1} \beta_3 \cdots \sigma_{n-1} \beta_l,$$

thus, by induction (on $l$), we have $\beta \in V_n$.

Now, we take $\beta \in B_n^+$ and turn to prove that $T_0^0(\beta) \in \mathbb{Z}[q, z]$. We argue by induction on $n$.

Suppose $n \geq 2$. By the above observation, we can assume that either $\beta \in B_{n-1}^+$, or $\beta = \alpha \sigma_{n-1} \alpha'$ for some $\alpha, \alpha' \in B_{n-1}^+$. If $\beta \in B_{n-1}^+$, then, by induction, $T_0^0(\beta) \in \mathbb{Z}[q, z]$. If $\beta = \alpha \sigma_{n-1} \alpha'$ for some $\alpha, \alpha' \in B_{n-1}^+$, then, by induction, $T_0^0(\beta) = z \cdot T_0^0(\alpha \alpha') \in \mathbb{Z}[q, z]$.

**Lemma 4.5.** — Let $1 \leq a \leq n-1$, and let $\alpha, \alpha' \in \langle \sigma_{a+1}, \ldots, \sigma_{n-1} \rangle^+$, where $\langle \sigma_{a+1}, \ldots, \sigma_{n-1} \rangle^+$ denotes the submonoid generated by $\sigma_{a+1}, \ldots, \sigma_{n-1}$. Then

$$T_0^0(\alpha \sigma_a \alpha')|_{z=0} = 0,$$

$$T_0^0(\alpha \sigma_a^2 \alpha')|_{z=0} = q \cdot T_0^0(\alpha \alpha')|_{z=0}.$$
Proof. — The first equality is a consequence of the following one

\[ T_0^0(\alpha \sigma_a \alpha') = z \cdot T_0^0(\alpha \alpha') \]

whose proof is left to the reader. The second equality follows from the first one and the Hecke relation (3.1).

The following lemma is a direct consequence of the previous one.

**Lemma 4.6.** Let \( 0 \leq a, b \leq n - 1 \), and let \( i_1, \ldots, i_a \in \{1, \ldots, n-1\} \) such that \( i_1 < i_2 < \cdots < i_a \). Let

\[ \gamma = \sigma_{i_a} \cdots \sigma_{i_2} \sigma_{i_1} \sigma_1 \sigma_2 \cdots \sigma_b. \]

Then

\[ T_0^0(\gamma)|_{z=0} = \begin{cases} q^a & \text{if } a = b, i_1 = 1, \ldots, i_a = a, \\ 0 & \text{otherwise}. \end{cases} \]

**Proof of Theorem 4.3.** For \( 0 \leq b \leq d \), we set

\[ \gamma_b^d = \tau_d \cdots \tau_1 \sigma_2 \cdots \sigma_b. \]

A direct calculation shows that

\[ T_a^d(\gamma_b^d) = (d - a)! a! \sum_{1 \leq i_1 < \cdots < i_a \leq n-1} T_0^0(\sigma_{i_a} \cdots \sigma_{i_2} \sigma_{i_1} \sigma_1 \sigma_2 \cdots \sigma_b). \]

By Lemma 4.4, we have \( T_a^d(\gamma_b^d) \in \mathbb{Z}[q, z] \), and, by Lemma 4.6,

\[ T_a^d(\gamma_b^d)|_{z=0} = \begin{cases} (d - a)! a! q^a & \text{if } a = b, \\ 0 & \text{otherwise}. \end{cases} \]

This implies that \( T_0^d, T_1^d, \ldots, T_d^d \) are linearly independent.

**Theorem 4.7.** Let \( d \geq 0 \). Then \( \text{TR}_d \) is a \( \mathbb{K}(z) \)-vector space of dimension \( d + 1 \). In particular, \( \{T_0^d, T_1^d, \ldots, T_d^d\} \) is a basis of \( \text{TR}_d \).

The main ingredient in the proof of Theorem 4.7 are the relations in \( \mathcal{H}(SB_n) \) that will be proved in the following lemmas 4.8 to 4.11. We will prove Theorem 4.7 after these lemmas.

**Lemma 4.8.** Let \( i, j \in \{1, \ldots, n-1\} \) such that \( |i - j| = 1 \), and let \( a \geq 1 \). Set

\[ B_{i,j} = \sigma_i + \sigma_j - (q - 1). \]
Then
\begin{align}
\sigma_i \tau_j^a &= q^{-1} \tau_j^a \sigma_i \sigma_j \sigma_i - q^{-1} \tau_i^a \sigma_i \sigma_j \sigma_i + \tau_j^a \sigma_i; \\
\sigma_j \tau_i^a &= \tau_j^a (\sigma_i + \sigma_j - (q-1)) - \tau_i^a (\sigma_i - (q-1)); \\
B_{ij} \tau_i^a &= \tau_j^a B_{ij}; \\
\tau_i^a (\sigma_i \sigma_j + \sigma_j \sigma_i - (q-1) \sigma_i - (q-1) \sigma_j + (q^2 - q + 1)) &= \tau_j^a (\sigma_i \sigma_j + \sigma_j \sigma_i - (q-1) \sigma_i - (q-1) \sigma_j + (q^2 - q + 1)).
\end{align}

**Proof.** — The equalities (4.1), (4.2), and (4.4) are proved in Section 3 (see (3.2), (3.5), (3.4)). Since \( \tau_i^a \) commutes with \( \sigma_i - (q-1) \), the equality (4.3) is a direct consequence of (4.2). \( \square \)

**Lemma 4.9.** — Let \( i, j \in \{1, \ldots, n-1\} \) such that \( |i - j| = 1 \). Then \( B_{ij} \) is invertible in \( \mathcal{H}(B_n) \).

**Proof.** — A direct calculation shows that
\[-q^{-1}(q+1)^2(q-1) - 2q\sigma_i - 2q\sigma_j - (q-1)\sigma_i\sigma_j - (q-1)\sigma_j\sigma_i + 2\sigma_i\sigma_j\sigma_i\]
is the inverse of \( B_{ij} \). \( \square \)

**Lemma 4.10.** — Let \( i, j \in \{1, \ldots, n-1\} \) such that \( |i - j| \geq 2 \), and let \( a \geq 1 \). Let
\[C_{ij} = 2\sigma_i\sigma_j - (q-1)\sigma_i - (q-1)\sigma_j + q^2 + 1.\]

Then
\begin{align}
\sigma_i \tau_j^a &= \tau_j^a \sigma_i; \\
(\sigma_i - \sigma_j)^2 &= (q+1)^2 - C_{ij}; \\
\tau_i^a C_{ij} &= \tau_j^a C_{ij}.
\end{align}

**Proof.** — The equality (4.5) is a straightforward consequence of Theorem 2.1, and (4.6) can be easily proved with a direct calculation. So, it remains to prove (4.7).

First, we study the case where \( i = 1 \) and \( j = 3 \). We apply twice (4.2) to \( \sigma_1 \sigma_3 \tau_2^a \) and obtain
\[
s_1 s_3 \tau_2^a = \sigma_1 \tau_3^a (\sigma_2 + \sigma_3 - (q-1)) - \sigma_1 \tau_2^a (\sigma_2 - (q-1))
\begin{align*}
&= \tau_3^a \sigma_1 (\sigma_2 + \sigma_3 - (q-1)) - \tau_1^a (\sigma_1 + \sigma_2 - (q-1)) (\sigma_2 - (q-1)) + \tau_2^a (\sigma_2 - (q-1))^2 \\
&= \tau_3^a (\sigma_1 \sigma_2 + \sigma_1 \sigma_3 - (q-1) \sigma_1) - \tau_1^a \left( \sigma_1 \sigma_2 - (q-1) \sigma_1 - (q-1) \sigma_2 + (q^2 - q + 1) \right) + \tau_2^a (\sigma_2 - (q-1))^2.
\end{align*}
\]
Similarly,
\[
\sigma_3 \sigma_1 \tau_2^a = \tau_1^a (\sigma_3 \sigma_2 + \sigma_1 \sigma_3 - (q - 1) \sigma_3) - \tau_3^a (\sigma_3 \sigma_2 - (q - 1) \sigma_2) - (q - 1) \sigma_3 + (q^2 - q + 1) + \tau_2^a (\sigma_2 - (q - 1))^2.
\]
Since \(\sigma_1 \sigma_3 \tau_2^a = \sigma_3 \sigma_1 \tau_2^a\), it follows that
\[
\tau_1^a \left( \sigma_1 \sigma_2 + \sigma_3 \sigma_2 + \sigma_1 \sigma_3 - (q - 1) \sigma_1 - (q - 1) \sigma_2 - (q - 1) \sigma_3 + (q^2 - q + 1) \right) = \tau_3^a \left( \sigma_1 \sigma_2 + \sigma_3 \sigma_2 + \sigma_1 \sigma_3 - (q - 1) \sigma_1 - (q - 1) \sigma_2 - (q - 1) \sigma_3 + (q^2 - q + 1) \right).
\]
(4.8)

Set
\[
\omega_0 = \sigma_1 \sigma_2 + \sigma_3 \sigma_2 + \sigma_1 \sigma_3 - (q - 1) \sigma_1 - (q - 1) \sigma_2 - (q - 1) \sigma_3 + (q^2 - q + 1).
\]
By (4.8), we have \(\tau_i^a \omega_0 = \tau_3^a \omega_0\). A direct calculation shows that
\[
C_{13} = q^{-2}(q \sigma_1 \omega_0 + q \omega_0 \sigma_3 + (q - 1) \sigma_1 \omega_0 \sigma_3 - \sigma_1 \omega_0 \sigma_3 \sigma_2)(\sigma_1 - (q - 1)).
\]
Since \(\tau_1\) and \(\tau_3\) commute with \(\sigma_1\), it follows that
\[
(4.9)\quad \tau_1^a C_{13} = \tau_3^a C_{13}.
\]
Now, suppose that \(1 \leq i < j \leq n - 2\). Set
\[
B_{j3} = B_{j-1} \cdots B_5 B_{43}, \quad B_{i1} = B_{i-1} \cdots B_3 B_{21}, \quad \delta_{i j} = B_{i1} B_{j3}.
\]
By Lemma 4.9, \(\delta_{i j}\) is invertible, and by (4.3), we have
\[
\delta_{i j} \sigma_1 \delta_{i j}^{-1} = \sigma_i, \quad \delta_{i j} \tau_1 \delta_{i j}^{-1} = \tau_i, \quad \delta_{i j} \sigma_3 \delta_{i j}^{-1} = \sigma_j, \quad \delta_{i j} \tau_3 \delta_{i j}^{-1} = \tau_j,
\]
thus, by (4.9),
\[
\tau_i^a C_{i j} = \delta_{i j} \tau_1^a C_{13} \delta_{i j}^{-1} = \delta_{i j} \tau_3^a C_{13} \delta_{i j}^{-1} = \tau_j^a C_{i j}.
\]
\[\square\]

**LEMMA 4.11.** — Let \(a, b \geq 1\). Then
\[
(4.10)\quad \tau_1^a \tau_3^b (\sigma_3 - \sigma_1) = (\tau_2^b \tau_1^a + \tau_2^a \tau_3^b) (\sigma_3 - \sigma_1) + \tau_2^{a+b} (B_{12} - B_{23}).
\]

**Proof.** — Applying twice (4.2) to \(\sigma_2 \tau_1^a \tau_3^b\) we obtain
\[
\sigma_2 \tau_1^a \tau_3^b = \tau_2^a (\sigma_1 + \sigma_2 - (q - 1)) \tau_3^b - \tau_1^a (\sigma_1 - (q - 1)) \tau_3^b
\]
\[
= \tau_2^a \tau_3^b (\sigma_1 - (q - 1)) + \tau_2^a \sigma_2 \tau_3^b - \tau_1^a \tau_3^b (\sigma_1 - (q - 1))
\]
\[
= \tau_2^a \tau_3^b (\sigma_1 - (q - 1)) + \tau_2^{a+b} (\sigma_2 + \sigma_3 - (q - 1))
\]
\[
- \tau_2^a \tau_3^b (\sigma_3 - (q - 1)) - \tau_1^a \tau_3^b (\sigma_1 - (q - 1))
\]
\[
= \tau_2^a \tau_3^b (\sigma_1 - \sigma_3) + \tau_2^{a+b} B_{23} - \tau_1^a \tau_3^b (\sigma_1 - (q - 1))
\]
Similarly,
\[
\sigma_2 \tau_3^b \tau_1^a = \tau_2^b \tau_1^a (\sigma_3 - \sigma_1) + \tau_2^{a+b} B_{12} - \tau_1^a \tau_3^b (\sigma_3 - (q - 1)) .
\]
Since \( \sigma_2 \tau_1^a \tau_3^b = \sigma_2 \tau_3^b \tau_1^a \), it follows that
\[
\tau_1^a \tau_3^b (\sigma_3 - \sigma_1) = (\tau_2^b \tau_1^a + \tau_2^b \tau_3^b) (\sigma_3 - \sigma_1) + \tau_2^{a+b} (B_{12} - B_{23}) .
\]
\( \square \)

Proof of Theorem 4.7. — We fix once for all the number \( d \geq 1 \) of singular points. We set
\[
\widetilde{\text{TR}}_d = \bigoplus_{n=2}^{+\infty} \left( \mathbb{K}(z) \otimes \mathcal{H}(S_d B_n) \right) .
\]
Then \( \text{TR}_d \) can and will be viewed as the quotient of \( \widetilde{\text{TR}}_d \) by the following relations:
- \((\alpha \beta, n) = (\beta \alpha, n)\) for all \( \alpha \in S_k B_n \) and \( \beta \in S_l B_n \) such that \( k + l = d \)
  and all \( n \geq 2 \);
- \((\beta, n + 1) = (\beta, n)\) for all \( \beta \in S_d B_n \) and all \( n \geq 2 \);
- \((\beta \sigma_n, n + 1) = z (\beta, n)\) for all \( \beta \in S_d B_n \) and all \( n \geq 2 \).

For \( \omega \in \mathbb{K}(z) \otimes \mathcal{H}(S_d B_n) \), we will denote by \([\omega]\) the element of \( \text{TR}_d \) represented by \( \omega \).

We already know that \( \dim \text{TR}_d \geq d + 1 \) (see Theorem 4.3). So, in order to prove Theorem 4.7, it suffices to show that \( \text{TR}_d \) is spanned by \( d + 1 \) elements.

Recall the basis \( \mathcal{B}_n \) of \( \mathcal{H}(B_n) \) described in Section 3. For \( n \geq 2 \) we set
\[
\mathcal{U}_n = \{1, \sigma_{n-1}, \sigma_{n-1} \sigma_{n-2}, \ldots, \sigma_{n-1} \cdots \sigma_2 \sigma_1\} .
\]
Then \( \mathcal{B}_n \) is defined by induction on \( n \) by
\[
\mathcal{B}_1 = \{1\}, \quad \mathcal{B}_n = \{\beta u; \beta \in \mathcal{B}_{n-1} \text{ and } u \in \mathcal{U}_n\} \text{ if } n \geq 2 .
\]
Let \( \mathcal{C}_n \) be the set of elements of \( \text{TR}_d \) of the form \([\tau_{i_1} \cdots \tau_{i_d} \beta]\), where \( 1 \leq i_j \leq n-1 \) for \( 1 \leq j \leq d \), and \( \beta \in \mathcal{B}_n \). Set \( \mathcal{C}_\infty = \bigcup_{n=2}^{+\infty} \mathcal{C}_n \). By Proposition 3.1, \( \mathcal{C}_\infty \) spans \( \text{TR}_d \).

Let \( \omega \in \mathcal{C}_n \). Let \( 1 \leq l \leq d \). If \( \omega \) can be written in the form \( \omega = [\tau_{i_1}^{a_1} \cdots \tau_{i_l}^{a_l} \beta] \), where \( 1 \leq i_j \leq n - 1 \) and \( a_j \geq 1 \) for \( 1 \leq j \leq l \), \( a_1 + \cdots + a_l = d \), and \( \beta \in \mathcal{B}_n \), then we say that \( \omega \) has a syllable length less or equal to \( l \), and we write \( \text{Syl}(\omega) \leq l \). We set
\[
\mathcal{D}_{l,n} = \{\omega \in \mathcal{C}_n; \text{Syl}(\omega) \leq l\}, \quad \mathcal{D}_{l,\infty} = \bigcup_{n=2}^{+\infty} \mathcal{D}_{l,n} .
\]
Note that \( \mathcal{D}_{d,\infty} = \mathcal{C}_\infty \) spans \( \text{TR}_d \).
For $\mathcal{X} \subset \text{TR}_d$, we denote by $\text{Span}(\mathcal{X})$ the $\mathbb{K}(z)$-linear subspace spanned by $\mathcal{X}$. The first step in the proof of Theorem 4.7 will consist on proving that $\text{Span}(\mathcal{D}_{l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty})$ for all $l \geq 3$ (see Claims 1 to 4). Since $\text{TR}_d = \text{Span}(\mathcal{D}_{d,\infty})$, it will follow that $\text{TR}_d = \text{Span}(\mathcal{D}_{2,\infty})$. The second step will consist on proving that there exists a subset $\mathcal{F}_3 \subset \mathcal{D}_{2,3}$ with $d+1$ elements such that $\text{Span}(\mathcal{F}_3) = \text{Span}(\mathcal{D}_{2,\infty}) = \text{TR}_d$ (see Claims 5 to 7).

Let $1 \leq l \leq d$, and let $1 \leq r \leq l$. Set $\varepsilon = 2$ if $r$ is even, and $\varepsilon = 1$ if $r$ is odd. Then we denote by $\mathcal{E}_{r,l,n}$ the set of elements of $\mathcal{D}_{l,n}$ of the form

$$\omega = [\tau_1^{a_1} \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_{i_\varepsilon}^{a_{i_\varepsilon}} \tau_{i_\varepsilon+1}^{a_{i_\varepsilon+1}} \cdots \tau_{i_l}^{a_i}]$$

where $1 \leq i_j \leq n-1$ for $r+1 \leq j \leq l$, and $\beta \in \mathcal{B}_n$. We set $\mathcal{E}_{r,l,\infty} = \bigcup_{n=2}^{\infty} \mathcal{E}_{r,l,n}$.

**Claim 1.** Let $2 \leq l \leq d$. Then

$$\text{Span}(\mathcal{D}_{l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{2,l,\infty}).$$

**Proof.** For $k \geq 2$, we denote by $\mathcal{E}_{k,l,n}^r(k)$ the set of elements $\omega \in \mathcal{D}_{l,n}$ of the form $\omega = [\tau_1^{a_1} \tau_2^{a_2} \cdots \tau_{i_k}^{a_{i_k}} \beta]$, where $1 \leq i_1 \leq k$, $1 \leq i_j \leq n-1$ for $2 \leq j \leq l$, and $\beta \in \mathcal{B}_n$. We set $\mathcal{E}_{k,l,\infty}^r(k) = \bigcup_{n=2}^{\infty} \mathcal{E}_{k,l,n}^r(k)$. Note that $\mathcal{E}_{2,l,\infty}^r(1) = \mathcal{E}_{1,l,\infty}$, and $\mathcal{D}_{l,n} = \mathcal{D}_{l-1,n} \cup \mathcal{E}_{1,l,n} (n-1)$ for all $n \geq 2$.

We prove that

$$\text{Span}(\mathcal{D}_{l-1,n} \cup \mathcal{E}_{1,l,n}^r(k)) = \text{Span}(\mathcal{D}_{l-1,n} \cup \mathcal{E}_{1,l,\infty})$$

for all $k \geq 2$. This implies that

$$\text{Span}(\mathcal{D}_{l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{1,l,\infty})$$

Let $\omega \in \mathcal{E}_{1,l,\infty}^r(k)$ be of the form $\omega = [\tau_1^{a_1} \tau_2^{a_2} \cdots \tau_{i_k}^{a_{i_k}} \beta]$. By (4.1), we have

$$\omega = [\tau_{i_k}^{a_1} \sigma_k \tau_{k-1}^{a_k} \sigma_k \tau_{k-1}^{a_1} \cdots \tau_i^{a_{i_k}} \beta] = [\tau_{i_k}^{a_1} \tau_2^{a_2} \cdots \tau_i^{a_i}] - q[\sigma_k \tau_{k-1}^{a_1} \cdots \tau_i^{a_i}]$$

It is easily checked by means of (4.2) and (4.5) that this element belongs to $\text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{1,l,\infty}(k-1))$.

Now, for $k \geq 2$, we denote by $\mathcal{E}_{2,l,n}^r(k)$ the set of elements $\omega \in \mathcal{D}_{l,n}$ of the form $\omega = [\tau_1^{a_1} \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_{i_k}^{a_{i_k}} \beta]$, where $2 \leq i_2 \leq k$, $1 \leq i_j \leq n-1$ for $3 \leq j \leq l$, and $\beta \in \mathcal{B}_n$. We set $\mathcal{E}_{2,l,\infty}^r(k) = \bigcup_{n=2}^{\infty} \mathcal{E}_{2,l,n}^r(k)$. Note that $\mathcal{E}_{2,l,\infty}^r(2) = \mathcal{E}_{2,l,\infty}$, and $\mathcal{E}_{2,l,n}(n-1) = \mathcal{E}_{1,l,n}$ for all $n \geq 2$.  

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Using the same arguments as in the proof of (4.12), one can easily show that

\[(4.14) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}'_{2,l,\infty}(k)) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}'_{2,l,\infty}(k-1))\]

for all \(k \geq 3\). (Here we also need to use the fact that \(\sigma_k\) commutes with \(\tau_1\).) It follows that

\[\text{Span}(\mathcal{D}_{l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{2,l,\infty}).\]

\[\square\]

**Claim 2.** Let \(l \geq 3\), and let \(2 \leq r \leq l-1\). Then

\[(4.15) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r,l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,l,\infty}).\]

**Proof.** Set \(\varepsilon = 2\) if \(r\) is even, and \(\varepsilon = 1\) if \(r\) is odd. For \(k \geq 3\), we denote by \(\mathcal{E}'_{r+1,l,n}(k)\) the set of elements \(\omega \in \mathcal{D}_{l,n}\) of the form \(\omega = [\tau_1^{a_1} \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_r^{a_r} \tau_{r+1}^{a_{r+1}} \tau_{r+2}^{a_{r+2}} \cdots \tau_{l-1}^{a_{l-1}} \beta]\), where \(1 \leq i_{r+1} \leq k\), \(1 \leq i_j \leq n-1\) for \(r+2 \leq j \leq l\), and \(\beta \in \mathcal{B}_n\). We set \(\mathcal{E}'_{r+1,l,\infty}(k) = \bigcup_{n=2}^{+\infty} \mathcal{E}'_{r+1,l,n}(k)\). Note that \(\mathcal{E}'_{r+1,l,n}(n-1) = \mathcal{E}_{r,l,n}\) for all \(n \geq 2\).

Using the same arguments as in the proof of (4.12), one can easily show that

\[(4.16) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}'_{r+1,l,\infty}(k)) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}'_{r+1,l,\infty}(k-1))\]

for all \(k \geq 4\). (Here we also need to use the fact that \(\sigma_k\) commutes with \(\tau_1\) and \(\tau_2\). This implies that

\[(4.17) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r,l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,l,\infty}(3)).\]

Let \(\omega \in \mathcal{E}'_{r+1,l,\infty}(3)\) be an element of the form

\[\omega = [\tau_1^{a_1} \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_r^{a_r} \tau_{r+1}^{a_{r+1}} \tau_{r+2}^{a_{r+2}} \cdots \tau_{l-1}^{a_{l-1}} \beta].\]

Now, in order to prove Claim 2, it suffices to show that such an element belongs to \(\text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,l,\infty})\).

Assume that \(r\) is odd. So,

\[\omega = [\tau_1^{a_1} \cdots \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_r^{a_r} \tau_{r+1}^{a_{r+1}} \tau_{r+2}^{a_{r+2}} \cdots \tau_{l-1}^{a_{l-1}} \beta].\]

Let

\[\omega_1 = [\tau_1^{a_1} \cdots \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_r^{a_r} \tau_{r+1}^{a_{r+1}} (\sigma_3 - \sigma_1) \tau_{r+2}^{a_{r+2}} \cdots \tau_{l-1}^{a_{l-1}} \beta],\]

\[\omega_2 = [\tau_1^{a_1} \cdots \tau_2^{a_2} \tau_3^{a_3} \cdots \tau_r^{a_r} \tau_{r+1}^{a_{r+1}} C_1 \tau_{r+2}^{a_{r+2}} \cdots \tau_{l-1}^{a_{l-1}} \beta].\]
By Lemma 4.11, we have
\[
\omega_1 = [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}(\sigma_3 - \sigma_1)\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta] \\
+ [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}\tau_1^{ar+2}\cdots \tau_{i_1}^{a_1} \beta] \\
+ [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1+ar+1}(B_{12} - B_{23})(\sigma_3 - \sigma_1)\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta] \\
\in \text{Span}(\mathcal{D}_{l-1,\infty}) \subset \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}).
\]
On the other hand, by Lemma 4.10,
\[
\omega_2 = [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}C_1\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta] \\
\in \text{Span}(\mathcal{D}_{l-1,\infty}) \subset \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}).
\]
Hence, by Lemma 4.10,
\[
\omega = (q + 1)^{2}(\omega_1 + \omega_2) \in \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}).
\]
Now, assume that \( r \) is even. So
\[
\omega = [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta].
\]
Let
\[
\omega_1 = [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}B_{12}B_{23}\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-2}], \\
\omega_2 = [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_1^{ar+2}\tau_3^{a_r+1}(\sigma_1 - \sigma_3)\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}].
\]
Obviously, \( \omega_1 \in \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}). \)
On the other hand, by Lemma 4.11,
\[
\omega_2 = [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}(\sigma_1 - \sigma_3)\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
+ [\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}\tau_1^{ar+2}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
+ [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1+ar+1}(B_{23} - B_{12})\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
\in \text{Span}(\mathcal{D}_{l-1,\infty}) \subset \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}).
\]
Hence, by Lemma 4.8,
\[
\omega = [B_{12}\tau_1^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
= [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_1^{ar+2}\tau_1^{ar+2}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
= [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_1^{ar+2}(\sigma_1 - (q - 1))\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
+ [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
= [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}(\sigma_1 - (q - 1))\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
+ [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}(\sigma_3 - (q - 1))\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
- [\tau_2^{a_1}\cdots \tau_2^{a_{r-1}}\tau_3^{a_r+1}(\sigma_3 - (q - 1))\tau_{ir+2}^{a_{r+2}}\cdots \tau_{i_1}^{a_1} \beta B_{12}^{-1}] \\
= \omega_1 + \omega_2 \in \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{r+1,\infty}).
\]
At this point, thanks to Claims 1 and 2, we have proved that

\[(4.18) \quad \text{Span}(\mathcal{D}_{l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,\infty}) , \]

for all \( l \geq 3 \).

**Claim 3.** — Let \( l \geq 3 \). Then

\[(4.19) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,\infty}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,3}) . \]

**Proof.** — It suffices to show that

\[\text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,n}) = \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,n-1}) \]

for all \( n \geq 4 \).

Set \( \varepsilon = 2 \) if \( l \) is even, and \( \varepsilon = 1 \) if \( l \) is odd. Let \( \omega \in \mathcal{E}_{l,l,n} \) be an element of the form

\[\omega = [\tau_1^{a_1} \tau_2^{a_2} \cdots \tau_l^{a_l} \beta] , \]

where \( \beta \in \mathcal{B}_n \). By construction, either \( \beta \in \mathcal{B}_{n-1} \), or \( \beta = \alpha_1 \sigma_{n-1} \alpha_2 \) for some \( \alpha_1, \alpha_2 \in \mathcal{B}_{n-1} \). If \( \beta \in \mathcal{B}_{n-1} \), then \( \omega \in \mathcal{E}_{l,l,n-1} \). If \( \beta = \alpha_1 \sigma_{n-1} \alpha_2 \) for some \( \alpha_1, \alpha_2 \in \mathcal{B}_{n-1} \), then

\[\omega = z[\tau_1^{a_1} \tau_2^{a_2} \cdots \tau_l^{a_l} \alpha_1 \alpha_2] \in \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,n-1}) . \]

\[\Box\]

**Claim 4.** — Let \( l \geq 3 \). Then

\[(4.20) \quad \text{Span}(\mathcal{D}_{l-1,\infty} \cup \mathcal{E}_{l,l,3}) = \text{Span}(\mathcal{D}_{l-1,\infty}) . \]

**Proof.** — Let

\[\delta_0 = (z^2 - (q - 1)z - q)^{-1}(z - (q - 1) + \sigma_1) . \]

A direct calculation shows that we have

\[\delta_0(z - \sigma_1) = (z - \sigma_1)\delta_0 = 1 \]

in \( \mathbb{K}(z) \otimes \mathcal{H}(B_2) \).

We set \( \varepsilon = 1 \) if \( l \) is odd, and \( \varepsilon = 2 \) if \( l \) is even. Let \( \omega \in \mathcal{E}_{l,l,3} \). We write

\[\omega = [\tau_1^{a_1} \tau_2^{a_2} \cdots \tau_l^{a_l} \beta] , \]

where \( \beta \in \mathcal{B}_3 \). Set

\[\omega_1 = [\tau_1^{a_1} \tau_3^{a_2} \tau_3^{a_3} B_1 \tau_2^{a_4} \cdots \tau_l^{a_l} \beta \delta_0] , \]

\[\omega_2 = [\tau_1^{a_1} + \tau_3^{a_2} \tau_3^{a_3} (\sigma_3 - \sigma_1) \tau_2^{a_4} \cdots \tau_l^{a_l} \beta \delta_0] , \]

\[\omega_3 = [\tau_1^{a_1} + \tau_2^{a_2} B_1 \tau_1^{a_3} \tau_2^{a_4} \cdots \tau_l^{a_l} \beta \delta_0] . \]
Obviously, $\omega_2, \omega_3 \in \text{Span}(D_{l-1,\infty})$. On the other hand, by Lemma 4.11,
\[
[(\sigma_3 - \sigma_1)^2 r_1 a_1^2 r_3 a_3^2 r_2 a_2^3 B_1 2_1 \tau_2 \cdots \tau_\epsilon^a \beta \delta_0] \\
= [(\sigma_3 - \sigma_1)^2 r_1 a_1^2 r_2 a_2^3 r_3 a_3^2 B_1 2_1 \tau_2 \cdots \tau_\epsilon^a \beta \delta_0] \\
+ [(\sigma_3 - \sigma_1)^2 r_1 a_1^2 r_3 a_3^2 r_2 a_2^3 B_1 2_1 \tau_2 \cdots \tau_\epsilon^a \beta \delta_0] \\
+ [(\sigma_3 - \sigma_1)(B_1 2_1 \tau_2 a_2^4 \cdots \tau_\epsilon^a \beta \delta_0] \\
\in \text{Span}(D_{l-1,\infty})\).
\]

Moreover, by Lemma 4.10,
\[
[C_1 3_1 r_1^a a_1^3 r_3 a_3^2 r_2 a_2^4 \cdots \tau_\epsilon^a \beta \delta_0] \\
= [C_1 3_1 r_1^a a_1^3 r_3 a_3^2 r_2 a_2^4 \cdots \tau_\epsilon^a \beta \delta_0] \\
\in \text{Span}(D_{l-1,\infty})\).
\]

Hence, by Lemma 4.10,
\[
\omega_1 = (q + 1)^{-2}[(\sigma_3 - \sigma_1)^2 r_1 a_1^2 r_3 a_3^2 r_2 a_2^3 B_1 2_1 \tau_2 \cdots \tau_\epsilon^a \beta \delta_0] \\
+ (q + 1)^{-2}[C_1 3_1 r_1^a a_1^3 r_3 a_3^2 r_2 a_2^4 \cdots \tau_\epsilon^a \beta \delta_0] \\
\in \text{Span}(D_{l-1,\infty})\).
\]

Finally, by (4.2),
\[
\omega = [(z - \sigma_1) r_1^a a_1^3 r_3 a_3^2 r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] \\
= [(\sigma_3 - \sigma_1) r_1^a a_1^3 r_3 a_3^2 r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] \\
= [r_1^a a_1^3 r_3 a_3^2 r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] - [r_1^a \sigma_1 r_2 a_2^3 r_1^a r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] \\
= [r_1^a r_3 a_3^2 r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] + [r_1^a a_1^3 r_2 a_2^3 a_3 a_3^2 (\sigma_3 - (q - 1)) r_2 a_2^3 r_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] \\
- [r_1^a a_1^3 r_2 a_2^3 a_3 a_3^2 \cdots \tau_\epsilon^a \beta \delta_0] \\
= \omega_1 + \omega_2 - \omega_3 \in \text{Span}(D_{l-1,\infty})\).
\]

At this point we have proved that
\[
\text{Span}(D_{l,\infty}) = \text{Span}(D_{l-1,\infty})
\]
for all $l \geq 3$. This implies that
\[
(4.21) \quad \text{TR}_d = \text{Span}(D_{d,\infty}) = \text{Span}(D_{2,\infty})\).
\]

Now, let
\[
\mathcal{F}_1 = \left\{ [r_1^1], [r_1^1 \sigma_1] \right\} \cup \left\{ [r_1^a b, r_1^a r_2 \sigma_1], [r_1^a b, r_1^a r_2 \sigma_2], [r_1^a b, r_1^a r_2 \sigma_1 \sigma_2], [r_1^a b, r_1^a r_2 \sigma_2 \sigma_1], [r_1^a r_2 \sigma_1 \sigma_2 \sigma_1]; a, b \geq 1 \text{ and } a + b = d \right\}.
\]

Claim 5. — TR$_d =$ Span($\mathcal{F}_1$).
Proof. — One can easily prove using the same arguments as in the proof of Claim 1 that

\[ \text{Span}(D_{2,\infty}) = \text{Span}(\mathcal{E}_{1,1,\infty} \cup \mathcal{E}_{2,2,\infty}). \]

On the other hand, using the same arguments as in the proof of Claim 3, it is easily seen that

\[ \text{Span}(\mathcal{E}_{1,1,\infty} \cup \mathcal{E}_{2,2,\infty}) = \text{Span}(F_1) \]

Now, let

\[ F_2 = \{[\tau_1^d], [\tau_1^d \sigma_1]\} \cup \{[\tau_1^a \tau_2^b], [\tau_1^a \tau_2^b \sigma_1] ; a, b \geq 1 \text{ and } a + b = d\}. \]

CLAIM 6. — TR_d = \text{Span}(F_2).

Proof. — Let \( a, b \geq 1 \) such that \( a + b = d \). Then

\[ [\tau_1^a \tau_2^b \sigma_1 \sigma_2 \sigma_1] = [\tau_1^a \sigma_1 \sigma_2 \sigma_1 \tau_1^b] = [\tau_1^{a+b} \sigma_1 \sigma_2 \sigma_1] = z[\tau_1^{a+b} \sigma_1^2] = z(q-1)[\tau_1^d \sigma_1] + zq[\tau_1^d] \in \text{Span}(F_2). \]

By (4.3) we have

\[ [\tau_1^a \tau_2^b B_{12}] = [\tau_1^a B_{12} \tau_2^b] = [\tau_1^{a+b} (\sigma_1 + \sigma_2 - (q-1))] = [\tau_1^d (\sigma_1 + z - (q-1))] \in \text{Span}(F_2). \]

On the other hand,

\[ [\tau_1^a \tau_2^b \sigma_2] = [\tau_1^a \tau_2^b B_{12}] - [\tau_1^a \tau_2^b \sigma_1] + (q-1)[\tau_1^a \tau_2^b], \]

thus \( [\tau_1^a \tau_2^b \sigma_2] \in \text{Span}(F_2) \). By (4.4) we have

\[ [\tau_1^a \tau_2^b (\sigma_1 \sigma_2 + \sigma_2 \sigma_1 - (q-1) \sigma_1 - (q-1) \sigma_2 + (q^2 - q + 1))] = [\tau_1^{a+b} (\sigma_1 \sigma_2 + \sigma_2 \sigma_1 - (q-1) \sigma_1 - (q-1) \sigma_2 + (q^2 - q + 1))] = [\tau_1^d (2z \sigma_1 - (q-1) \sigma_1 - (q-1) z + (q^2 - q + 1))] \in \text{Span}(F_2). \]

On the other hand,

\[ [\tau_1^a \tau_2^b \sigma_2 \sigma_1] = \bigg[\tau_1^a \tau_2^b \left(\sigma_1 \sigma_2 + \sigma_2 \sigma_1 - (q-1) \sigma_1 - (q-1) \sigma_2 + (q^2 - q + 1)\right)\bigg] - [\tau_1^a \tau_2^b \sigma_1 \sigma_2] + (q-1)[\tau_1^a \tau_2^b \sigma_1] + (q-1)[\tau_1^a \tau_2^b \sigma_2] - (q^2 - q + 1)[\tau_1^a \tau_2^b], \]

thus \( [\tau_1^a \tau_2^b \sigma_2 \sigma_1] \in \text{Span}(F_2) \).
Let

\[ F_3 = \{[\tau_1^d], [\tau_1^d \sigma_1]\} \cup \{[\tau_1^a \tau_2^b]; a \geq b \geq 1 \text{ and } a + b = d\} \]
\[ \cup \{[\tau_1^a \tau_2^b \sigma_1]; a > b \geq 1 \text{ and } a + b = d\}. \]

Note that \(|F_3| = d + 1\), thus the following finishes the proof of Theorem 4.7.

**Claim 7.** \(\text{TR}_d = \text{Span}(F_3)\).

**Proof.** Let \(a, b \geq 1\) such that \(a < b\) and \(a + b = d\).

\[ [\tau_1^a \tau_2^b] = [\tau_2^b \tau_1^a] = [B_1^d \tau_2^b \tau_1^a B_{12}^{-1}] = [\tau_1^d \tau_2^b] \in \text{Span}(F_3). \]

By Lemma 4.8,

\[ [\tau_1^b \tau_2^a B_{12}] = [\tau_1^b B_{12} \tau_1^a] = [\tau_1^d (\sigma_1 + \sigma_2 - (q-1))] \]
\[ = \tau_1^d (\sigma_1 + z - (q - 1)) \in \text{Span}(F_3). \]

Moreover,

\[ [\tau_1^b \tau_2^a \sigma_2] = [\tau_1^b \tau_2^a B_{12}] - [\tau_1^b \tau_2^a \sigma_1] + (q - 1)[\tau_1^b \tau_2^a], \]

thus \([\tau_1^b \tau_2^a \sigma_2] \in \text{Span}(F_3)\). It follows that

\[ [\tau_1^a \tau_2^a \sigma_1] = [\sigma_1 \tau_1^a \tau_2^a] = [\tau_1^a \sigma_1 \tau_2^a] = [\tau_1^a \tau_2^a \sigma_1] = [B_1^d \tau_2^a \tau_1^a \sigma_1 B_{12}^{-1}] \]
\[ = \tau_1^d (\sigma_1 + z - (q - 1)) \in \text{Span}(F_3). \]

Now, assume that \(d\) is even, and let \(a = b = \frac{d}{2}\). We have

\[ [\tau_1^a \tau_2^a \sigma_1] = [\sigma_1 \tau_1^a \tau_2^a] = [\tau_1^a \sigma_1 \tau_2^a] = [\tau_1^a \tau_2^a \sigma_1] = [B_1^d \tau_2^a \tau_1^a \sigma_1 B_{12}^{-1}] = [\tau_1^a \tau_2^a \sigma_2]. \]

Moreover,

\[ [\tau_1^a \tau_2^a B_{12}] = [\tau_1^a B_{12} \tau_1^a] = [\tau_1^d (\sigma_1 + \sigma_2 - (q-1))] \]
\[ = \tau_1^d (\sigma_1 + z - (q - 1)) \in \text{Span}(F_3). \]

Thus

\[ [\tau_1^a \tau_2^a \sigma_1] = \frac{1}{2} ([\tau_1^a \tau_2^a \sigma_1] + [\tau_1^a \tau_2^a \sigma_2]) \]
\[ = \frac{1}{2} [\tau_1^a \tau_2^a B_{12}] + \frac{1}{2} (q - 1)[\tau_1^a \tau_2^a] \in \text{Span}(F_3). \]
5. Universal Markov trace and universal HOMFLY-type invariant

Let $X, Y$ be two new variables. We define the universal Markov trace as the collection $\hat{T} = \{\hat{\text{tr}}_n\}_{n=1}^{\infty}$ of $\mathbb{K}$-linear maps

$$\hat{\text{tr}}_n : \mathcal{H}(SB_n) \rightarrow \mathbb{C}(\sqrt{q}, z)[X, Y], \quad n \geq 1,$$

defined as follows. Let $d \geq 0$, and let $\omega \in \mathcal{H}(S_d B_n)$. Then

$$\hat{\text{tr}}_n(\omega) = \sum_{k=0}^{d} \frac{\sqrt{q}^k}{(d-k)!k!} X^k Y^{d-k} \cdot T_d^k(\omega),$$

where $\{T_d^0, T_d^1, \ldots, T_d^d\}$ is the $\mathbb{K}(z)$-basis of $\text{TR}_d$ constructed in Section 4.

**Proposition 5.1.** —

1. We have $\hat{\text{tr}}_n(\alpha \beta) = \hat{\text{tr}}_n(\beta \alpha)$ for all $\alpha, \beta \in SB_n$, and all $n \geq 1$.

2. Let $\iota_n : \mathcal{H}(SB_n) \rightarrow \mathcal{H}(SB_{n+1})$ be the morphism induced by the inclusion $SB_n \hookrightarrow SB_{n+1}$. Then $\hat{\text{tr}}_{n+1} \circ \iota_n = \hat{\text{tr}}_n$ for all $n \geq 1$.

3. $\hat{\text{tr}}_{n+1}(\iota_n(\omega) \sigma_n) = z \cdot \hat{\text{tr}}_n(\omega)$ for all $\omega \in \mathcal{H}(SB_n)$, and all $n \geq 1$.

4. We have

$$\hat{\text{tr}}_n(\tau_i \omega) = X \sqrt{q} \cdot \hat{\text{tr}}_n(\sigma_i \omega) + Y \cdot \hat{\text{tr}}_n(\omega)$$

for all $\omega \in \mathcal{H}(SB_n)$, all $n \geq 2$, and all $1 \leq i \leq n - 1$.

**Proof.** — Parts (1), (2), and (3) follow from the definition of a Markov trace (see Section 3), and from the fact that $T_0^d, T_1^d, \ldots, T_d^d$ are Markov traces for all $d \geq 0$.

We turn now to prove (4). Let $\beta \in S_d B_n$. We write $\beta$ in the form

$$\beta = \alpha_0 \tau_{i_1} \alpha_1 \cdots \tau_{i_d} \alpha_d,$$

where $1 \leq i_j \leq n - 1$ for $1 \leq j \leq d$, and $\alpha_j \in B_n$ for $0 \leq j \leq d$. For $S \subset \{1, \ldots, d\}$ we set

$$\beta(S) = \alpha_0 u_1 \alpha_1 \cdots u_d \alpha_d,$$

where $u_j = \sigma_{i_j}$ if $j \in S$, and $u_j = 1$ if $j \notin S$. It is easily checked that, for $0 \leq k \leq d$, $T_k^d(\beta)$ is given by the formula

$$T_k^d(\beta) = k! (d-k)! \sum_{\substack{S \subset \{1, \ldots, d\} \atop |S| = k}} T_d^0(\beta(S)).$$

This implies that

$$\hat{\text{tr}}_n(\beta) = \sum_{S \subset \{1, \ldots, d\}} \sqrt{q}^{|S|} X^{|S|} Y^{d-|S|} \cdot T_d^0(\beta(S)).$$
Now, from (5.2), it follows that
\[
\hat{\text{tr}}_n(\tau_i \beta) = X \sqrt{q} \sum_{S \subseteq \{1, \ldots, d\}} \sqrt{q}^{\|S\|} X^{\|S\| Y^{d-\|S\|}} \cdot T_0^0(\sigma_i \beta(S)) \\
+ Y \sum_{S \subseteq \{1, \ldots, d\}} \sqrt{q}^{\|S\|} X^{\|S\| Y^{d-\|S\|}} \cdot T_0^0(\beta(S)) \\
= X \sqrt{q} \cdot \hat{\text{tr}}_n(\sigma_i \beta) + Y \cdot \hat{\text{tr}}_n(\beta).
\]
\[\square\]

Recall from Section 3 that \(\pi : SB_n \to \mathcal{H}(SB_n)\) denotes the natural map, and that \(\varepsilon : SB_n \to \mathbb{Z}\) is the homomorphism defined by
\[
\varepsilon(\sigma_i) = 1, \quad \varepsilon(\sigma_i^{-1}) = -1, \quad \varepsilon(\tau_i) = 0, \quad \text{for } 1 \leq i \leq n-1.
\]

We consider the following change of variables:
\[
z = \frac{q - 1}{1 - qy} \implies y = \frac{z - q + 1}{qz}.
\]
For \(\beta \in SB_n\), we set
\[
\hat{I}(\beta) = \left(\frac{q - 1}{1 - qy}\right)^{-n+1} \cdot (\sqrt{y})^{\varepsilon(\beta)-n+1} \cdot \hat{\text{tr}}_n(\pi(\beta)).
\]
This is an element of \(\mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y]\).

The following can be proved in the same way as Proposition 3.3.

**Proposition 5.2.** — Let \((\alpha, n)\) and \((\beta, m)\) be two singular braids. If \(\hat{\alpha}\) is isotopic to \(\hat{\beta}\), then \(\hat{I}(\alpha) = \hat{I}(\beta)\).

Let \(\mathcal{L}\) denote the set of (isotopy classes of) singular links. For \(L \in \mathcal{L}\), we choose a singular braid \((\beta, n)\) such that \(\hat{\beta} = L\), and we set \(\hat{I}(L) = \hat{I}(\beta)\).

By Proposition 5.2, the map \(\hat{I} : \mathcal{L} \to \mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y]\) is a well-defined invariant that we call the **universal HOMFLY-type invariant** of \(\mathcal{L}\).

For \(d \geq 0\), we denote by \(S_d\) the set of invariants \(I : \mathcal{L}_d \to \mathbb{C}(\sqrt{q}, \sqrt{y})\) which satisfies the skein relation for \(t = \sqrt{y}\sqrt{q}\) and \(x = \sqrt{q} - \frac{1}{\sqrt{q}}\). Now, the above terminology “universal HOMFLY-type invariant” is justified by the following.

**Theorem 5.3.** — Let \(d \geq 0\), and let \(L, L' \in \mathcal{L}_d\). We have \(\hat{I}(L) = \hat{I}(L')\) if and only if \(I(L) = I(L')\) for all \(I \in S_d\).

**Proof.** — Let \(\text{TR}'_d\) be the space of traces on \(\{\mathcal{H}(S_d B_n)\}_{n=1}^{+\infty}\) with coefficients in \(\mathbb{C}(\sqrt{q}, \sqrt{y})\). Clearly, \(\text{TR}'_d\) is a \(\mathbb{C}(\sqrt{q}, \sqrt{y})\)-vector space, and
\[
\text{TR}'_d = \mathbb{C}(\sqrt{q}, \sqrt{y}) \otimes \text{TR}_d.
\]
On the other hand, we have

\[(5.3) \hat{I}(\beta) = \sum_{k=0}^{d} \frac{\sqrt{q}^k}{(d-k)!k!} X^k Y^{d-k} \cdot I_{T_k^d}(\beta),\]

for all $\beta \in S_d B_n$.

Let $L, L' \in \mathcal{L}_d$ such that $\hat{I}(L) = \hat{I}(L')$. By (5.3), we have $I_{T_k^d}(L) = I_{T_k^d}(L')$ for all $0 \leq k \leq d$. Let $I \in \mathcal{S}_d$. By Proposition 3.5, there exists $T \in \mathcal{T}_d$ such that $I = I_T$. By Theorem 4.7, there exist $\lambda_0, \lambda_1, \ldots, \lambda_d \in \mathbb{C}(\sqrt{q}, \sqrt{y})$ such that

$$T = \lambda_0 T_0^d + \lambda_1 T_1^d + \cdots + \lambda_d T_d^d.$$ 

Then

$$I(L) = \sum_{k=0}^{d} \lambda_k I_{T_k^d}(L) = \sum_{k=0}^{d} \lambda_k I_{T_k^d}(L') = I(L').$$

Now, let $L, L' \in \mathcal{L}_d$ such that $I(L) = I(L')$ for all $I \in \mathcal{S}_d$. We have in particular $I_{T_k^d}(L) = I_{T_k^d}(L')$ for all $0 \leq k \leq d$, thus, by (5.3), $\hat{I}(L) = \hat{I}(L')$. \qed

Let $A$ be an abelian group, let $I : \mathcal{L} \to A$ be an invariant, and let $X, Y \in A$. We say that $I$ satisfies the $(X, Y)$ desingularization relation if

$$I(L_X) = X \cdot I(L_+) + Y \cdot I(L_0),$$

for all singular links $L_X, L_+, L_0 \in \mathcal{L}$ that have the same link diagram except in a neighborhood of a crossing where they are as in Figure 5.1.

![Figure 5.1. The singular links $L_X$, $L_+$, and $L_0$.](image)

We set

$$t = \sqrt{y}\sqrt{q}, \quad x = \sqrt{q} - \frac{1}{\sqrt{q}},$$

and we define $\tilde{tr}_n : SB_n \to \mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y]$ by

$$\tilde{tr}_n(\beta) = (\sqrt{y})^{-\varepsilon(\beta)} \cdot \tilde{tr}_n(\pi(\beta)).$$
With these new notations, \( \mathring{I}(\beta) \) can be written
\[
\mathring{I}(\beta) = \left( 1 - \frac{t^2}{tx} \right)^{n-1} \cdot t^{\varepsilon(\beta)} \cdot \mathring{\tau}_n(\beta).
\]

**Proposition 5.4.** — The invariant \( \mathring{I} \) satisfies the \((t, x)\) skein relation and the \((X, Y)\) desingularization relation.

**Proof.** — The fact that \( \mathring{I} \) satisfies the \((t, x)\) skein relation is proved in the same way as Proposition 3.4. So, we only need to show that \( \mathring{I} \) satisfies the \((X, Y)\) desingularization relation.

Let \( L_X, L_+, L_0 \in \mathcal{L} \) be three singular links that have the same link diagram except in a neighborhood of a crossing where they are as in Figure 5.1. A careful reading of Birman’s proof of Theorem 2.2 shows that there exist a singular braid \((\beta, n)\) and an index \(1 \leq i \leq n - 1\) such that \( L_X = \mathring{\tau}_i \beta, L_+ = \sigma_i \beta, \) and \( L_0 = \beta. \) On the other hand, Proposition 5.1(4) implies that
\[
\mathring{\tau}_n(\tau_i \beta) = X t \cdot \mathring{\tau}_n(\sigma_i \beta) + Y \cdot \mathring{\tau}_n(\beta).
\]

Hence
\[
X \cdot \mathring{I}(L_+) + Y \cdot \mathring{I}(L_0) = \left( 1 - \frac{t^2}{tx} \right)^{n-1} \cdot t^{\varepsilon(\tau_i \beta)} \cdot (X t \cdot \mathring{\tau}_n(\sigma_i \beta) + Y \cdot \mathring{\tau}_n(\beta))
= \left( 1 - \frac{t^2}{tx} \right)^{n-1} \cdot t^{\varepsilon(\tau_i \beta)} \cdot \mathring{\tau}_n(\tau_i \beta)
= \mathring{I}(L_X).
\]

Now, the following shows that our invariant \( \mathring{I} \) is a reasonable extension of the HOMFLY polynomial to the singular links.

**Theorem 5.5.** — There exists a unique invariant \( \mathring{I} : \mathcal{L} \to \mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y] \) which satisfies the \((t, x)\) skein relation and the \((X, Y)\) desingularization relation, and which takes the value 1 on the trivial knot. Moreover, \( \mathring{I}(L) \in \mathbb{C}[t^{\pm 1}, x^{\pm 1}, X, Y] \) for all \( L \in \mathcal{L}. \)

**Proof.** — The existence of the invariant is given by Proposition 5.4.

Suppose that \( \hat{I}^I : \mathcal{L} \to \mathbb{C}(\sqrt{q}, \sqrt{y})[X, Y] \) is an invariant which satisfies the \((t, x)\) skein relation and the \((X, Y)\) desingularization relation, and which takes the value 1 on the trivial knot. Let \( L \in \mathcal{L}_d \) be a singular link with \( d \) singular points. We prove by induction on \( d \geq 0 \) that \( \hat{I}(L) = \hat{I}(L) \), and that this element belongs to \( \mathbb{C}[t^{\pm 1}, x^{\pm 1}, X, Y]. \)

The case \( d = 0 \) is well-known (see [7], [3]). We assume \( d \geq 1 \). Let \( P \) be a singular point of \( L \). Set \( L_X = L \), and let \( L_+ \) and \( L_0 \) be the singular
links having the same link diagram as $L$ except in a neighborhood of $P$ where they are as in Figure 5.1. Then, by induction and by the $(X,Y)$ desingularization relation, we have

$$\hat{I}'(L) = X \cdot \hat{I}'(L_+) + Y \cdot \hat{I}'(L_0) = X \cdot \hat{I}(L_+) + Y \cdot \hat{I}(L_0) = \hat{I}(L).$$

Moreover, again by induction,

$$\hat{I}(L) = X \cdot \hat{I}(L_+) + Y \cdot \hat{I}(L_0) \in \mathbb{C}[t^\pm 1, x^\pm 1, X, Y].$$

□

In [9] Kauffman and Vogel proved that there exists an invariant $I_{KV} : \mathcal{L} \to \mathbb{C}(a, A, B)$ defined by the equalities

\begin{align}
a \cdot I_{KV}(L_+) &= A \cdot I_{KV}(L_0) + I_{KV}(L_X), \\
a^{-1} \cdot I_{KV}(L_-) &= B \cdot I_{KV}(L_0) + I_{KV}(L_X),
\end{align}

for all links $L_X, L_+, L_-, L_0 \in \mathcal{L}$ that have the same link diagram except in a neighborhood of a crossing where they are as in Figure 3.1 or as in Figure 5.1. It is easily checked that (5.4) is equivalent to

\begin{align}
a \cdot I_{KV}(L_+) - a^{-1} \cdot I_{KV}(L_-) &= (A - B) \cdot I_{KV}(L_0), \\
I_{KV}(L_X) &= a \cdot I_{KV}(L_+) - A \cdot I_{KV}(L_0),
\end{align}

thus $I_{KV}$ is defined by the $(a^{-1}, A - B)$ skein relation and the $(a, A^{-1})$ desingularization relation. In other words, we have:

**Lemma 5.6.** — The invariant $I_{KV}$ can be obtained from the universal HOMFLY-type invariant $\hat{I}$ by setting $t = a^{-1}$, $x = A - B$, $X = a$, and $Y = -A$.

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