# **ROGER G. MCCANN Another characterization of absolute stability**

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## ANOTHER CHARACTERIZATION OF ABSOLUTE STABILITY

### by Roger C. McCANN

It is well known that absolute stability of a compact subset M of a locally compact metric space can be characterized by the presence of a fundamental system of absolutely stable neighborhoods, and also by the existence of a continuous Liapunov function  $\nu$  defined on some neighborhood of  $M = \nu^{-1}(0)$ , [1]. In a more general setting it has been shown that a set M is closed and absolutely stable if and only if  $M = \cap \nu_i^{-1}(0)$  for suitable Liapunov functions  $\nu_i$ , [2]. This paper presents a more elementary description of absolute stability in terms of positively invariant neighborhoods only.

Throughout this paper R and R<sup>+</sup> will denote the reals and il non-negative reals respectively. A rational number r is called dyadic iff there are integers n and j such that  $n \ge 0, \ 1 \le j < 2^n$ , and  $r = j/2^n$ .

A dynamical system on a topological space X is a mapping  $\pi$  of X × R into X satisfying the following axioms (where  $x\pi t = \pi(x, t)$ ):

(1)  $x \pi 0 = x$  for  $x \in X$ .

(2)  $(x\pi t)\pi s = x\pi(t+s)$  for  $x \in X$  and  $t, s \in \mathbb{R}$ .

(3)  $\pi$  is continuous in the product topology.

If  $A \subseteq X$  and  $B \subseteq R$ , then  $A\pi B$  will denote the set  $\{x\pi t : x \in A, t \in B\}$  A subset A of X is called positively invariant if and only if  $A\pi R^+ = A$ .

A mapping  $\varphi: X \to \mathbb{R}^+$  is called a Liapunov function (relative to  $\pi$ ) if and only if  $\varphi$  is continuous and  $\varphi(x\pi t) \leq \varphi(x)$  for all  $x \in X$  and  $t \in \mathbb{R}^+$ .

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Absolute stability is defined in terms of a prolongation ([1], [2]) and, in [1], is characterized in a special setting by the following theorem.

**THEOREM** A. — Let M be a compact subset of a locally compact metric space. Then the following are equivalent:

(a) There is a Liapunov function  $\circ$  with  $\circ^{-1}(0) = M$ .

(b) M possesses a fundamental system of absolutely stable neighborhoods.

(c) M is absolutely stable.

In [2], absolutely stable sets, in a more general setting, are characterized by Liapunov functions.

THEOREM B. — Let M be a subset of a space X which is Hausdorff paracompact, and locally compact. Then M is closed and absolutely stable if and only if  $M = \bigcap \varphi_i^{-1}(0)$  for suitable Liapunov functions  $\varphi_i: X \to [0, 1]$ .

In order to obtain our result we will need the following result [2, Corollary 18].

**THEOREM** C. — In a locally compact metric space X, the closed absolutely stable sets are precisely the zero-sets of Liapunov functions mapping X into [0, 1].

THEOREM. — Let M be a closed subset of a locally compact metric space X. Then M is absolutely stable if and only if M possesses a family F of neighborhoods satisfying

(i) If  $U \in \mathcal{F}$ , then U is open and positively invariant.

(*ii*)  $\cap \mathcal{F} = \mathbf{M}$ .

(iii) If  $U \in \mathcal{F}$ , then there is a  $V \in \mathcal{F}$  such that  $\overline{V} \subset U$ .

(iv) If U,  $V \in \mathcal{F}$  are such that  $\overline{U} \subset V$ , then there is a  $W \in \mathcal{F}$  such that  $\overline{U} \subset W \subset \overline{W} \subset V$ .

**Proof.** — If. Let  $U \in \mathcal{F}$ . For each dyadic rational r we construct a set  $U(r) \subset U$  such that  $U(r) \in \mathcal{F}$  and  $\overline{U}(r) \subset U(s)$  if r < s. Then we construct a Liapunov function  $v_{U}: X \rightarrow [0, 1]$  and show that  $M = \bigcap \{v_{\overline{U}}^{-1}(0): U \in \mathcal{F}\}$ . The result will then follow from Theorem B. First obtain from  $\mathcal{F}$  a system

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of neighborhoods  $U\left(\frac{1}{2^n}\right)$ , *n* a non-negative integer, such that U(1) = U and  $U\left(\frac{1}{2^{n+1}}\right) \subset U\left(\frac{1}{2^n}\right)$ . This is clearly possible by (*iii*). Using (*iv*) this system of neighborhoods can be extended to one with the desired properties. For example, we choose  $U\left(\frac{3}{4}\right)$  to be any member W of  $\mathcal{F}$  such that  $\overline{U}\left(\frac{1}{2}\right) \subset W \subset \overline{W} \subset U(1)$ . Now define  $v_U: X \to R^+$  by  $v_U(x) = 1$ if  $x \notin U = U(1)$  and  $v_U(x) = \inf \{v: x \in U(r)\}$  if  $x \in U$ . If  $x \in U(r)$  and  $t \in R^+$ , then  $x\pi t \in U(r)$  since U(r) is positively invariant. Therefore

$$\nu_{\mathbf{U}}(x) = \inf \{r : x \in \mathbf{U}(r)\} \ge \inf \{r : x\pi t \in \mathbf{U}(r)\} = \nu_{\mathbf{U}}(x\pi t).$$

The continuity of  $\rho_{U}$  is proved as in the proof of Urysohn's lemma. Thus for each  $U \in \mathcal{F}$  we have constructed a continuous Liapunov function  $\rho_{U}$  such that  $M \subseteq \rho_{U}^{-1}(0) \subseteq U$ . By (*ii*),  $\cap \rho_{U}^{-1}(0) = M$ .

Only if. — Let M be absolutely stable. Then by theorem C,  $M = \nu_{\overline{U}}^{-1}(0)$  for some Liapunov function  $\nu$ . Let  $\mathcal{F}$  consist of all sets of the form  $\{x : \nu(x) < r\}$  where  $r \in (0, 1)$ ]. Evidently  $\mathcal{F}$  satisfies conditions (i)- $(i\nu)$ .

Remark. — In the « If » part of the proof we only need that X is Hausdorff, paracompact, and locally compact.

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